

Total Variation Reconstruction From Quasi-Random Samples

ABSTRACT

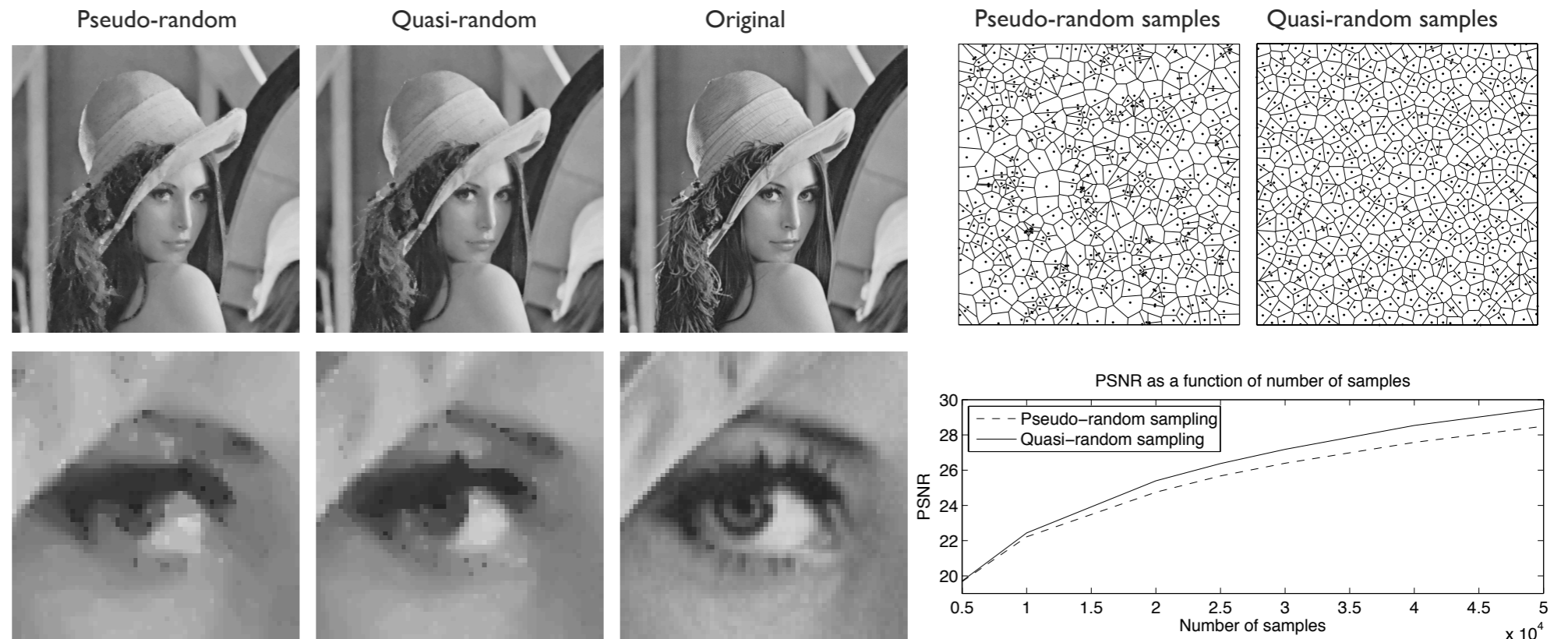
Pseudo-random numbers are often used for generating incoherent uniformly distributed sample distributions.

Observation: Randomness is a sufficient but not necessary condition to ensure incoherence.

Thesis: A globally optimized set of evenly distributed points could capture the visual content more efficiently to reconstruct (interpolate) images from few samples.

Method: We compare classical random sampling with a simple construction based on properties of the fractional Golden ratio sequence and the Hilbert space filling curve. Images are reconstructed using a TV prior.

Results: We observed improvements in terms of peak signal to noise ratio over pseudo-random sampling.



QUASI-RANDOM SAMPLING

Elements of the fractional golden ratio sequence $G_s(i)$ with given seed constant $s \in [0, 1)$ are

$$G_s(i) = \{s + i \cdot \phi\}, \forall i \geq 1, \quad \text{with } \phi = \frac{1 + \sqrt{5}}{2} \quad (1)$$

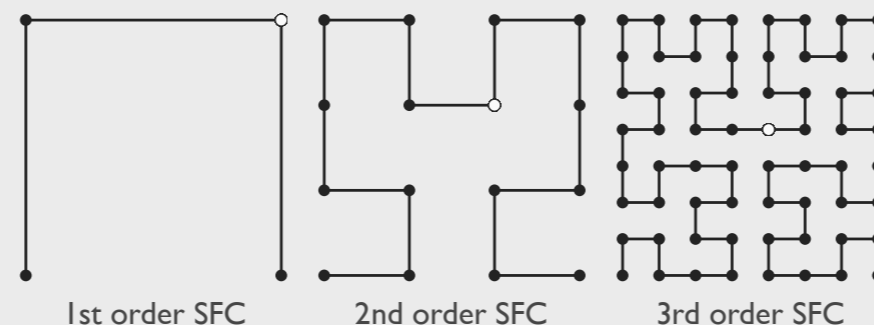
where $\{t\}$ is the fractional part of the real number t .

The Hilbert space filling curve $H(t) = (x, y)$, $t \in [0, 1)$ defines a nested recursive grid and a locally-preserving traversal order of grid elements. Plugin-in $G_s(\cdot)$ in $H(\cdot)$, we obtain the following sets of N uniformly distributed points:

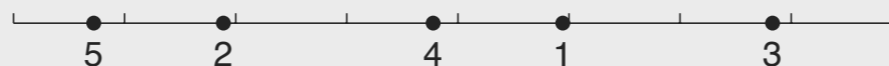
$$H(G_s(i)) = H(\{s + i \cdot \tau\}), \quad i \in [1 \dots N]. \quad (2)$$

A key corollary of the strong irrationality of ϕ is that the fractional parts of integer multiples will not align on any regular grid.

HILBERT SPACE FILLING CURVE



Coordinates of the golden ratio sequence (below) are transformed from the unit interval to the unit square with the Hilbert space filling curve.



TOTAL VARIATION MINIMIZATION

Based on samples y of some given image ($y = Su^{\text{orig}}$), the reconstructed image u^{rec} minimizes the total variation and coincides with u^{orig} in the chosen samples:

$$u^{\text{rec}} = \arg \min_{Su=y} \text{TV}(u). \quad (1)$$

Here the total variation $\text{TV}(u)$ is defined in terms of the local differences (image gradients) $D(u) \equiv (D_h u, D_v u) \in \mathbb{R}^2$:

$$\text{TV}(u) = \sum_{i=1}^{N_1} \sum_{j=1}^{N_2} \sqrt{(D_h u_{i,j})^2 + (D_v u_{i,j})^2}. \quad (2)$$

We use an iterative scheme to compute the minimum TV solution.