Deformation Quantization and Symmetries Episode 3



Image: Image:

→ ∢ ∃ →

Programme

Introduction to the concept of deformation quantization (existence, classification and representation results for formal star products).

Notion of formal star products with symmetries;

э

< ロ > < 同 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 >

A Lie group G acts by **Poisson diffeomorphisms** on (M, P) iff

 $\{g^*u,g^*v\}=g^*(\{u,v\}) \qquad \forall u,v\in C^\infty(M), \forall g\in G,$

or, equivalently, if and only if $g_*P = P$ for all $g \in G$. In the symplectic case, this is equivalent to $g^*\omega = \omega$ for all $g \in G$. Then G is a symmetry group for our classical system.

Any X in the Lie algebra $\mathfrak g$ of G gives rise to a fundamental vector field X^{*M}

$$X_p^{*M} = \frac{d}{dt}_{vert0} \exp -tX \cdot p;$$

then $[X^{*M}, Y^{*M}] = [X, Y]^{*M}$ and we have an infinitesimal Poisson action of g

$$\mathcal{L}_{X^{*M}}\{u, v\} = \{\mathcal{L}_{X^{*M}}u, v\} + \{u, \mathcal{L}_{X^{*M}}v\}$$
(1)

イロト イヨト イヨト イヨト 三日

or equivalently $\mathcal{L}_{X^{*M}}P = 0$ or, in the symplectic case $\mathcal{L}_{X^{*M}}\omega = 0$ which says that $\iota(X^{*M})\omega$ is a closed 1-form on M.

A Lie group G acts by **Poisson diffeomorphisms** on (M, P) iff

 $\{g^*u,g^*v\}=g^*(\{u,v\}) \qquad \forall u,v\in C^\infty(M), \forall g\in G,$

or, equivalently, if and only if $g_*P = P$ for all $g \in G$. In the symplectic case, this is equivalent to $g^*\omega = \omega$ for all $g \in G$. Then G is a symmetry group for our classical system.

Any X in the Lie algebra \mathfrak{g} of G gives rise to a fundamental vector field X^{*M}

$$X_p^{*M} = \frac{d}{dt}_{vert0} \exp -tX \cdot p;$$

then $[X^{*M}, Y^{*M}] = [X, Y]^{*M}$ and we have an infinitesimal Poisson action of g

$$\mathcal{L}_{X^{*M}}\{u, v\} = \{\mathcal{L}_{X^{*M}}u, v\} + \{u, \mathcal{L}_{X^{*M}}v\}$$
(1)

or equivalently $\mathcal{L}_{X^{*M}}P = 0$ or, in the symplectic case $\mathcal{L}_{X^{*M}}\omega = 0$ which says that $\iota(X^{*M})\omega$ is a closed 1-form on M.

▲□▶ ▲圖▶ ▲ 臣▶ ▲ 臣▶ 三臣 - のへで

A Lie group G acts by **Poisson diffeomorphisms** on (M, P) iff

 $\{g^*u,g^*v\}=g^*(\{u,v\}) \qquad \forall u,v\in C^\infty(M),\forall g\in G,$

or, equivalently, if and only if $g_*P = P$ for all $g \in G$. In the symplectic case, this is equivalent to $g^*\omega = \omega$ for all $g \in G$. Then G is a symmetry group for our classical system.

Any X in the Lie algebra \mathfrak{g} of G gives rise to a fundamental vector field X^{*M}

$$X_p^{*M} = \frac{d}{dt}_{vert0} \exp -tX \cdot p;$$

then $[X^{*M}, Y^{*M}] = [X, Y]^{*M}$ and we have an infinitesimal Poisson action of g

$$\mathcal{L}_{X^{*M}}\{u, v\} = \{\mathcal{L}_{X^{*M}}u, v\} + \{u, \mathcal{L}_{X^{*M}}v\}$$
(1)

or equivalently $\mathcal{L}_{X^{*M}}P = 0$ or, in the symplectic case $\mathcal{L}_{X^{*M}}\omega = 0$ which says that $\iota(X^{*M})\omega$ is a closed 1-form on M.

▲□▶ ▲圖▶ ▲ 臣▶ ▲ 臣▶ 三臣 - のへで

The action of a Lie group on the classical Hilbert space framework of quantum mechanics is described by a unitary representation of the group on the Hilbert space; such a representation acts by conjugaison on the set of selfadjoint operators on that space and yields an automorphism of the algebra of quantum observables.

In the setting of deformation quantization, the classical action of a group G on a Poisson manifold extends to the algebra of observables $C^{\infty}(M)[[\nu]]$ and one can define different notions of invariance of the deformation quantization under the action of a Lie group.

Assume (M, P) is a Poisson manifold and G is a Lie group acting on M. Let $(\mathbb{C}^{\infty}(M)[[\nu]], \star)$ be a deformation quantization of (M, P). The star product is said to be geometrically invariant if,

 $g^*(u \star v) = g^*u \star g^*v \qquad \forall g \in G, \forall u, v \in C^{\infty}(M).$

This clearly implies that $g^*(\{u, v\}) = \{g^*u, g^*v\}$ so G acts by Poisson diffeomorphisms.

 X^{*M} is then a derivation of the star product $X^{*M}(u \star v) = (X^{*M}u) \star v + u \star (X^{*M}v)$.

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

The action of a Lie group on the classical Hilbert space framework of quantum mechanics is described by a unitary representation of the group on the Hilbert space; such a representation acts by conjugaison on the set of selfadjoint operators on that space and yields an automorphism of the algebra of quantum observables.

In the setting of deformation quantization, the classical action of a group G on a Poisson manifold extends to the algebra of observables $C^{\infty}(M)[[\nu]]$ and one can define different notions of invariance of the deformation quantization under the action of a Lie group.

Assume (M, P) is a Poisson manifold and G is a Lie group acting on M. Let $(\mathbb{C}^{\infty}(M)[[\nu]], \star)$ be a deformation quantization of (M, P). The star product is said to be geometrically invariant if,

 $g^*(u \star v) = g^*u \star g^*v \qquad \forall g \in G, \forall u, v \in C^{\infty}(M).$

This clearly implies that $g^*(\{u, v\}) = \{g^*u, g^*v\}$ so G acts by Poisson diffeomorphisms.

 X^{*M} is then a derivation of the star product $X^{*M}(u \star v) = (X^{*M}u) \star v + u \star (X^{*M}v)$.

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

The action of a Lie group on the classical Hilbert space framework of quantum mechanics is described by a unitary representation of the group on the Hilbert space; such a representation acts by conjugaison on the set of selfadjoint operators on that space and yields an automorphism of the algebra of quantum observables.

In the setting of deformation quantization, the classical action of a group G on a Poisson manifold extends to the algebra of observables $C^{\infty}(M)[[\nu]]$ and one can define different notions of invariance of the deformation quantization under the action of a Lie group.

Assume (M, P) is a Poisson manifold and G is a Lie group acting on M. Let $(\mathbb{C}^{\infty}(M)[[\nu]], \star)$ be a deformation quantization of (M, P). The star product is said to be geometrically invariant if,

 $g^*(u \star v) = g^*u \star g^*v \qquad \forall g \in G, \forall u, v \in C^{\infty}(M).$

This clearly implies that $g^*(\{u, v\}) = \{g^*u, g^*v\}$ so G acts by Poisson diffeomorphisms.

 X^{*M} is then a derivation of the star product $X^{*M}(u \star v) = (X^{*M}u) \star v + u \star (X^{*M}v)$.

イロト イヨト イヨト 一日

More generally, symmetries in quantum theories are automorphisms of the algebra of observables. A symmetry σ of a star product \star is an automorphism of the $\mathbb{C}[[\nu]]$ -algebra ($C^{\infty}(M)[[\nu]], \star$)

$$\sigma(u \star v) = \sigma(u) \star \sigma(v), \qquad \sigma(1) = 1,$$

where σ is a formal series of linear maps.

One can show that $\sigma(u) = T(u \circ \tau)$ where τ is a Poisson diffeomorphism of (M, P) and $T = \text{Id} + \sum_{r>1} \nu^r T_r$ a formal series of differential maps.

A Lie group G acts as symmetries of $(C^{\infty}(M)[[\nu]], \star)$ if there is a homomorphism

 $\sigma: G \to \operatorname{Aut}(M, \star).$

In that case, $\sigma(g)u = T(g)(\tau(g)^*u)$ and τ defines a Poisson action of G on (M, P).

3

(日)

More generally, symmetries in quantum theories are automorphisms of the algebra of observables. A symmetry σ of a star product \star is an automorphism of the $\mathbb{C}[[\nu]]$ -algebra ($C^{\infty}(M)[[\nu]], \star$)

$$\sigma(u \star v) = \sigma(u) \star \sigma(v), \qquad \sigma(1) = 1,$$

where σ is a formal series of linear maps.

One can show that $\sigma(u) = T(u \circ \tau)$ where τ is a Poisson diffeomorphism of (M, P) and $T = \text{Id} + \sum_{r>1} \nu^r T_r$ a formal series of differential maps.

A Lie group G acts as symmetries of $(C^{\infty}(M)[[\nu]], \star)$ if there is a homomorphism

 $\sigma: G \to \operatorname{Aut}(M, \star).$

In that case, $\sigma(g)u = T(g)(\tau(g)^*u)$ and τ defines a Poisson action of G on (M, P).

3

・ロト ・ 四ト ・ ヨト ・ ヨト …

More generally, symmetries in quantum theories are automorphisms of the algebra of observables. A symmetry σ of a star product \star is an automorphism of the $\mathbb{C}[[\nu]]$ -algebra ($C^{\infty}(M)[[\nu]], \star$)

$$\sigma(u \star v) = \sigma(u) \star \sigma(v), \qquad \sigma(1) = 1,$$

where σ is a formal series of linear maps.

One can show that $\sigma(u) = T(u \circ \tau)$ where τ is a Poisson diffeomorphism of (M, P) and $T = \text{Id} + \sum_{r>1} \nu^r T_r$ a formal series of differential maps.

A Lie group G acts as symmetries of $(C^{\infty}(M)[[\nu]], \star)$ if there is a homomorphism

 $\sigma: G \to \operatorname{Aut}(M, \star).$

In that case, $\sigma(g)u = T(g)(\tau(g)^*u)$ and τ defines a Poisson action of G on (M, P).

イロト 不得 トイヨト イヨト 二日

Existence and classification of invariant star products on a Poisson manifold is known, provided there exists an invariant connection on the manifold.

Fedosov's construction in the symplectic case builds a star product $\star_{\nabla,0}$, from a symplectic connection ∇ . If ∇ is invariant under the action of G, $\star_{\nabla,0}$ is invariant.

More generally, any diffeomorphism ϕ of (M, ω) is a symmetry of the Fedosov star product $\star_{\nabla, \tilde{\Omega}}$ iff it preserves the symplectic 2-form ω , the connection ∇ and the series of closed 2-forms $\tilde{\Omega}$.

Reciprocally [Rawnsley-G], a natural star product on a symplectic manifold determines in a unique way a symplectic connection. Hence, when G acts on (M, ω) and leaves a natural * product invariant, there is a unique symplectic connection which is invariant under G.

< ロ > < 同 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 >

Existence and classification of invariant star products on a Poisson manifold is known, provided there exists an invariant connection on the manifold.

Fedosov's construction in the symplectic case builds a star product $\star_{\nabla,0}$, from a symplectic connection ∇ . If ∇ is invariant under the action of G, $\star_{\nabla,0}$ is invariant.

More generally, any diffeomorphism ϕ of (M, ω) is a symmetry of the Fedosov star product $\star_{\nabla, \tilde{\Omega}}$ iff it preserves the symplectic 2-form ω , the connection ∇ and the series of closed 2-forms $\tilde{\Omega}$.

Reciprocally [Rawnsley-G], a natural star product on a symplectic manifold determines in a unique way a symplectic connection. Hence, when G acts on (M, ω) and leaves a natural \star product invariant, there is a unique symplectic connection which is invariant under G.

э

イロト 不得 トイヨト イヨト

Existence and classification of invariant star products on a Poisson manifold is known, provided there exists an invariant connection on the manifold.

Fedosov's construction in the symplectic case builds a star product $\star_{\nabla,0}$, from a symplectic connection ∇ . If ∇ is invariant under the action of G, $\star_{\nabla,0}$ is invariant.

More generally, any diffeomorphism ϕ of (M, ω) is a symmetry of the Fedosov star product $\star_{\nabla, \tilde{\Omega}}$ iff it preserves the symplectic 2-form ω , the connection ∇ and the series of closed 2-forms $\tilde{\Omega}$.

Reciprocally [Rawnsley-G], a natural star product on a symplectic manifold determines in a unique way a symplectic connection. Hence, when G acts on (M, ω) and leaves a natural * product invariant, there is a unique symplectic connection which is invariant under G.

3

イロト 不得 トイヨト イヨト

Existence and classification of invariant star products on a Poisson manifold is known, provided there exists an invariant connection on the manifold.

Fedosov's construction in the symplectic case builds a star product $\star_{\nabla,0}$, from a symplectic connection ∇ . If ∇ is invariant under the action of G, $\star_{\nabla,0}$ is invariant.

More generally, any diffeomorphism ϕ of (M, ω) is a symmetry of the Fedosov star product $\star_{\nabla, \tilde{\Omega}}$ iff it preserves the symplectic 2-form ω , the connection ∇ and the series of closed 2-forms $\tilde{\Omega}$.

Reciprocally [Rawnsley-G], a natural star product on a symplectic manifold determines in a unique way a symplectic connection. Hence, when G acts on (M, ω) and leaves a natural * product invariant, there is a unique symplectic connection which is invariant under G.

3

(日)

Hence [Bertelson, Bieliavsky, G.], there is a bijection between the *G*-equivalence classes of *G*-invariant *-products on (M, ω) and the space of formal series of elements in the second space of invariant cohomology of M, $H^2(M, \mathbb{R})^{G-inv}[[\nu]]$.

Using Dolgushev's construction of a formality starting from a connection, one has a similar result in the Poisson setting : If there exists an invariant connection, there is a bijection between the *G*-equivalence classes of *G*-invariant *-products on (M, P) and the *G*-equivariant equivalence classes of *G*-invariant Poisson deformations of *P*.

Let us mention that there exist symplectic manifolds which are *G*-homogeneous but do not admit any *G*-invariant symplectic connection. A first example was given by Arnal: the orbit of a filiform nilpotent Lie group in the dual of its algebra.

イロト イポト イヨト イヨト

Hence [Bertelson, Bieliavsky, G.], there is a bijection between the *G*-equivalence classes of *G*-invariant *-products on (M, ω) and the space of formal series of elements in the second space of invariant cohomology of M, $H^2(M, \mathbb{R})^{G-inv}[[\nu]]$.

Using Dolgushev's construction of a formality starting from a connection, one has a similar result in the Poisson setting : If there exists an invariant connection, there is a bijection between the *G*-equivalence classes of *G*-invariant *-products on (M, P) and the *G*-equivariant equivalence classes of *G*-invariant Poisson deformations of *P*.

Let us mention that there exist symplectic manifolds which are *G*-homogeneous but do not admit any *G*-invariant symplectic connection. A first example was given by Arnal: the orbit of a filiform nilpotent Lie group in the dual of its algebra.

イロト イポト イヨト イヨト

Hence [Bertelson, Bieliavsky, G.], there is a bijection between the *G*-equivalence classes of *G*-invariant *-products on (M, ω) and the space of formal series of elements in the second space of invariant cohomology of M, $H^2(M, \mathbb{R})^{G-inv}[[\nu]]$.

Using Dolgushev's construction of a formality starting from a connection, one has a similar result in the Poisson setting : If there exists an invariant connection, there is a bijection between the *G*-equivalence classes of *G*-invariant *-products on (M, P) and the *G*-equivariant equivalence classes of *G*-invariant Poisson deformations of *P*.

Let us mention that there exist symplectic manifolds which are *G*-homogeneous but do not admit any *G*-invariant symplectic connection. A first example was given by Arnal: the orbit of a filiform nilpotent Lie group in the dual of its algebra.

Hence [Bertelson, Bieliavsky, G.], there is a bijection between the *G*-equivalence classes of *G*-invariant *-products on (M, ω) and the space of formal series of elements in the second space of invariant cohomology of M, $H^2(M, \mathbb{R})^{G-inv}[[\nu]]$.

Using Dolgushev's construction of a formality starting from a connection, one has a similar result in the Poisson setting : If there exists an invariant connection, there is a bijection between the *G*-equivalence classes of *G*-invariant *-products on (M, P) and the *G*-equivariant equivalence classes of *G*-invariant Poisson deformations of *P*.

Let us mention that there exist symplectic manifolds which are *G*-homogeneous but do not admit any *G*-invariant symplectic connection. A first example was given by Arnal: the orbit of a filiform nilpotent Lie group in the dual of its algebra.

э

Invariant star products on Lie groups and Drinfeld twists

The class of manifolds with a simply transitive action are Lie groups with the action given by left multiplication; one is interested in left invariant *-products on Lie groups.

Since left invariant differential operators on a Lie group G are identified with elements in the universal enveloping algebra $\mathcal{U}(\mathfrak{g})$, left invariant bidifferential operators can be viewed as elements of $\mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})$ and a left invariant \star -product on a Lie group G is given by an element

$F \in (\mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})) \, [[\nu]].$

such that

- $(\Delta \otimes \mathrm{Id})(F) \circ (F \otimes 1) = (\mathrm{Id} \otimes \Delta)(F) \circ (1 \otimes F)$ where \circ denotes the product in $\mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})$ and $\Delta : \mathcal{U}(\mathfrak{g}) \to \mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})$ is the usual coproduct $(\Delta : \mathcal{U}(\mathfrak{g}) \to \mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})$ is the algebra morphism such that $\Delta(x) = 1 \otimes x + x \otimes 1$ for $x \in \mathfrak{g}$.) , both extended $\mathbb{C}[[\nu]]$ -linearly ; this expresses the associativity;
- $(\epsilon \otimes \operatorname{Id})F = 1 = (\operatorname{Id} \otimes \epsilon)F$, where $\epsilon : \mathcal{U}(\mathfrak{g}) \to \mathbb{C}$ is the counit; this expresses that $1 \star u = u \star 1 = u$;
- F = 1 ⊗ 1 + O(ν), which expresses that the zeroth order term is the usual product of functions.

Such an element is called a formal Drinfeld twist.

・ロト ・四ト ・ヨト ・ヨト

Invariant star products on Lie groups and Drinfeld twists

The class of manifolds with a simply transitive action are Lie groups with the action given by left multiplication; one is interested in left invariant *-products on Lie groups.

Since left invariant differential operators on a Lie group G are identified with elements in the universal enveloping algebra $\mathcal{U}(\mathfrak{g})$, left invariant bidifferential operators can be viewed as elements of $\mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})$ and a left invariant *-product on a Lie group G is given by an element

$F \in (\mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})) \, [[\nu]].$

such that

- $(\Delta \otimes \mathrm{Id})(F) \circ (F \otimes 1) = (\mathrm{Id} \otimes \Delta)(F) \circ (1 \otimes F)$ where \circ denotes the product in $\mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})$ and $\Delta : \mathcal{U}(\mathfrak{g}) \to \mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})$ is the usual coproduct $(\Delta : \mathcal{U}(\mathfrak{g}) \to \mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})$ is the algebra morphism such that $\Delta(x) = 1 \otimes x + x \otimes 1$ for $x \in \mathfrak{g}$.), both extended $\mathbb{C}[[\nu]$ -linearly; this expresses the associativity;
- $(\epsilon \otimes \operatorname{Id})F = 1 = (\operatorname{Id} \otimes \epsilon)F$, where $\epsilon : \mathcal{U}(\mathfrak{g}) \to \mathbb{C}$ is the counit; this expresses that $1 \star u = u \star 1 = u$;
- F = 1 ⊗ 1 + O(ν), which expresses that the zeroth order term is the usual product of functions.

Such an element is called a formal Drinfeld twist.

< ロ > < 同 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 >

Since left invariant differential operators on a Lie group G are identified with elements in the universal enveloping algebra $\mathcal{U}(\mathfrak{g})$, left invariant bidifferential operators can be viewed as elements of $\mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})$ and a left invariant \star -product on a Lie group G is given by an element

$F \in (\mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})) \, [[\nu]].$

such that

- $(\Delta \otimes \mathrm{Id})(F) \circ (F \otimes 1) = (\mathrm{Id} \otimes \Delta)(F) \circ (1 \otimes F)$ where \circ denotes the product in $\mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})$ and $\Delta : \mathcal{U}(\mathfrak{g}) \to \mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})$ is the usual coproduct $(\Delta : \mathcal{U}(\mathfrak{g}) \to \mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})$ is the algebra morphism such that $\Delta(x) = 1 \otimes x + x \otimes 1$ for $x \in \mathfrak{g}$.), both extended $\mathbb{C}[[\nu]]$ -linearly; this expresses the associativity;
- $(\epsilon \otimes \mathrm{Id})F = 1 = (\mathrm{Id} \otimes \epsilon)F$, where $\epsilon : \mathcal{U}(\mathfrak{g}) \to \mathbb{C}$ is the counit; this expresses that $1 \star u = u \star 1 = u$;
- F = 1 ⊗ 1 + O(ν), which expresses that the zeroth order term is the usual product of functions.

Such an element is called a formal Drinfeld twist.

3

イロト 不得 トイヨト イヨト

Since left invariant differential operators on a Lie group G are identified with elements in the universal enveloping algebra $\mathcal{U}(\mathfrak{g})$, left invariant bidifferential operators can be viewed as elements of $\mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})$ and a left invariant \star -product on a Lie group G is given by an element

$F \in (\mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})) \, [[\nu]].$

such that

- $(\Delta \otimes \mathrm{Id})(F) \circ (F \otimes 1) = (\mathrm{Id} \otimes \Delta)(F) \circ (1 \otimes F)$ where \circ denotes the product in $\mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})$ and $\Delta : \mathcal{U}(\mathfrak{g}) \to \mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})$ is the usual coproduct $(\Delta : \mathcal{U}(\mathfrak{g}) \to \mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})$ is the algebra morphism such that $\Delta(x) = 1 \otimes x + x \otimes 1$ for $x \in \mathfrak{g}$.), both extended $\mathbb{C}[[\nu]]$ -linearly; this expresses the associativity;
- $(\epsilon \otimes \operatorname{Id})F = 1 = (\operatorname{Id} \otimes \epsilon)F$, where $\epsilon : \mathcal{U}(\mathfrak{g}) \to \mathbb{C}$ is the counit; this expresses that $1 \star u = u \star 1 = u$;
- F = 1 ⊗ 1 + O(ν), which expresses that the zeroth order term is the usual product of functions.

Such an element is called a formal Drinfeld twist.

3

イロト 不得 トイヨト イヨト

Since left invariant differential operators on a Lie group G are identified with elements in the universal enveloping algebra $\mathcal{U}(\mathfrak{g})$, left invariant bidifferential operators can be viewed as elements of $\mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})$ and a left invariant \star -product on a Lie group G is given by an element

$F \in (\mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})) \, [[\nu]].$

such that

- $(\Delta \otimes \mathrm{Id})(F) \circ (F \otimes 1) = (\mathrm{Id} \otimes \Delta)(F) \circ (1 \otimes F)$ where \circ denotes the product in $\mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})$ and $\Delta : \mathcal{U}(\mathfrak{g}) \to \mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})$ is the usual coproduct $(\Delta : \mathcal{U}(\mathfrak{g}) \to \mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})$ is the algebra morphism such that $\Delta(x) = 1 \otimes x + x \otimes 1$ for $x \in \mathfrak{g}$.), both extended $\mathbb{C}[[\nu]]$ -linearly; this expresses the associativity;
- $(\epsilon \otimes \operatorname{Id})F = 1 = (\operatorname{Id} \otimes \epsilon)F$, where $\epsilon : \mathcal{U}(\mathfrak{g}) \to \mathbb{C}$ is the counit; this expresses that $1 \star u = u \star 1 = u$;
- $F = 1 \otimes 1 + O(\nu)$, which expresses that the zeroth order term is the usual product of functions.

Such an element is called a formal Drinfeld twist.

3

(日)

Since left invariant differential operators on a Lie group G are identified with elements in the universal enveloping algebra $\mathcal{U}(\mathfrak{g})$, left invariant bidifferential operators can be viewed as elements of $\mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})$ and a left invariant \star -product on a Lie group G is given by an element

$F \in (\mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})) \, [[\nu]].$

such that

- $(\Delta \otimes \mathrm{Id})(F) \circ (F \otimes 1) = (\mathrm{Id} \otimes \Delta)(F) \circ (1 \otimes F)$ where \circ denotes the product in $\mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})$ and $\Delta : \mathcal{U}(\mathfrak{g}) \to \mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})$ is the usual coproduct $(\Delta : \mathcal{U}(\mathfrak{g}) \to \mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})$ is the algebra morphism such that $\Delta(x) = 1 \otimes x + x \otimes 1$ for $x \in \mathfrak{g}$.), both extended $\mathbb{C}[[\nu]]$ -linearly; this expresses the associativity;
- $(\epsilon \otimes \operatorname{Id})F = 1 = (\operatorname{Id} \otimes \epsilon)F$, where $\epsilon : \mathcal{U}(\mathfrak{g}) \to \mathbb{C}$ is the counit; this expresses that $1 \star u = u \star 1 = u$;
- $F = 1 \otimes 1 + O(\nu)$, which expresses that the zeroth order term is the usual product of functions.

Such an element is called a formal Drinfeld twist.

3

(日)

Since left invariant differential operators on a Lie group G are identified with elements in the universal enveloping algebra $\mathcal{U}(\mathfrak{g})$, left invariant bidifferential operators can be viewed as elements of $\mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})$ and a left invariant \star -product on a Lie group G is given by an element

$F \in (\mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})) \, [[\nu]].$

such that

- $(\Delta \otimes \mathrm{Id})(F) \circ (F \otimes 1) = (\mathrm{Id} \otimes \Delta)(F) \circ (1 \otimes F)$ where \circ denotes the product in $\mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})$ and $\Delta : \mathcal{U}(\mathfrak{g}) \to \mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})$ is the usual coproduct $(\Delta : \mathcal{U}(\mathfrak{g}) \to \mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g})$ is the algebra morphism such that $\Delta(x) = 1 \otimes x + x \otimes 1$ for $x \in \mathfrak{g}$.), both extended $\mathbb{C}[[\nu]]$ -linearly; this expresses the associativity;
- $(\epsilon \otimes \operatorname{Id})F = 1 = (\operatorname{Id} \otimes \epsilon)F$, where $\epsilon : \mathcal{U}(\mathfrak{g}) \to \mathbb{C}$ is the counit; this expresses that $1 \star u = u \star 1 = u$;
- $F = 1 \otimes 1 + O(\nu)$, which expresses that the zeroth order term is the usual product of functions.

Such an element is called a formal Drinfeld twist.

3

イロン イヨン イヨン

The skewsymmetric part of the first order term, which is automatically in $\mathfrak{g} \otimes \mathfrak{g}$ corresponds to a left invariant Poisson structure on *G* and is what is called a classical *r*-matrix.

Drinfeld has proven in 83 that any classical *r*-matrix arises as the first term of a Drinfeld twist (see Halbout about formality of bialgebras, or Esposito, Schnitzer and Waldmann in 2017 about a universal construction).

An invariant equivalence is given by an element $S \in \mathcal{U}(\mathfrak{g})[[\nu]]$ of the form $S = 1 + O(\nu)$ and the equivalent *-product is defined by the new Drinfeld twist given by

 $F' = \Delta(S^{-1})F(S \otimes S).$

An analogous algebraic construction on a homogeneous space M = G/H was given by Alekseev and Lachowska in 2005; invariant bidifferential operators on G/H are viewed as elements of $((\mathcal{U}(\mathfrak{g})/\mathcal{U}(\mathfrak{g}) \cdot \mathfrak{h})^{\otimes 2})^H$; a star product is given in terms of a series $B \in ((\mathcal{U}(\mathfrak{g})/\mathcal{U}(\mathfrak{g}) \cdot \mathfrak{h})^{\otimes 2})^H[[\nu]]$ and associativity writes again as $((\Delta \otimes \mathrm{Id})B)(B \otimes 1) = ((\mathrm{Id} \otimes \Delta)B)(1 \otimes B)$ where both sides define uniquely invariant tri-differential operators on G/H.

<ロト < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

The skewsymmetric part of the first order term, which is automatically in $\mathfrak{g} \otimes \mathfrak{g}$ corresponds to a left invariant Poisson structure on *G* and is what is called a classical *r*-matrix.

Drinfeld has proven in 83 that any classical *r*-matrix arises as the first term of a Drinfeld twist (see Halbout about formality of bialgebras, or Esposito, Schnitzer and Waldmann in 2017 about a universal construction).

An invariant equivalence is given by an element $S \in \mathcal{U}(\mathfrak{g})[[\nu]]$ of the form $S = 1 + O(\nu)$ and the equivalent *-product is defined by the new Drinfeld twist given by

$F' = \Delta(S^{-1})F(S \otimes S).$

An analogous algebraic construction on a homogeneous space M = G/H was given by Alekseev and Lachowska in 2005; invariant bidifferential operators on G/H are viewed as elements of $((\mathcal{U}(\mathfrak{g})/\mathcal{U}(\mathfrak{g}) \cdot \mathfrak{h})^{\otimes 2})^{H}$; a star product is given in terms of a series $B \in ((\mathcal{U}(\mathfrak{g})/\mathcal{U}(\mathfrak{g}) \cdot \mathfrak{h})^{\otimes 2})^{H}[[\nu]]$ and associativity writes again as $((\Delta \otimes \mathrm{Id})B)(B \otimes 1) = ((\mathrm{Id} \otimes \Delta)B)(1 \otimes B)$ where both sides define uniquely invariant tri-differential operators on G/H.

▲□▶ ▲圖▶ ▲ 臣▶ ▲ 臣▶ 三臣 - のへで

The skewsymmetric part of the first order term, which is automatically in $\mathfrak{g} \otimes \mathfrak{g}$ corresponds to a left invariant Poisson structure on *G* and is what is called a classical *r*-matrix.

Drinfeld has proven in 83 that any classical *r*-matrix arises as the first term of a Drinfeld twist (see Halbout about formality of bialgebras, or Esposito, Schnitzer and Waldmann in 2017 about a universal construction).

An invariant equivalence is given by an element $S \in \mathcal{U}(\mathfrak{g})[[\nu]]$ of the form $S = 1 + O(\nu)$ and the equivalent *-product is defined by the new Drinfeld twist given by

$$F' = \Delta(S^{-1})F(S \otimes S).$$

An analogous algebraic construction on a homogeneous space M = G/H was given by Alekseev and Lachowska in 2005; invariant bidifferential operators on G/H are viewed as elements of $((\mathcal{U}(\mathfrak{g})/\mathcal{U}(\mathfrak{g}) \cdot \mathfrak{h})^{\otimes 2})^{H}$; a star product is given in terms of a series $B \in ((\mathcal{U}(\mathfrak{g})/\mathcal{U}(\mathfrak{g}) \cdot \mathfrak{h})^{\otimes 2})^{H}[[\nu]]$ and associativity writes again as $((\Delta \otimes \mathrm{Id})B)(B \otimes 1) = ((\mathrm{Id} \otimes \Delta)B)(1 \otimes B)$ where both sides define uniquely invariant tri-differential operators on G/H.

▲□▶ ▲圖▶ ▲ 臣▶ ▲ 臣▶ 三臣 - のへで

Given a left invariant star product on a Lie group, hence a formal Drinfeld twist $F \in (\mathcal{U}(\mathfrak{g}) \otimes \mathcal{U}(\mathfrak{g}))[[\nu]]$ on its Lie algebra \mathfrak{g} , one can deform any associative algebra (A, μ_A) acted upon by \mathfrak{g} through derivations.

This process is called a universal deformation formula and is defined as follows:

 $a \star_F b := \mu_A (F \bullet (a \otimes b))$

where • denotes the action of $\mathcal{U}(\mathfrak{g}) \times \mathcal{U}(\mathfrak{g})[[\nu]]$ on $A \times A[[\nu]]$ which is the extension of the action of \mathfrak{g} on A to an action of $\mathcal{U}(\mathfrak{g}) \times \mathcal{U}(\mathfrak{g})$ on $A \times A$ extended $\mathbb{C}[[\nu]]$ -linearly. The properties of a twist ensure that \star_F is an associative deformation of μ_A . (Giaquinto and Zhang in 1998, by Bieliavsky and Gayral in a non formal setting, Esposito, Schnitzer and Waldmann).

3

イロト イヨト イヨト ・

Programme

Introduction to the concept of deformation quantization (existence, classification and representation results for formal star products).

Notion of formal star products with symmetries; one has a Lie group action (or a Lie algebra action) compatible with the classical Poisson structure, and one wants to consider star products such that the Lie group acts by automorphisms (or the Lie algebra acts by derivations). We recall in particular the link between left invariant star products on Lie groups and Drinfeld twists, and the notion of universal deformation formulas.

Quantum moment map : Classically, symmetries are particularly interesting when they are implemented by a moment map and we give indications to build a corresponding quantum version.

・ 同 ト ・ ヨ ト ・ ヨ ト

Of particular importance in physics is the case where the action is implemented by a moment map. The action is called (almost) Hamiltonian when each fundamental vector field is Hamiltonian, i.e. when for each $X \in \mathfrak{g}$ there exists a function f_X on M such that

$$X^{*M}u = \{f_X, u\} \qquad \forall u \in C^{\infty}(M).$$

In the symplectic case this amounts to say that $\iota(X^{*M})\omega = df_X$.

When the Hamiltonian governing the dynamics on (M, P) is invariant under the action of G, any of those functions f_X is a constant of the motion.

A further assumption is to ask that the action possesses **a** G **equivariant moment map** J:

$$J: M \to \mathfrak{g}^*$$
 s.t. $X^{*M}u = \{ \langle J, X \rangle, u \} \quad \forall u \in C^{\infty}(M)$

 $\langle J, X \rangle : M \to \mathbb{R} : p \mapsto \langle J(p), X \rangle, \langle ., . \rangle$ denoting the pairing between g and its dual. Equivariance means that the Hamiltonian functions $f_X := \langle J, X \rangle$ satisfy $f_X(g \cdot p) = f_{Adg^{-1}X}(p)$ and thus

$$\{f_X, f_Y\} = f_{[X,Y]} \quad \forall X, Y \in \mathfrak{g}.$$

An action so that each fundamental vector field is Hamiltonian and so that one can choose $X \mapsto f_X$ to be a homomorphism of Lie algebras is also called a **(strongly) Hamiltonian action**. If G is connected, it is equivalent to the existence of a G equivariant moment mapping $f_{A} = f_{A}$.

Of particular importance in physics is the case where the action is implemented by a moment map. The action is called (almost) Hamiltonian when each fundamental vector field is Hamiltonian, i.e. when for each $X \in \mathfrak{g}$ there exists a function f_X on M such that

$$X^{*M}u = \{f_X, u\} \qquad \forall u \in C^{\infty}(M).$$

In the symplectic case this amounts to say that $\iota(X^{*M})\omega = df_X$.

When the Hamiltonian governing the dynamics on (M, P) is invariant under the action of G, any of those functions f_X is a constant of the motion.

A further assumption is to ask that the action possesses a G equivariant moment map J:

$$J: M \to \mathfrak{g}^*$$
 s.t. $X^{*M}u = \{ \langle J, X \rangle, u \} \quad \forall u \in C^{\infty}(M)$

 $\langle J, X \rangle$: $M \to \mathbb{R}$: $p \mapsto \langle J(p), X \rangle$, $\langle ., . \rangle$ denoting the pairing between g and its dual. Equivariance means that the Hamiltonian functions $f_X := \langle J, X \rangle$ satisfy $f_X(g \cdot p) = f_{Adg}^{-1}(p)$ and thus

$$\{f_X, f_Y\} = f_{[X,Y]} \quad \forall X, Y \in \mathfrak{g}.$$

An action so that each fundamental vector field is Hamiltonian and so that one can choose $X \mapsto f_X$ to be a homomorphism of Lie algebras is also called a **(strongly) Hamiltonian action**. If G is connected, it is equivalent to the existence of a G equivariant moment map. $\mathfrak{g} : \mathfrak{g} : \mathfrak{g} = \mathfrak{g} \mathfrak{g}$

Of particular importance in physics is the case where the action is implemented by a moment map. The action is called (almost) Hamiltonian when each fundamental vector field is Hamiltonian, i.e. when for each $X \in \mathfrak{g}$ there exists a function f_X on M such that

$$X^{*M}u = \{f_X, u\} \qquad \forall u \in C^{\infty}(M).$$

In the symplectic case this amounts to say that $\iota(X^{*M})\omega = df_X$.

When the Hamiltonian governing the dynamics on (M, P) is invariant under the action of G, any of those functions f_X is a constant of the motion.

A further assumption is to ask that the action possesses a G equivariant moment map J:

$$J: M \to \mathfrak{g}^*$$
 s.t. $X^{*M}u = \{ \langle J, X \rangle, u \} \quad \forall u \in C^{\infty}(M)$

 $\langle J, X \rangle : M \to \mathbb{R} : p \mapsto \langle J(p), X \rangle, \langle ., . \rangle$ denoting the pairing between g and its dual. Equivariance means that the Hamiltonian functions $f_X := \langle J, X \rangle$ satisfy $f_X(g \cdot p) = f_{Adg^{-1}X}(p)$ and thus

$$\{f_X, f_Y\} = f_{[X,Y]} \quad \forall X, Y \in \mathfrak{g}.$$

An action so that each fundamental vector field is Hamiltonian and so that one can choose $X \mapsto f_X$ to be a homomorphism of Lie algebras is also called a **(strongly) Hamiltonian action**. If G is connected, it is equivalent to the existence of a G equivariant moment, mapping $f_X = f_X$.

Of particular importance in physics is the case where the action is implemented by a moment map. The action is called (almost) Hamiltonian when each fundamental vector field is Hamiltonian, i.e. when for each $X \in \mathfrak{g}$ there exists a function f_X on M such that

$$X^{*M}u = \{f_X, u\} \qquad \forall u \in C^{\infty}(M).$$

In the symplectic case this amounts to say that $\iota(X^{*M})\omega = df_X$.

When the Hamiltonian governing the dynamics on (M, P) is invariant under the action of G, any of those functions f_X is a constant of the motion.

A further assumption is to ask that the action possesses a G equivariant moment map J:

$$J: M \to \mathfrak{g}^*$$
 s.t. $X^{*M}u = \{ \langle J, X \rangle, u \} \quad \forall u \in C^{\infty}(M)$

 $\langle J, X \rangle : M \to \mathbb{R} : p \mapsto \langle J(p), X \rangle, \langle ., . \rangle$ denoting the pairing between g and its dual. Equivariance means that the Hamiltonian functions $f_X := \langle J, X \rangle$ satisfy $f_X(g \cdot p) = f_{Adg^{-1}X}(p)$ and thus

$$\{f_X, f_Y\} = f_{[X,Y]} \quad \forall X, Y \in \mathfrak{g}.$$

An action so that each fundamental vector field is Hamiltonian and so that one can choose $X \mapsto f_X$ to be a homomorphism of Lie algebras is also called a **(strongly) Hamiltonian action**. If G is connected, it is equivalent to the existence of a G equivariant moment map. $f \equiv f = f_{X}$

An action of the Lie algebra \mathfrak{g} on the deformed algebra, $(C^{\infty}(M)[\nu]], \star)$, is a homomorphism $D: \mathfrak{g} \to \operatorname{Der}(M, \star)$ into the space of derivations of the star product.

A derivation D is essentially inner or Hamiltonian if $D = \frac{1}{\nu} \operatorname{ad}_* u$ for some $u \in C^{\infty}(M)[[\nu]]$. We call an action of a Lie algebra (or of a Lie group) on a deformed algebra almost *-Hamiltonian if each D(X), for any $X \in \mathfrak{g}$, is essentially inner, and we call (quantum) Hamiltonian a linear choice of functions u_X satisfying

$$D(X) = \frac{1}{\nu} \operatorname{ad}_{\star} u_X, \qquad X \in \mathfrak{g}.$$

The action is ***-Hamiltonian** if u_X can be chosen to make the map

$$\mathfrak{g} \to C^{\infty}(M)[[\nu]]: X \mapsto u_X$$

a homomorphism of Lie algebras (i.e. $rac{1}{
u}(u_X \star u_Y - \star u_Y \star u_X) = u_{[X,Y]} \quad orall X, Y \in \mathfrak{g}).$

(日) (四) (日) (日) (日)

An action of the Lie algebra \mathfrak{g} on the deformed algebra, $(C^{\infty}(M)[\nu]], \star)$, is a homomorphism $D: \mathfrak{g} \to \operatorname{Der}(M, \star)$ into the space of derivations of the star product.

A derivation D is essentially inner or Hamiltonian if $D = \frac{1}{\nu} \operatorname{ad}_{\star} u$ for some $u \in C^{\infty}(M)[[\nu]]$.

We call an action of a Lie algebra (or of a Lie group) on a deformed algebra **almost *-Hamiltonian** if each D(X), for any $X \in \mathfrak{g}$, is essentially inner, and we call (quantum) Hamiltonian a linear choice of functions u_X satisfying

$$D(X) = \frac{1}{\nu} \operatorname{ad}_{\star} u_X, \qquad X \in \mathfrak{g}.$$

The action is \star -Hamiltonian if u_X can be chosen to make the map

$$\mathfrak{g} \to C^{\infty}(M)[[\nu]]: X \mapsto u_X$$

a homomorphism of Lie algebras (i.e. $\frac{1}{\nu}(u_X \star u_Y - \star u_Y \star u_X) = u_{[X,Y]} \quad \forall X, Y \in \mathfrak{g}).$

イロト イヨト イヨト

An action of the Lie algebra \mathfrak{g} on the deformed algebra, $(C^{\infty}(M)[\nu]], \star)$, is a homomorphism $D: \mathfrak{g} \to \operatorname{Der}(M, \star)$ into the space of derivations of the star product.

A derivation D is essentially inner or Hamiltonian if $D = \frac{1}{\nu} \operatorname{ad}_{\star} u$ for some $u \in C^{\infty}(M)[[\nu]]$.

We call an action of a Lie algebra (or of a Lie group) on a deformed algebra **almost** *-Hamiltonian if each D(X), for any $X \in \mathfrak{g}$, is essentially inner, and we call (quantum) Hamiltonian a linear choice of functions u_X satisfying

$$D(X) = \frac{1}{\nu} \operatorname{ad}_{\star} u_X, \qquad X \in \mathfrak{g}.$$

The action is \star -Hamiltonian if u_X can be chosen to make the map

$$\mathfrak{g} \to C^{\infty}(M)[[\nu]]: X \mapsto u_X$$

a homomorphism of Lie algebras (i.e. $\frac{1}{\nu}(u_X \star u_Y - \star u_Y \star u_X) = u_{[X,Y]} \quad \forall X, Y \in \mathfrak{g}).$

イロト イヨト イヨト -

When \star is invariant under the action of G on (M, P) and the corresponding action of the Lie algebra \mathfrak{g} (given by $D(X) = X^{*M}$) is \star -Hamiltonian, a map $\mathfrak{g} \to C^{\infty}(M)[[\nu]]$ s.t.

$$X^{*M} = \frac{1}{\nu} \operatorname{ad}_{\star} u_X, \qquad \frac{1}{\nu} (u_X \star u_Y - \star u_Y \star u_X) = u_{[X,Y]} \qquad X, Y \in \mathfrak{g}.$$

is called a quantum moment map [Xu].

For a (strongly) Hamiltonian action of Lie group G on (M, P), with $f : \mathfrak{g} \to \mathbb{C}^{\infty}(M)$ describing the classical moment map (i.e. $X^{*M}u = \{f_X, u\}$),

• a star product is said to be covariant under G if

$$\frac{1}{\nu}(f_X \star f_Y - f_Y \star f_X) = f_{[X,Y]} \quad \forall X, Y \in \mathfrak{g}$$

• and is called strongly invariant if it is geometrically invariant and

$$\frac{1}{\nu}(f_X \star u - u \star f_X) = \{f_X, u\} = X^{*M}u \quad \forall X \in \mathfrak{g}, u \in C^{\infty}(M)$$

In that case, f is a quantum moment map.

イロト イポト イヨト イヨト

When \star is invariant under the action of G on (M, P) and the corresponding action of the Lie algebra \mathfrak{g} (given by $D(X) = X^{*M}$) is \star -Hamiltonian, a map $\mathfrak{g} \to C^{\infty}(M)[[\nu]]$ s.t.

$$X^{*M} = \frac{1}{\nu} \operatorname{ad}_{\star} u_X, \qquad \frac{1}{\nu} (u_X \star u_Y - \star u_Y \star u_X) = u_{[X,Y]} \qquad X, Y \in \mathfrak{g}.$$

is called a quantum moment map [Xu].

For a (strongly) Hamiltonian action of Lie group G on (M, P), with $f : \mathfrak{g} \to \mathbb{C}^{\infty}(M)$ describing the classical moment map (i.e. $X^{*M}u = \{f_X, u\}$),

• a star product is said to be covariant under G if

$$\frac{1}{\nu}(f_X \star f_Y - f_Y \star f_X) = f_{[X,Y]} \quad \forall X, Y \in \mathfrak{g}$$

• and is called strongly invariant if it is geometrically invariant and

$$\frac{1}{\nu}(f_X \star u - u \star f_X) = \{f_X, u\} = X^{*M}u \quad \forall X \in \mathfrak{g}, u \in C^{\infty}(M).$$

In that case, f is a quantum moment map.

< ロ > < 同 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 > < 0 >

When \star is invariant under the action of G on (M, P) and the corresponding action of the Lie algebra \mathfrak{g} (given by $D(X) = X^{*M}$) is \star -Hamiltonian, a map $\mathfrak{g} \to C^{\infty}(M)[[\nu]]$ s.t.

$$X^{*M} = \frac{1}{\nu} \operatorname{ad}_{\star} u_X, \qquad \frac{1}{\nu} (u_X \star u_Y - \star u_Y \star u_X) = u_{[X,Y]} \qquad X, Y \in \mathfrak{g}.$$

is called a quantum moment map [Xu].

For a (strongly) Hamiltonian action of Lie group G on (M, P), with $f : \mathfrak{g} \to \mathbb{C}^{\infty}(M)$ describing the classical moment map (i.e. $X^{*M}u = \{f_X, u\}$),

a star product is said to be covariant under G if

$$\frac{1}{\nu}(f_X \star f_Y - f_Y \star f_X) = f_{[X,Y]} \quad \forall X, Y \in \mathfrak{g}$$

and is called strongly invariant if it is geometrically invariant and

$$\frac{1}{\nu}(f_X \star u - u \star f_X) = \{f_X, u\} = X^{*M}u \quad \forall X \in \mathfrak{g}, u \in C^{\infty}(M).$$

In that case, f is a quantum moment map.

イロト 不得 トイヨト イヨト

Any diffeomorphism ϕ of (M, ω) is a symmetry of $\star_{\nabla, \tilde{\Omega}}$ iff it preserves the symplectic 2-form ω , the connection ∇ and the series of closed 2-forms $\tilde{\Omega}$.

X is a derivation of $\star_{\nabla,\tilde{\Omega}}$ iff $\mathcal{L}_X \omega = 0$, $\mathcal{L}_X \tilde{\Omega} = 0$, and $\mathcal{L}_X \nabla = 0$.

X is an inner derivation of $\star_{
abla,\Omega}$ iff $\mathcal{L}_X
abla=0$ and $\exists\lambda_X\in C^\infty(M)[[
u]]$ such that

 $i(X)\omega - i(X)\tilde{\Omega} = d\lambda_X.$

In this case $X(u) = \frac{1}{\nu} (\operatorname{ad}_{\star} \lambda_X)(u)$ [G. -Rawnsley, Bahns-Neumaier, Kravchenko].

A g-invariant Fedosov star product for (M, ω) is obtained from a g invariant connexion and a g invariant series of closed 2-forms Ω . It admits a quantum moment map if and only if there is a linear map $J : g \to C^{\infty}(M)[[\nu]]$ such that

$$dJ(X) = \iota(X^{*M})\omega - \iota(X^{*M})\tilde{\Omega} \qquad \forall X \in \mathfrak{g}.$$

(then have $X^{*M}u = \frac{1}{\nu} \operatorname{ad}_{\star} J(X)u$), and so that

$$J([X,Y]) = -\omega(X^{*M},Y^{*M}) + \Omega(X^{*M},Y^{*M}) \qquad orall X,Y \in \mathfrak{g}.$$

Any symplectic manifold (M, ω) equipped with a g-strongly hamiltonian action with moment map J and a g-invariant connection, admits strongly invariant station of the strong s

Any diffeomorphism ϕ of (M, ω) is a symmetry of $\star_{\nabla, \tilde{\Omega}}$ iff it preserves the symplectic 2-form ω , the connection ∇ and the series of closed 2-forms $\tilde{\Omega}$.

X is a derivation of $\star_{\nabla,\tilde{\Omega}}$ iff $\mathcal{L}_X \omega = 0$, $\mathcal{L}_X \tilde{\Omega} = 0$, and $\mathcal{L}_X \nabla = 0$.

X is an inner derivation of $\star_{\nabla,\Omega}$ iff $\mathcal{L}_X \nabla = 0$ and $\exists \lambda_X \in C^\infty(M)[[\nu]]$ such that

$$i(X)\omega - i(X)\tilde{\Omega} = d\lambda_X.$$

In this case $X(u) = \frac{1}{\nu} (\operatorname{ad}_{\star} \lambda_X)(u)$ [G. -Rawnsley, Bahns-Neumaier, Kravchenko].

A g -invariant Fedosov star product for (M, ω) is obtained from a g invariant connexion and a g invariant series of closed 2-forms Ω . It admits a quantum moment map if and only if there is a linear map $J : g \to C^{\infty}(M)[[\nu]]$ such that

$$dJ(X) = \iota(X^{*M})\omega - \iota(X^{*M})\tilde{\Omega} \qquad \forall X \in \mathfrak{g}.$$

(then have $X^{*M}u = \frac{1}{\nu} \operatorname{ad}_{\star} J(X)u$), and so that

$$J([X,Y]) = -\omega(X^{*M},Y^{*M}) + \Omega(X^{*M},Y^{*M}) \qquad orall X,Y \in \mathfrak{g}.$$

Any symplectic manifold (M, ω) equipped with a g-strongly hamiltonian action with moment map J and a g-invariant connection, admits strongly invariant station of $\mathfrak{g}_{\mathfrak{g}}$ and $\mathfrak{g}_{\mathfrak{g}$ and $\mathfrak{g}_{\mathfrak{g}}$ and \mathfrak{g} and \mathfrak{g} and \mathfrak{g} and \mathfrak{g} and \mathfrak{g} and \mathfrak{g}

Any diffeomorphism ϕ of (M, ω) is a symmetry of $\star_{\nabla, \tilde{\Omega}}$ iff it preserves the symplectic 2-form ω , the connection ∇ and the series of closed 2-forms $\tilde{\Omega}$.

X is a derivation of $\star_{\nabla,\tilde{\Omega}}$ iff $\mathcal{L}_X \omega = 0$, $\mathcal{L}_X \tilde{\Omega} = 0$, and $\mathcal{L}_X \nabla = 0$.

X is an inner derivation of $\star_{\nabla,\Omega}$ iff $\mathcal{L}_X \nabla = 0$ and $\exists \lambda_X \in C^\infty(M)[[\nu]]$ such that

$$i(X)\omega - i(X)\tilde{\Omega} = d\lambda_X.$$

In this case $X(u) = \frac{1}{\nu} (ad_{\star} \lambda_X)(u)$ [G. -Rawnsley, Bahns-Neumaier, Kravchenko].

A g-invariant Fedosov star product for (M, ω) is obtained from a g invariant connexion and a g invariant series of closed 2-forms Ω . It admits a quantum moment map if and only if there is a linear map $J : \mathfrak{g} \to C^{\infty}(M)[[\nu]]$ such that

$$dJ(X) = \iota(X^{*M})\omega - \iota(X^{*M})\tilde{\Omega} \qquad \forall X \in \mathfrak{g}.$$

(then have $X^{*M}u = \frac{1}{\nu} \operatorname{ad}_{\star} J(X)u$), and so that

$$J([X,Y]) = -\omega(X^{*M},Y^{*M}) + \Omega(X^{*M},Y^{*M}) \qquad \forall X,Y \in \mathfrak{g}.$$

Any symplectic manifold (M, ω) equipped with a g-strongly hamiltonian action with moment map J and a g-invariant connection, admits strongly invariant stat products $z \to z \to z$

Any diffeomorphism ϕ of (M, ω) is a symmetry of $\star_{\nabla, \tilde{\Omega}}$ iff it preserves the symplectic 2-form ω , the connection ∇ and the series of closed 2-forms $\tilde{\Omega}$.

X is a derivation of $\star_{\nabla,\tilde{\Omega}}$ iff $\mathcal{L}_X \omega = 0$, $\mathcal{L}_X \tilde{\Omega} = 0$, and $\mathcal{L}_X \nabla = 0$.

X is an inner derivation of $\star_{\nabla,\Omega}$ iff $\mathcal{L}_X \nabla = 0$ and $\exists \lambda_X \in C^\infty(M)[[\nu]]$ such that

$$i(X)\omega - i(X)\tilde{\Omega} = d\lambda_X.$$

In this case $X(u) = \frac{1}{\nu} (ad_{\star} \lambda_X)(u)$ [G. -Rawnsley, Bahns-Neumaier, Kravchenko].

A g-invariant Fedosov star product for (M, ω) is obtained from a g invariant connexion and a g invariant series of closed 2-forms Ω . It admits a quantum moment map if and only if there is a linear map $J : \mathfrak{g} \to C^{\infty}(M)[[\nu]]$ such that

$$dJ(X) = \iota(X^{*M})\omega - \iota(X^{*M})\tilde{\Omega} \qquad \forall X \in \mathfrak{g}.$$

(then have $X^{*M}u = \frac{1}{\nu} \operatorname{ad}_{\star} J(X)u$), and so that

$$J([X,Y]) = -\omega(X^{*M},Y^{*M}) + \Omega(X^{*M},Y^{*M}) \qquad \forall X,Y \in \mathfrak{g}.$$

Any symplectic manifold (M, ω) equipped with a g-strongly hamiltonian action with moment map J and a g-invariant connection, admits strongly invariant star products, $\Xi \rightarrow A \equiv A = A$

If one considers a pair (\star, J) of an g-invariant star-product and a quantum moment map, there is a natural notion of equivalence : two such pairs (\star, J) and (\star', J') , are "equivariantly" equivalent if there is a g-invariant equivalence T between \star and \star' such that J' = TJ.

On any symplectic manifold (M, ω) equipped with a g-strongly hamiltonian action with moment map J and a g-invariant connection, the "equivariant" equivalence classes of such pairs are parametrized by series of second equivariant cohomology classes $\left(\frac{|\omega-J|}{\nu} + H_g^2(M)[[\nu]]\right)$ [Reichert-Waldmann, 2017].

Let *M* be a manifold, g be a Lia algebra and $\rho : g \to \chi(M)$ a Lie algebra action of g on *M*. The complex of g-equivariant forms $\Omega_g(M)$ is defined as

$$\Omega_{\mathfrak{g}}(M) := \left(\oplus_{2i+j=k} [S^{i}(\mathfrak{g}^{*}) \otimes \Omega^{j}(M)]^{\mathfrak{g}} , \ , d_{\mathfrak{g}} := d + \iota_{\bullet} \right)$$

where invariants are taken with respect to $X \cdot (p \otimes \alpha) = (\operatorname{ad}_X^* p \otimes \alpha + p \otimes (\mathcal{L}_{\rho(X)}\alpha))$ and where ι_{\bullet} denotes the insertion of a vector field in the first component of the differential form part : $(\iota_{\bullet}(p \otimes \alpha))(X) = \iota(\rho(X))((p \otimes \alpha)(X))$ when $p \otimes \alpha$ is viewed as a polynomial on \mathfrak{g} with values in the space $\Omega(M)$

イロト イ理ト イヨト イヨト

If one considers a pair (\star, J) of an g-invariant star-product and a quantum moment map, there is a natural notion of equivalence : two such pairs (\star, J) and (\star', J') , are "equivariantly" equivalent if there is a g-invariant equivalence T between \star and \star' such that J' = TJ.

On any symplectic manifold (M, ω) equipped with a g-strongly hamiltonian action with moment map J and a g-invariant connection, the "equivariant" equivalence classes of such pairs are parametrized by series of second equivariant cohomology classes $\left(\frac{|\omega-J|}{\nu} + H_g^2(M)[[\nu]]\right)$ [Reichert-Waldmann, 2017].

Let M be a manifold, \mathfrak{g} be a Lia algebra and $\rho : \mathfrak{g} \to \chi(M)$ a Lie algebra action of \mathfrak{g} on M. The complex of \mathfrak{g} -equivariant forms $\Omega_{\mathfrak{g}}(M)$ is defined as

$$\Omega_{\mathfrak{g}}(M) := \left(\oplus_{2i+j=k} [S^{i}(\mathfrak{g}^{*}) \otimes \Omega^{j}(M)]^{\mathfrak{g}} , \ , d_{\mathfrak{g}} := d + \iota_{\bullet} \right)$$

where invariants are taken with respect to $X \cdot (p \otimes \alpha) = (ad_X^* p \otimes \alpha + p \otimes (\mathcal{L}_{\rho(X)}\alpha))$ and where ι_{\bullet} denotes the insertion of a vector field in the first component of the differential form part : $(\iota_{\bullet}(p \otimes \alpha))(X) = \iota(\rho(X))((p \otimes \alpha)(X))$ when $p \otimes \alpha$ is viewed as a polynomial on \mathfrak{g} with values in the space $\Omega(M)$.

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

Derivations of a Kontsevich star product \star_P

Given a Poisson structure P and a vector field X so that $\mathcal{L}_X P = 0$, then

$$A_X = X + \sum_{k\geq 1} \nu^k F_{k+1}(X, P, \cdots, P)$$

is automatically a derivation of the *-product $*_P = \mu + \sum_{k\geq 1} \nu^k F(X, P, \dots, P)$. If X, Y are two vector fileds M preserving P then

$$[A_X, A_Y] = A_{[X, Y]} + \sum_{k \ge 1} \nu^k F_{k+2}(X, Y, P, \cdots, P).$$

Esposito, de Kleijn and Schnitzer have recently proven an equivariant version of formality of multidifferential operators for a proper Lie group action; this allows to obtain a quantum moment map from a classical moment map with respect to a *G*-invariant Poisson structure and generalizes the theorem cited above from the symplectic setting to the Poisson setting.

イロト イヨト イヨト ・

Derivations of a Kontsevich star product \star_P

Given a Poisson structure P and a vector field X so that $\mathcal{L}_X P = 0$, then

$$A_X = X + \sum_{k\geq 1} \nu^k F_{k+1}(X, P, \cdots, P)$$

is automatically a derivation of the *-product $*_P = \mu + \sum_{k \ge 1} \nu^k F(X, P, \dots, P)$. If X, Y are two vector fileds M preserving P then

$$[A_X, A_Y] = A_{[X, Y]} + \sum_{k \ge 1} \nu^k F_{k+2}(X, Y, P, \cdots, P).$$

Esposito, de Kleijn and Schnitzer have recently proven an equivariant version of formality of multidifferential operators for a proper Lie group action; this allows to obtain a quantum moment map from a classical moment map with respect to a *G*-invariant Poisson structure and generalizes the theorem cited above from the symplectic setting to the Poisson setting.

イロト 不得 トイヨト イヨト 二日



A natural class of symplectic manifolds on which there is a strongly hamiltonian action of a Lie group is the class of coadjoint orbits in Lie groups in the dual of their algebras.

Their interest comes from the Kirillov-Souriau-Kostant orbit method in representation theory which associates certains irreducible unitary representations of a given Lie group to some of its coadjoint orbits.

Much work has been devoted to the construction of interesting star-products on these orbits. Remark that those orbits do not always possess an invariant connection so one can not hope to get in all cases an invariant star-product!

