

A CLASS OF OPTIMAL TESTS FOR SYMMETRY BASED ON LOCAL EDGEWORTH APPROXIMATIONS

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Abstract

The objective of this paper is to provide, for the problem of univariate symmetry (with respect to specified or unspecified location), a concept of optimality, and to construct tests achieving such optimality. This requires embedding symmetry into adequate families of asymmetric (local) alternatives. We construct such families by considering non-Gaussian generalizations of classical first-order Edgeworth expansions indexed by a measure of skewness such that (i) location, scale and skewness play well-separated roles (diagonality of the corresponding information matrices), and (ii) the classical tests based on the Pearson-Fisher coefficient of skewness are optimal in the vicinity of Gaussian densities.

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1 Introduction.

1.1 Testing for symmetry.

Symmetry is one of the most important and fundamental structural assumptions in statistics, playing a major role, for instance, in the identifiability of location or intercept under nonparametric conditions: see Stein (1956), Beran (1974) and Stone (1975). This importance explains the huge variety of existing testing procedures of the null hypothesis of symmetry in an i.i.d. sample X_1, \dots, X_n ; see Hollander (1988) for a survey.

Classical tests of the null hypothesis of symmetry—the hypothesis under which $X_1 - \theta \stackrel{d}{=} -(X_1 - \theta)$ for some location $\theta \in \mathbb{R}$, where $\stackrel{d}{=}$ stands for equality in distribution—are based on third-order moments. Let $m_k^{(n)}(\theta) := n^{-1} \sum_{i=1}^n (X_i - \theta)^k$ and $m_k^{(n)} := m_k^{(n)}(\bar{X}^{(n)})$, where $\bar{X}^{(n)} := n^{-1} \sum_{i=1}^n X_i$. When the location θ is specified, the test statistic is

$$S_1^{(n)} := n^{1/2} m_3^{(n)}(\theta) / (m_6^{(n)}(\theta))^{1/2}, \quad (1.1)$$

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the null distribution of which, under finite sixth-order moments, is asymptotically standard normal. When θ is unspecified, the classical test is based on the empirical coefficient of skewness $b_1^{(n)} := m_3^{(n)}/s_n^3$, where $s_n := (m_2^{(n)})^{1/2}$ stands for the empirical standard error in a sample of size n . More precisely, this test relies on the asymptotic standard normal distribution (still under finite moments of order six) of

$$S_2^{(n)} := n^{1/2}m_3^{(n)}/(m_6^{(n)} - 6s_n^2m_4^{(n)} + 9s_n^6)^{1/2} \quad (1.2)$$

which, under Gaussian densities, asymptotically reduces to $\sqrt{n/6} b_1^{(n)}$. These two tests are generally considered as Gaussian procedures, although they do not require any Gaussian assumptions, and despite the fact that none of them can be considered optimal in any Gaussian sense, since asymmetric alternatives clearly cannot belong to a Gaussian universe. Despite the long history of the problem, the optimality features of those classical procedures thus are all but clear, and optimality issues, in that fundamental problem, remain essentially unexplored.

The main objective of this paper is to provide this classical testing problem with a concept of optimality that coincides with practitioners' intuition (that is, justifying $b_1^{(n)}$ -based Gaussian practice), and to construct tests achieving such optimality. This requires embedding the null hypothesis of symmetry into adequate families of asymmetric alternatives. We therefore define local (in the Le Cam sense) alternatives indexed by location, scale, and a measure of skewness, in such a way that

- (i) location, scale, and skewness play well separated roles (diagonality of the corresponding information matrices), and
- (ii) the traditional tests based on $b_1^{(n)}$ (more precisely, based on $S_2^{(n)}$ given in (1.2)) become locally and asymptotically optimal in the vicinity of Gaussian densities.

As we shall see, part (ii) of this objective is achieved by considering local first-order Edgeworth approximations of the form

$$\phi(x - \theta) + n^{-1/2}\xi(x - \theta)\phi(x - \theta)((x - \theta)^2 - \kappa), \quad (1.3)$$

where ϕ as usual stands for the standard normal density, $\kappa(=3)$ is the Gaussian kurtosis coefficient, θ is a location parameter, and ξ is a measure of skewness. Adequate modifications of (1.3), playing similar roles in the vicinity of non-Gaussian standardized symmetric reference densities f_1 , are proposed in (2.1).

The resulting tests of symmetry (for specified as well as for unspecified location θ) are valid under a broad class of symmetric densities, and parametrically efficient at the reference (standardized) density f_1 . Of particular interest are the pseudo-Gaussian tests (associated with a Gaussian reference density), which appear to be closely related with the test based on $b_1^{(n)}$, and the Laplace tests (associated with a double-exponential reference density).

These tests are of a parametric nature. Since the null hypothesis of symmetry enjoys a rich group invariance structure, classical maximal invariance arguments naturally bring *signs* and *signed-ranks* into the picture. Such nonparametric approach is adopted in a companion paper (Cassart et al. 2009), where we construct signed-rank versions of the parametrically efficient tests proposed here. These signed-rank tests are distribution-free (asymptotically so in case of an unspecified location θ) under the null hypothesis of symmetry, and therefore remain valid under milder distributional assumptions (for the specified location case, they are valid in the absence of *any* distributional assumption).

1.2 Outline of the paper.

The problem we are considering throughout is that of testing the null hypothesis of symmetry. In the notation of Section 1.1, ξ (see (2.1) for a more precise definition) is thus the parameter of interest, the location θ and the standardized null symmetric density f_1 either are specified or play the role of nuisance parameters, whereas the scale σ (not necessarily a standard error) always is a nuisance.

The paper is organized as follows. In Section 2.1 we describe the Edgeworth-type families of local alternatives, extending (1.3), we are considering. Section 2.2 establishes the local and asymptotic normality (with respect to location, scale, and the asymmetry parameters) result that provides the main theoretical tool of the paper. The classical Le Cam theory then allows (Section 3.1) for developing asymptotically optimal procedures for testing symmetry ($\xi = 0$), with specified or unspecified location θ but specified standardized symmetric density f_1 . The more realistic case of an unspecified f_1 is treated in Section 3.2, where we obtain versions of the optimal (at given f_1) tests that remain valid under $g_1 \neq f_1$, for specified (Section 3.2.1) and unspecified (Section 3.2.2) location θ , respectively. The particular case of pseudo-Gaussian procedures (optimal for Gaussian f_1 but valid under any symmetric density with finite moments of order six) is studied in detail in Section 3.3 and their relation with classical tests of symmetry is discussed. We also show that the Laplace tests (optimal for double-exponential f_1 but valid under any symmetric density with finite fourth-order moment) are closely related to the Fechner-type tests derived in Cassart et al. (2008). The finite-sample performances of these tests are investigated via simulations in Section 4, where they are applied to the classical skew-normal and skew- t densities.

2 A class of locally asymptotically normal families of asymmetric distributions.

2.1 Families of asymmetric densities based on Edgeworth approximations.

Denote by $\mathbf{X}^{(n)} := (X_1^{(n)}, \dots, X_n^{(n)})$, $n \in \mathbb{N}$ an i.i.d. n -tuple of observations with common density f . The null hypotheses we are interested in are

- (a) the hypothesis $\mathcal{H}_\theta^{(n)}$ of symmetry with respect to specified location $\theta \in \mathbb{R}$: under $\mathcal{H}_\theta^{(n)}$, the X_i 's have density function $x \mapsto f(x) := \sigma^{-1} f_1((x - \theta)/\sigma)$ (all densities are over the real line, with respect to the Lebesgue measure), for some unspecified $\sigma \in \mathbb{R}_0^+$, where f_1 belongs to the class of standardized symmetric densities

$$\mathcal{F}_0 := \left\{ f_1 : f_1(-z) = f_1(z) \text{ and } \int_{-\infty}^1 f_1(z) dz = 0.75 \right\}.$$

The scale parameter σ (associated with the symmetric density f) we are considering here thus is not the standard error, but the median of the absolute deviations $|X_i - \theta|$; this avoids making any moment assumptions;

- (b) the hypothesis $\mathcal{H}^{(n)} := \bigcup_{\theta \in \mathbb{R}} \mathcal{H}_\theta^{(n)}$ of symmetry with respect to unspecified location.

As explained in the introduction, efficient testing requires the definition of families of asymmetric alternatives exhibiting some adequate structure, such as local asymptotic normality, at the null. For a selected class of densities f enjoying the required regularity assumptions, we

therefore are embedding the null hypothesis of symmetry into families of distributions indexed by $\theta \in \mathbb{R}$ (location), $\sigma \in \mathbb{R}_0^+$ (scale), and a parameter $\xi \in \mathbb{R}$ characterizing asymmetry. More precisely, consider the class \mathcal{F}_1 of densities f_1 satisfying

- (i) (symmetry and standardization) $f_1 \in \mathcal{F}_0$;
- (ii) (absolute continuity) there exists \dot{f}_1 such that, for all $z_1 < z_2$, $f_1(z_2) - f_1(z_1) = \int_{z_1}^{z_2} \dot{f}_1(z) dz$;
- (iii) (strong unimodality) $z \mapsto \phi_{f_1}(z) := -\dot{f}_1(z)/f_1(z)$ is monotone increasing, and
- (iv) (finite Fisher information) $\mathcal{K}(f_1) := \int_{-\infty}^{+\infty} z^4 \phi_{f_1}^2(z) f_1(z) dz$, hence also, under strong unimodality, $\mathcal{I}(f_1) := \int_{-\infty}^{+\infty} \phi_{f_1}^2(z) f_1(z) dz$ and $\mathcal{J}(f_1) := \int_{-\infty}^{+\infty} z^2 \phi_{f_1}^2(z) f_1(z) dz$, are finite;
- (v) there exists $\beta > 0$ such that $\int_a^\infty f_1(z) dz = O(a^{-\beta})$ as $a \rightarrow \infty$ and $\phi_{f_1}(z) = o(z^{\beta/2-2})$ as $z \rightarrow \infty$.

That class \mathcal{F}_1 thus consists of all symmetric standardized densities f_1 that are absolutely continuous, strongly unimodal (that is, log-concave), and have finite information $\mathcal{I}(f_1)$ and $\mathcal{J}(f_1)$ for location and scale, and, as we shall see, $\mathcal{K}(f_1)$ for asymmetry, with tails satisfying (v).

For all $f_1 \in \mathcal{F}_1$, denote by $\kappa(f_1) := \mathcal{J}(f_1)/\mathcal{I}(f_1)$ the ratio of information for scale and information for location; $\kappa(f_1)$, as we shall see, for Gaussian density ($f_1 = \phi_1$) reduces to kurtosis ($\kappa(\phi_1) = 3$), and can be interpreted as a *generalized kurtosis coefficient*. Finally, write $P_{\theta, \sigma, \xi, f_1}^{(n)}$ for the probability distribution of $\mathbf{X}^{(n)}$ when the X_i 's are i.i.d. with density

$$f(x) = \sigma^{-1} f_1\left(\frac{x-\theta}{\sigma}\right) - \xi \sigma^{-1} \dot{f}_1\left(\frac{x-\theta}{\sigma}\right) \left(\left(\frac{x-\theta}{\sigma}\right)^2 - \kappa(f_1) \right) I[|x-\theta| \leq \sigma|z^*|] \quad (2.1)$$

$$- \text{sign}(\xi) \sigma^{-1} \dot{f}_1\left(\frac{x-\theta}{\sigma}\right) \{ I[x-\theta > \text{sign}(-\xi)\sigma|z^*|] - I[x-\theta < \text{sign}(\xi)\sigma|z^*|] \}.$$

Here $\theta \in \mathbb{R}$ and $\sigma \in \mathbb{R}^+$ clearly are location and scale parameters, $\xi \in \mathbb{R}$ is a measure of skewness, $\kappa(f_1)$ (strictly positive for $f_1 \in \mathcal{F}_1$) the generalized kurtosis coefficient just defined, and z^* the unique (for ξ small enough; unicity follows from the monotonicity of ϕ_{f_1}) solution of $f_1(z^*) = \xi \dot{f}_1(z^*)((z^*)^2 - \kappa(f_1))$. The function f defined in (2.1) is indeed a probability density (nonnegative, integrating up to one), since it is obtained by adding and subtracting the same probability mass

$$\frac{|\xi|}{\sigma} \int_\theta^\infty \min \left(\dot{f}_1\left(\frac{x-\theta}{\sigma}\right) \left(\left(\frac{x-\theta}{\sigma}\right)^2 - \kappa(f_1) \right), f_1\left(\frac{x-\theta}{\sigma}\right) \right) dx$$

on both sides of θ (according to the sign of ξ). Note that $\xi > 0$ implies $f(x) = 0$ for $x-\theta < -\sigma|z^*|$ and $f(x) = 2\sigma^{-1} f_1((x-\theta)/\sigma)$ for $x-\theta > \sigma|z^*|$. Moreover, $x \mapsto f(x)$ is continuous whenever $\dot{f}_1(x)$ is, vanishes for $x \leq \theta + \sigma z^*$ if $\xi > 0$, for $x \geq \theta + \sigma z^*$ if $\xi < 0$, and is left- or right-skewed according as $\xi < 0$ or $\xi > 0$. As for z^* , it tends to $-\infty$ as $\xi \downarrow 0$, to ∞ as $\xi \uparrow 0$; in the Gaussian case, it is easy to check that $|z^*| = O(|\xi|^{-1/3})$ as $\xi \rightarrow 0$.

The intuition behind this class of alternatives is that, in the Gaussian case, (2.1), with $\xi = n^{-1/2}\tau$ yields (for $x \in [\theta \pm \sigma z^*]$) the first-order Edgeworth development of the density of

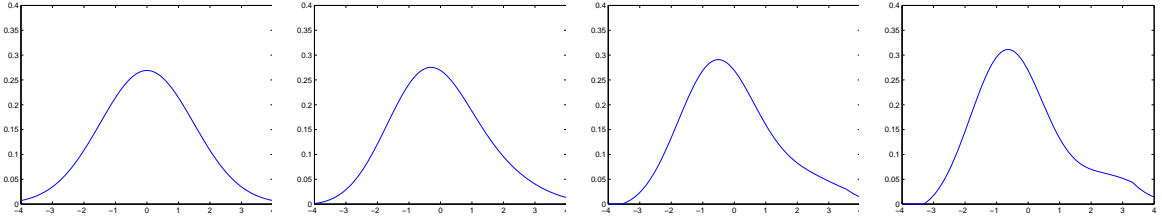


Figure 1: Graphical representation of the Gaussian Edgeworth family (2.1) ($f_1 = \phi_1$), for $\xi = 0, 0.05, 0.10$, and 0.15 .

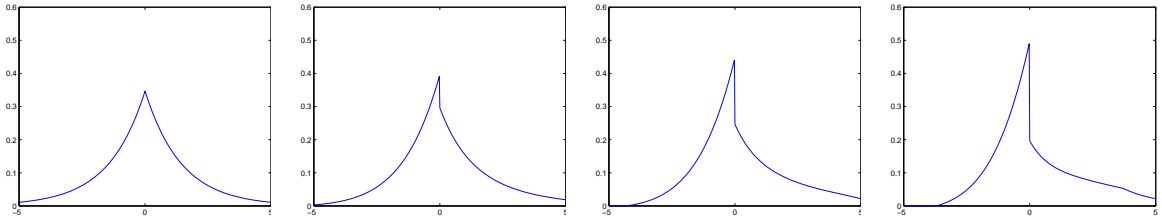


Figure 2: Graphical representation of the double-exponential Edgeworth family (2.1) ($f_1 = f_{\mathcal{L}}$), for $\xi = 0, 0.05, 0.10$, and 0.15 .

the standardized mean of an i.i.d. n -tuple of variables with third-order moment $6\tau\sigma^3$ (where standardization is based on the median σ of absolute deviations from θ). For a “local” value of ξ , of the form $n^{-1/2}\tau$, (2.1) thus describes the type of deviation from symmetry that corresponds to the classical central-limit context. Hence, if a Gaussian density is justified as resulting from the additive combination of a large number of small independent symmetric variables, the locally asymmetric f results from the same additive combination, of independent, but slightly skew observations. As we shall see, the locally optimal test in such case is the traditional test based on $b_1^{(n)}$.

Besides the Gaussian one (with standardized density $\phi_1(z) := \sqrt{a/2\pi} \exp(-az^2/2)$), interesting special cases of (2.1) are obtained in the vicinity of

- (i) the double-exponential distributions, with standardized density

$$f_1(z) = f_{\mathcal{L}}(z) := (1/2d) \exp(-|z|/d),$$

$$\mathcal{I}(f_1) = 1/d^2, \mathcal{J}(f_1) = 2, \text{ and } \mathcal{K}(f_1) = 24d^2.$$

- (ii) the logistic distributions, with standardized density

$$f_1(z) = f_{Log}(z) := \sqrt{b} \exp(-\sqrt{b}z) / (1 + \exp(-\sqrt{b}z))^2,$$

$$\mathcal{I}(f_1) = b/3, \mathcal{J}(f_1) = (12 + \pi^2)/9, \text{ and } \mathcal{K}(f_1) = \pi^2(120 + 7\pi^2)/45b;$$

- (iii) the power-exponential distributions, with standardized densities

$$f_1(z) = f_{\exp_\eta}(z) := C_{\exp_\eta} \exp(-(g_\eta z)^{2\eta}),$$

$$\eta \in \mathbb{N}_0, \mathcal{I}(f_1) = 2g_\eta^2\eta\Gamma(2 - 1/2\eta)/\Gamma(1 + 1/2\eta), \mathcal{J}(f_1) = 1 + 2\eta, \text{ and } \mathcal{K}(f_1) = 2g_\eta\eta/\Gamma(1 + 1/2\eta)$$

(the positive constants $C_{\text{exp},\eta}$, a , b , d , and g_η are such that $f_1 \in \mathcal{F}_1$).

Although not strongly unimodal, the Student distributions with $\nu > 2$ degrees of freedom also can be considered here (strong unimodality indeed is essentially used as a sufficient condition for the existence of z^* in (2.1)—an existence that can be checked directly here). Standardized Student densities take the form

$$f_1(z) = f_{t_\nu}(z) := C_{t_\nu}(1 + a_\nu z^2/\nu)^{-(\nu+1)/2},$$

with $\mathcal{I}(f_1) = a_\nu(\nu + 1)/(\nu + 3)$, $\mathcal{J}(f_1) = 3(\nu + 1)/(\nu + 3)$, and $\mathcal{K}(f_1) = 15\nu(\nu + 1)/a_\nu(\nu - 2)(\nu + 3)$ (C_{t_ν} and a_ν are normalizing constants). Note that the corresponding Gaussian values, namely $\mathcal{I}(\phi_1) = a = 0.4549$, $\mathcal{J}(\phi_1) = 3$ and $\mathcal{K}(\phi_1) = 15/a$, are obtained by taking limits as $\nu \rightarrow \infty$.

Figures 1 and 2 provide graphical representations of some densities in the Gaussian ($f_1 = \phi_1$) and double-exponential ($f_1 = f_{\mathcal{L}}$) Edgeworth families (2.1), respectively. In the Gaussian case, the skewed densities are continuous, while the double-exponential ones, due to the discontinuity of $f_{\mathcal{L}}(x)$ at $x = 0$, exhibit a discontinuity at the origin.

2.2 Uniform local asymptotic normality (ULAN).

The main technical tool in our derivation of optimal tests is the uniform local asymptotic normality (ULAN), with respect to $\boldsymbol{\vartheta} := (\theta, \sigma, \xi)'$, at $(\theta, \sigma, 0)'$, of the parametric families

$$\mathcal{P}_{f_1}^{(n)} := \bigcup_{\sigma > 0} \mathcal{P}_{\sigma; f_1}^{(n)} := \bigcup_{\sigma > 0} \left\{ \mathbb{P}_{\theta, \sigma, \xi; f_1}^{(n)} \mid \theta \in \mathbb{R}, \xi \in \mathbb{R} \right\}, \quad (2.2)$$

where $f_1 \in \mathcal{F}_1$. More precisely, the following result (see the appendix for proof) holds.

Proposition 2.1 (ULAN) *For any $f_1 \in \mathcal{F}_1$, $\theta \in \mathbb{R}$, and $\sigma \in \mathbb{R}_0^+$, the family $\mathcal{P}_{f_1}^{(n)}$ is ULAN at $(\theta, \sigma, 0)'$, with (writing Z_i for $Z_i^{(n)}(\theta, \sigma) := \sigma^{-1}(X_i^{(n)} - \theta)$ and ϕ_{f_1} for $-\dot{f}_1/f_1$) central sequence*

$$\Delta_{f_1}^{(n)}(\boldsymbol{\vartheta}) := \begin{pmatrix} \Delta_{f_1;1}^{(n)}(\boldsymbol{\vartheta}) \\ \Delta_{f_1;2}^{(n)}(\boldsymbol{\vartheta}) \\ \Delta_{f_1;3}^{(n)}(\boldsymbol{\vartheta}) \end{pmatrix} = n^{-1/2} \sum_{i=1}^n \begin{pmatrix} \sigma^{-1} \phi_{f_1}(Z_i) \\ \sigma^{-1} (\phi_{f_1}(Z_i) Z_i - 1) \\ \phi_{f_1}(Z_i) (Z_i^2 - \kappa(f_1)) \end{pmatrix} \quad (2.3)$$

and full-rank information matrix

$$\mathbf{\Gamma}_{f_1}(\boldsymbol{\vartheta}) = \begin{pmatrix} \sigma^{-2} \mathcal{I}(f_1) & 0 & 0 \\ 0 & \sigma^{-2} (\mathcal{J}(f_1) - 1) & 0 \\ 0 & 0 & \gamma(f_1) \end{pmatrix} \quad (2.4)$$

where $\gamma(f_1) := \mathcal{K}(f_1) - \mathcal{J}^2(f_1)/\mathcal{I}(f_1)$. More precisely, for any $\boldsymbol{\vartheta}^{(n)} := (\theta^{(n)}, \sigma^{(n)}, 0)'$ such that $\theta^{(n)} - \theta = O(n^{-1/2})$ and $\sigma^{(n)} - \sigma = O(n^{-1/2})$, and for any bounded sequence $\boldsymbol{\tau}^{(n)} = (t^{(n)}, s^{(n)}, \tau^{(n)})' \in \mathbb{R}^3$, we have, under $\mathbb{P}_{\boldsymbol{\vartheta}^{(n)}; f_1}^{(n)}$, as $n \rightarrow \infty$,

$$\begin{aligned} \Lambda_{\boldsymbol{\vartheta}^{(n)} + n^{-1/2} \boldsymbol{\tau}^{(n)}; f_1}^{(n)} &:= \log \left(\frac{d\mathbb{P}_{\boldsymbol{\vartheta}^{(n)} + n^{-1/2} \boldsymbol{\tau}^{(n)}; f_1}^{(n)}}{d\mathbb{P}_{\boldsymbol{\vartheta}^{(n)}; f_1}^{(n)}} \right) \\ &= \boldsymbol{\tau}^{(n)'} \Delta_{f_1}^{(n)}(\boldsymbol{\vartheta}^{(n)}) - \frac{1}{2} \boldsymbol{\tau}^{(n)'} \mathbf{\Gamma}_{f_1}(\boldsymbol{\vartheta}) \boldsymbol{\tau}^{(n)} + o_{\mathbb{P}}(1), \end{aligned}$$

and

$$\Delta_{f_1}^{(n)}(\boldsymbol{\vartheta}^{(n)}) \xrightarrow{\mathcal{L}} \mathcal{N}(\mathbf{0}, \mathbf{\Gamma}_{f_1}(\boldsymbol{\vartheta})).$$

The diagonal form of the information matrix $\mathbf{\Gamma}_{f_1}(\boldsymbol{\vartheta})$ confirms that location, scale, and skewness, in the parametric family (2.2), play distinct and well separated roles. Note that orthogonality between the scale and skewness components of $\Delta_{f_1}^{(n)}(\boldsymbol{\vartheta})$ automatically follows from the symmetry of f_1 , while for location and skewness, this orthogonality is a consequence of the definition of $\kappa(f_1)$. The Gaussian versions of (2.3) and (2.4) are

$$\Delta_{\phi_1}^{(n)}(\boldsymbol{\vartheta}) = n^{-1/2} \sum_{i=1}^n \begin{pmatrix} a\sigma^{-1}Z_i \\ \sigma^{-1}(aZ_i^2 - 1) \\ aZ_i(Z_i^2 - \frac{3}{a}) \end{pmatrix} \quad \text{and} \quad \mathbf{\Gamma}_{\phi_1}(\boldsymbol{\vartheta}) = \begin{pmatrix} a\sigma^{-2} & 0 & 0 \\ 0 & 2\sigma^{-2} & 0 \\ 0 & 0 & 6/a \end{pmatrix},$$

respectively (recall that $a = 0.4549$).

3 Optimal parametric tests.

3.1 Optimal parametric tests: specified density.

For specified $f_1 \in \mathcal{F}_1$, consider the null hypothesis $\mathcal{H}_{\theta;f_1}^{(n)} := \bigcup_{\sigma \in \mathbb{R}_0^+} \{\mathbf{P}_{\theta,\sigma,0;f_1}^{(n)}\}$ of symmetry with respect to some specified location θ , and the null hypothesis $\mathcal{H}_{f_1}^{(n)} := \bigcup_{\theta \in \mathbb{R}} \bigcup_{\sigma \in \mathbb{R}_0^+} \{\mathbf{P}_{\theta,\sigma,0;f_1}^{(n)}\}$ of symmetry with respect to unspecified θ . ULAN and the diagonal structure of (2.4) imply that substituting discretized root- n consistent estimators $\hat{\theta}$ and $\hat{\sigma}$ for the unknown θ and σ has no influence, asymptotically, on the ξ -part of the central sequence.

Recall that a sequence of estimators $\hat{\lambda}^{(n)}$ defined in a sequence of experiments $\{\mathbf{P}_{\lambda}^{(n)} | \lambda \in \Lambda\}$ indexed by some parameter λ is *root- n consistent* and *asymptotically discrete* if, under $\mathbf{P}_{\lambda}^{(n)}$, as $n \rightarrow \infty$,

$$(C1) \quad \hat{\lambda}^{(n)} - \lambda = O_{\mathbf{P}}(n^{-1/2}), \text{ and}$$

$$(C2) \quad \text{the number of possible values of } \hat{\lambda}^{(n)} \text{ in balls with } O(n^{-1/2}) \text{ radius centered at } \lambda \text{ is bounded as } n \rightarrow \infty.$$

An estimator $\lambda^{(n)}$ satisfying (C1) but not (C2) is easily discretized by letting, for some arbitrary constant $c > 0$, $\lambda_{\#}^{(n)} := (cn^{1/2})^{-1} \text{sign}(\lambda^{(n)}) \lceil cn^{1/2} |\lambda^{(n)}| \rceil$, which satisfies both (C1) and (C2). Subscripts $\#$ in the sequel are used for estimators $(\hat{\theta}_{\#}, \hat{\sigma}_{\#}, \dots)$ satisfying (C1) and (C2). It should be noted, however, that (C2) has no implications in practice, where n is fixed, as the discretization constant c can be chosen arbitrarily large.

It follows from the diagonal form of the information matrix (2.4) that locally uniformly asymptotically most powerful tests of $\mathcal{H}_{\theta;f_1}^{(n)}$ (resp., of $\mathcal{H}_{f_1}^{(n)}$) can be based on $\Delta_{f_1;3}^{(n)}(\theta, \hat{\sigma}_{\#}, 0)$ (resp., on $\Delta_{f_1;3}^{(n)}(\hat{\theta}_{\#}, \hat{\sigma}_{\#}, 0)$), hence on $T_{f_1}^{(n)}(\theta, \hat{\sigma}_{\#})$ (resp., on $T_{f_1}^{(n)}(\hat{\theta}_{\#}, \hat{\sigma}_{\#})$), where

$$T_{f_1}^{(n)}(\theta, \sigma) := \frac{1}{\sqrt{n\gamma(f_1)}} \sum_{i=1}^n \phi_{f_1}(Z_i(\theta, \sigma)) \left(Z_i^2(\theta, \sigma) - \kappa(f_1) \right). \quad (3.5)$$

Root- n consistent (under the null hypothesis of symmetry) estimators of θ and σ that do not require any moment assumptions are, for instance, the medians $\hat{\theta} := \text{Med}(X_i^{(n)})$ and $\hat{\sigma} := \text{Med}(|X_i^{(n)} - \hat{\theta}|)$ of the $X_i^{(n)}$'s and of their absolute deviations from $\hat{\theta}$, respectively.

The following proposition then results from classical results on ULAN families (see, e.g., Chapter 11 of Le Cam 1986).

Proposition 3.1 *Let $f_1 \in \mathcal{F}_1$. Then,*

- (i) $T_{f_1}^{(n)}(\hat{\theta}_\#, \hat{\sigma}_\#) = T_{f_1}^{(n)}(\theta, \sigma) + o_P(1)$ is asymptotically normal, with mean zero under $\mathbb{P}_{\theta, \sigma, 0; f_1}^{(n)}$, mean $\tau\gamma^{1/2}(f_1)$ under $\mathbb{P}_{\theta, \sigma, n^{-1/2}\tau; f_1}^{(n)}$, and variance one under both.
- (ii) The sequence of tests rejecting the null hypothesis of symmetry (with standardized density f_1) whenever $T_{f_1}^{(n)}(\theta, \hat{\sigma}_\#)$ (resp., $T_{f_1}^{(n)}(\hat{\theta}_\#, \hat{\sigma}_\#)$) exceeds the $(1 - \alpha)$ standard normal quantile z_α is locally asymptotically most powerful, at asymptotic level α , for $\mathcal{H}_{\theta; f_1}^{(n)}$ (resp., for $\mathcal{H}_{f_1}^{(n)}$) against $\bigcup_{\xi > 0} \bigcup_{\sigma \in \mathbb{R}_0^+} \{\mathbb{P}_{\theta, \sigma, \xi; f_1}^{(n)}\}$ (resp., $\bigcup_{\xi > 0} \bigcup_{\theta \in \mathbb{R}} \bigcup_{\sigma \in \mathbb{R}_0^+} \{\mathbb{P}_{\theta, \sigma, \xi; f_1}^{(n)}\}$).

It follows that unspecified location θ and scale σ do not induce any loss of efficiency when the standardized density f_1 itself is specified.

The Gaussian version of (3.5) is

$$T_{\phi_1}^{(n)}(\theta, \sigma) := \sqrt{\frac{a^3}{6n}} \sum_{i=1}^n Z_i(\theta, \sigma) \left(Z_i^2(\theta, \sigma) - \frac{3}{a} \right) = \sqrt{\frac{a}{6n}} \sum_{i=1}^n \left(aZ_i^3(\theta, \sigma) - 3Z_i(\theta, \sigma) \right);$$

thanks to the linearity of Gaussian scores, it easily follows from a traditional Slutsky argument that $\hat{\theta}$ and $\hat{\sigma}$ in $T_{\phi_1}^{(n)}(\hat{\theta}, \hat{\sigma})$ need not be discretized. Under Gaussian densities, both $T_{\phi_1}^{(n)}(\hat{\theta}, \hat{\sigma})$ and $T_{\phi_1}^{(n)}(\theta, \hat{\sigma})$ are asymptotically equivalent to $T_{\phi_1}^{(n)}(\bar{X}^{(n)}, \hat{\sigma}) = (na^3/6)^{1/2} m_3^{(n)}/\hat{\sigma}^3 = \sqrt{n/6} b_1^{(n)} + o_P(1)$, that is, to $S_2^{(n)}$ given in (1.2). The latter is thus locally asymptotically optimal under Gaussian assumptions, whether θ is or not, whereas the specified- θ test based on $m_3^{(n)}(\theta)/(m_6^{(n)}(\theta))^{1/2}$ (more precisely, on $S_1^{(n)}$ given in (1.1)) is suboptimal. The fact that $m_3^{(n)}(\hat{\theta})$ yields a better performance than $m_3^{(n)}(\theta)$ under specified location θ (see the comments after Proposition 3.5 for a comparison of local powers) looks puzzling at first sight. The reason is that orthogonality, in the Fisher information sense, between asymmetry and location, is a “built-in” feature of Edgeworth families. Since $m_3^{(n)}(\theta)$ and $S_1^{(n)}$ are sensitive to location shifts, tests based on $S_1^{(n)}$ are “wasting” some power on location alternatives (which are irrelevant when θ is specified), to the detriment of asymmetry alternatives, contrary to $S_2^{(n)}$, which is shift-invariant.

Locally asymptotically maximin two-sided tests are easily derived along the same lines.

3.2 Optimal parametric tests: unspecified density.

The parametric tests based on (3.5) achieve local and asymptotic optimality at correctly specified f_1 , which sets the parametric efficiency bounds for the problem, but has limited practical value, as these tests are not valid anymore under density $g_1 \neq f_1$. If Proposition 3.1 is to be adapted to the more realistic null hypotheses $\mathcal{H}_\theta^{(n)} := \bigcup_{g_1} \mathcal{H}_{\theta; g_1}^{(n)}$ and $\mathcal{H}^{(n)} := \bigcup_{g_1} \mathcal{H}_{g_1}^{(n)}$ under which the (symmetric) density remains unspecified, three problems have to be treated with care under $g_1 \neq f_1$: the centering of $T_{f_1}^{(n)}$ and its scaling under the null, and the impact on the asymptotic distribution of $T_{f_1}^{(n)}$ of the substitution of $\hat{\theta}$ (under $\mathcal{H}^{(n)}$) and $\hat{\sigma}$ (under $\mathcal{H}_\theta^{(n)}$ and $\mathcal{H}^{(n)}$) for θ and σ .

3.2.1 Specified location.

Let us first assume that both θ and σ are specified. Write $\Delta_{f_1; 3}^{(n)}(\kappa)$ for $n^{-1/2} \sum_{i=1}^n \phi_{f_1}(Z_i)(Z_i^2 - \kappa)$,

where $\kappa \in \mathbb{R}_0^+$. Note that $\Delta_{f_1;3}^{(n)}(\kappa)$ remains centered under $\mathbb{P}_{\theta,\sigma,0;g_1}^{(n)}$, irrespective of the choice of κ . Indeed, the functions $z \mapsto \phi_{f_1}(z)z^2$ and $z \mapsto \phi_{f_1}(z)$ are skew-symmetric, and their expectations under any symmetric density are automatically zero—provided that they exist. The variance under $\mathbb{P}_{\theta,\sigma,0;g_1}^{(n)}$ of $\Delta_{f_1;3}^{(n)}(\kappa)$ is then

$$\gamma_{g_1}^\kappa(f_1) := \mathbb{E}_{g_1}[(\phi_{f_1}(Z_i)(Z_i^2 - \kappa))^2] = \mathcal{K}_{g_1}(f_1) - 2\kappa\mathcal{J}_{g_1}(f_1) + \kappa^2\mathcal{I}_{g_1}(f_1),$$

where

$$\mathcal{I}_{g_1}(f_1) := \int_{-\infty}^{\infty} \phi_{f_1}^2(z)g_1(z) dz, \quad \mathcal{J}_{g_1}(f_1) := \int_{-\infty}^{\infty} z^2\phi_{f_1}^2(z)g_1(z) dz$$

and (still, provided that those integrals exist)

$$\mathcal{K}_{g_1}(f_1) := \int_{-\infty}^{+\infty} z^4\phi_{f_1}^2(z)g_1(z) dz.$$

We know from Le Cam's third Lemma that, under $\mathbb{P}_{\theta,\sigma,0;g_1}^{(n)}$, the impact on $\Delta_{f_1;3}^{(n)}(\kappa)$ of an estimated scale depends on the asymptotic joint distribution (still, under $\mathbb{P}_{\theta,\sigma,0;g_1}^{(n)}$) of $\Delta_{f_1;3}^{(n)}(\kappa)$ and $\Delta_{g_1;2}^{(n)}$. Now,

$$\begin{pmatrix} \Delta_{f_1;3}^{(n)}(\kappa) \\ \Delta_{g_1;2}^{(n)}(\theta, \sigma, 0) \end{pmatrix} = n^{-1/2} \sum_{i=1}^n \begin{pmatrix} \phi_{f_1}(Z_i)(Z_i^2 - \kappa) \\ \sigma^{-1}(\phi_{g_1}(Z_i)Z_i - 1) \end{pmatrix} \quad (3.6)$$

is easily shown to be asymptotically normal under $\mathbb{P}_{\theta,\sigma,0;g_1}^{(n)}$, with diagonal covariance matrix, since, as the integral of a skew-symmetric function, $\int_{-\infty}^{\infty} \phi_{f_1}(z)(z^2 - \kappa)(\phi_{g_1}(z)z - 1)g_1(z)dz = 0$. The effect on the asymptotic distribution of $\Delta_{f_1;3}^{(n)}(\kappa)$ of a root- n perturbation of σ thus is asymptotically nil; the asymptotic linearity result of Proposition 6.1 allows for extending this conclusion to the stochastic perturbations induced by substituting a duly discretized root- n consistent estimator $\hat{\sigma}_{\#}^{(n)}$ for σ . Such a substitution consequently does not affect the asymptotic behavior of $\Delta_{f_1;3}^{(n)}(\kappa)$.

For $f_1 \in \mathcal{F}_1$ and $g_1 \in \mathcal{F}_{f_1} := \{g_1 \in \mathcal{F}_1 : \mathcal{K}_{g_1}(f_1) < \infty\}$ (due to strong unimodality, $\mathcal{K}_{g_1}(f_1) < \infty$ also implies $\mathcal{I}_{g_1}(f_1) < \infty$ and $\mathcal{J}_{g_1}(f_1) < \infty$), let

$$\gamma^{(n)}(f_1) = \gamma^{(n)}(f_1, \theta, \sigma) := \mathcal{K}^{(n)}(f_1) - 2\kappa(f_1)\mathcal{J}^{(n)}(f_1) + \kappa^2(f_1)\mathcal{I}^{(n)}(f_1),$$

where

$$\mathcal{I}^{(n)}(f_1) = \mathcal{I}^{(n)}(f_1, \theta, \sigma) := n^{-1} \sum_{i=1}^n \phi_{f_1}^2(Z_i(\theta, \sigma)), \quad (3.7)$$

$$\mathcal{J}^{(n)}(f_1) = \mathcal{J}^{(n)}(f_1, \theta, \sigma) := n^{-1} \sum_{i=1}^n Z_i^2(\theta, \sigma)\phi_{f_1}^2(Z_i(\theta, \sigma)), \quad (3.8)$$

and

$$\mathcal{K}^{(n)}(f_1) = \mathcal{K}^{(n)}(f_1, \theta, \sigma) := n^{-1} \sum_{i=1}^n Z_i^4(\theta, \sigma)\phi_{f_1}^2(Z_i(\theta, \sigma)), \quad (3.9)$$

under $\mathbb{P}_{\theta,\sigma,0;g_1}^{(n)}$ are consistent estimates of $\mathcal{I}_{g_1}(f_1)$, $\mathcal{J}_{g_1}(f_1)$, and $\mathcal{K}_{g_1}(f_1)$, respectively. Now, in practice, $\mathcal{I}^{(n)}(f_1)$, $\mathcal{J}^{(n)}(f_1)$, and $\mathcal{K}^{(n)}(f_1)$, hence $\gamma^{(n)}(f_1)$ cannot be computed from the observations, and $Z_i(\theta, \hat{\sigma}_{\#})$ is to be substituted for $Z_i(\theta, \sigma)$ in (3.7)-(3.9), yielding $\gamma^{(n)}(f_1, \theta, \hat{\sigma}_{\#})$.

This substitution in general requires a slight reinforcement of regularity assumptions. Routine application of Le Cam's third Lemma implies that $\gamma^{(n)}(f_1, \theta, \hat{\sigma}_\#) - \gamma^{(n)}(f_1, \theta, \sigma)$ is $o_P(1)$ under $P_{\theta, \sigma, 0; g_1}^{(n)}$ provided that the asymptotic covariance of $\gamma^{(n)}(f_1, \theta, \sigma)$ and $\Delta_{g_1; 2}^{(n)}$ is finite. A simple computation (and the strong unimodality of f_1 and g_1) shows that a sufficient condition for this is

$$\int_{-\infty}^{\infty} z^5 \phi_{f_1}^2(z) \phi_{g_1}(z) g_1(z) dz < \infty. \quad (3.10)$$

Denote by $\mathcal{F}_{f_1}^*$ the subset of \mathcal{F}_{f_1} for which (3.10) holds. Defining the test statistic

$$\hat{T}_{f_1}^{(n)}(\theta, \sigma) := \frac{1}{\sqrt{n\gamma^{(n)}(f_1, \theta, \sigma)}} \sum_{i=1}^n \phi_{f_1}(Z_i(\theta, \sigma)) \left(Z_i^2(\theta, \sigma) - \kappa(f_1) \right) \quad (3.11)$$

and the cross-information quantities

$$\mathcal{I}_{g_1}(f_1, g_1) := \int_{-\infty}^{+\infty} \phi_{f_1}(z) \phi_{g_1}(z) g_1(z) dz, \quad \mathcal{J}_{g_1}(f_1, g_1) := \int_{-\infty}^{+\infty} z^2 \phi_{f_1}(z) \phi_{g_1}(z) g_1(z) dz,$$

and

$$\mathcal{K}_{g_1}(f_1, g_1) := \int_{-\infty}^{+\infty} z^4 \phi_{f_1}(z) \phi_{g_1}(z) g_1(z) dz$$

(which for $f_1 \in \mathcal{F}_1$ and $g_1 \in \mathcal{F}_{f_1}^*$ are finite because of Cauchy-Schwarz), we have the following result.

Lemma 3.1 *Let $f_1 \in \mathcal{F}_1$ and $g_1 \in \mathcal{F}_{f_1}^*$. Then,*

$$(i) \quad \hat{T}_{f_1}^{(n)}(\theta, \hat{\sigma}_\#) = \hat{T}_{f_1}^{(n)}(\theta, \sigma) + o_P(1) \text{ is asymptotically normal, with mean zero under } P_{\theta, \sigma, 0; g_1}^{(n)},$$

mean

$$\tau \frac{\mathcal{K}_{g_1}(f_1, g_1) - \mathcal{J}_{g_1}(f_1, g_1)(\kappa(f_1) + \kappa(g_1)) + \mathcal{I}_{g_1}(f_1, g_1)\kappa(f_1)\kappa(g_1)}{[\mathcal{K}_{g_1}(f_1) - 2\mathcal{J}_{g_1}(f_1)\kappa(f_1) + \mathcal{I}_{g_1}(f_1)\kappa^2(f_1)]^{1/2}} \quad (3.12)$$

under $P_{\theta, \sigma, n^{-1/2}\tau; g_1}^{(n)}$, and variance one under both.

(ii) *The sequence of tests rejecting the null hypothesis $\mathcal{H}_\theta^{(n)} := \bigcup_{g_1 \in \mathcal{F}_{f_1}^*} \mathcal{H}_{\theta; g_1}^{(n)}$ of symmetry with respect to specified θ whenever $\hat{T}_{f_1}^{(n)}(\theta, \hat{\sigma}_\#)$ exceeds the $(1 - \alpha)$ standard normal quantile z_α is locally uniformly asymptotically most powerful, at asymptotic level α , for $\mathcal{H}_\theta^{(n)}$ against $\bigcup_{\xi > 0} \bigcup_{\sigma \in \mathbb{R}_0^+} \{P_{\theta, \sigma, \xi; f_1}^{(n)}\}$.*

The tests based on $\hat{T}_{f_1}^{(n)}(\theta, \hat{\sigma}_\#)$ enjoy all the validity (under $\mathcal{H}_\theta^{(n)}$) and optimality (against $\bigcup_{\xi > 0} \bigcup_{\sigma \in \mathbb{R}_0^+} \{P_{\theta, \sigma, \xi; f_1}^{(n)}\}$) properties one can expect. However, a closer look reveals that they are quite unsatisfactory on one count: under $g_1 \neq f_1$, their behavior strongly depends on the arbitrary choice of the concept of scale (here, the median of absolute deviations). Consider, for example, the Gaussian version of (3.11) which takes the form (here again, Slutsky's Lemma allows for not discretizing $\hat{\sigma}$)

$$\hat{T}_{\phi_1}^{(n)}(\theta, \sigma) = \frac{1}{\sqrt{n\gamma^{(n)}(\phi_1)}} \sum_{i=1}^n \left(aZ_i^3(\theta, \sigma) - 3Z_i(\theta, \sigma) \right),$$

where

$$\gamma^{(n)}(\phi_1) = \gamma^{(n)}(\phi_1, \theta, \sigma) = a^2 \sigma^{-6} m_6^{(n)}(\theta) - 6a \sigma^{-4} m_4^{(n)}(\theta) + 9 \sigma^{-2} m_2^{(n)}(\theta).$$

The test based on $\hat{T}_{\phi_1}^{(n)}(\theta, \hat{\sigma})$ is a pseudo-Gaussian test, hence optimal under Gaussian assumptions; the asymptotic shift (3.12) is $\tau \sqrt{6/a}$ under $P_{\theta, \sigma, n^{-1/2}\tau; \phi_1}^{(n)}$, and

$$\tau[5a\mu_4(g_1) - (9 + 3a\kappa(g_1))\mu_2(g_1) + 3\kappa(g_1)][a^2\mu_6(g_1) - 6a\mu_4(g_1) + 9\mu_2(g_1)]^{-1/2},$$

where $\mu_k(g_1) := \int_{-\infty}^{\infty} z^k g_1(z) dz$, under $P_{\theta, \sigma, n^{-1/2}\tau; g_1}^{(n)}$. This asymptotic shift strongly depends on a , hence on our (arbitrary) choice of a scale parameter. Setting to one the standard error instead of the median of absolute deviations would significantly modify the local behaviour of $\hat{T}_{f_1}^{(n)}(\theta, \hat{\sigma}_{\#})$ as soon as $g_1 \neq f_1$. This does not affect optimality properties (which hold under f_1), but is highly undesirable.

Now, the choice of $\kappa = \kappa(f_1)$ as a (nonrandom) centering in (3.11) is entirely motivated by asymptotic orthogonality considerations under $P_{\theta, \sigma, 0; f_1}^{(n)}$, and does not affect the validity of the test. It follows that replacing $\kappa(f_1)$ with any data-dependent sequence $\kappa^{(n)}$ such that $\kappa^{(n)} - \kappa(f_1) = o_P(1)$ under $P_{\theta, \sigma, 0; f_1}^{(n)}$ asymptotically has no impact on $\hat{T}_{f_1}^{(n)}(\theta, \sigma)$ under $P_{\theta, \sigma, 0; f_1}^{(n)}$. Let us show that this sequence $\kappa^{(n)}$ can be chosen in order to cancel the unpleasant dependence of the test statistic on the definition of scale.

Provided that

$$f_1 \in \mathcal{F}_1^{\circ} := \{h_1 \in \mathcal{F}_1 : z \mapsto \phi_{h_1}(z) \text{ is differentiable, with derivative } \dot{\phi}_{h_1}\},$$

integration by parts yields

$$\mathcal{I}_{g_1}(f_1, g_1) = \int_{-\infty}^{\infty} \dot{\phi}_{f_1}(z) g_1(z) dz \quad \text{and} \quad \mathcal{J}_{g_1}(f_1, g_1) = 2 \int_{-\infty}^{\infty} z \phi_{f_1}(z) g_1(z) dz + \int_{-\infty}^{\infty} z^2 \dot{\phi}_{f_1}(z) g_1(z) dz.$$

Therefore, $\mathcal{I}_{g_1}(f_1, g_1)$, $\mathcal{J}_{g_1}(f_1, g_1)$, and $\kappa_{g_1}(f_1, g_1) := \mathcal{J}_{g_1}(f_1, g_1) / \mathcal{I}_{g_1}(f_1, g_1)$ under $P_{\theta, \sigma, 0; g_1}^{(n)}$ are consistently estimated by

$$\begin{aligned} \mathcal{I}^{(n)\circ}(f_1) &= \mathcal{I}^{(n)\circ}(f_1, \theta, \sigma) := \frac{1}{n} \sum_{i=1}^n \dot{\phi}_{f_1}(Z_i(\theta, \sigma)), \\ \mathcal{J}^{(n)\circ}(f_1) &= \mathcal{J}^{(n)\circ}(f_1, \theta, \sigma) := \frac{2}{n} \sum_{i=1}^n Z_i(\theta, \sigma) \phi_{f_1}(Z_i(\theta, \sigma)) + \frac{1}{n} \sum_{i=1}^n Z_i^2(\theta, \sigma) \dot{\phi}_{f_1}(Z_i(\theta, \sigma)) \end{aligned}$$

and

$$\kappa^{(n)\circ}(f_1) = \kappa^{(n)\circ}(f_1, \theta, \sigma) := \mathcal{J}^{(n)\circ}(f_1) / \mathcal{I}^{(n)\circ}(f_1), \quad (3.13)$$

respectively. Clearly, $\kappa^{(n)\circ}(f_1)$ satisfies the requirement that $\kappa^{(n)\circ}(f_1) - \kappa(f_1) = o_P(1)$ under $P_{\theta, \sigma, 0; f_1}^{(n)}$. In practice, however, $\kappa^{(n)\circ}(f_1, \theta, \sigma)$ cannot be computed from the observations, and $\kappa^{(n)\circ}(f_1, \theta, \hat{\sigma}_{\#})$, where $Z_i(\theta, \hat{\sigma}_{\#})$ has been substituted for $Z_i(\theta, \sigma)$, is to be used instead. As in the estimation of $\gamma^{(n)}(f_1)$ above, this substitution requires mild additional regularity conditions. Le Cam's third Lemma implies that $\kappa^{(n)\circ}(f_1, \theta, \hat{\sigma}_{\#}) - \kappa^{(n)\circ}(f_1, \theta, \sigma)$ is $o_P(1)$ under $P_{\theta, \sigma, 0; g_1}^{(n)}$ as soon as the asymptotic covariances of $\mathcal{I}^{(n)\circ}(f_1)$ and $\mathcal{J}^{(n)\circ}(f_1)$ with $\Delta_{g_1; 2}^{(n)}$ are finite. A simple computation (and the strong unimodality of f_1 and g_1) shows that a sufficient conditions for this is

$$\int_{-\infty}^{\infty} z^3 \dot{\phi}_{f_1}(z) \phi_{g_1}(z) g_1(z) dz < \infty \quad \text{and} \quad \int_{-\infty}^{\infty} z \dot{\phi}_{f_1}(z) \phi_{g_1}(z) g_1(z) dz < \infty \quad (3.14)$$

(no redundancy, since $\dot{\phi}_{f_1}$ is not necessarily monotone).

Denote by $\mathcal{F}_{f_1}^o$ the subset of $\mathcal{F}_{f_1}^*$ for which (3.14) holds. Emphasize the dependence of $\Delta_{f_1;3}^{(n)}(\kappa)$ on θ and σ by writing $\Delta_{f_1;3}^{(n)}(\kappa, \theta, \sigma)$: it follows from Lemma 6.5 in the appendix that, for $f_1 \in \mathcal{F}_1^o$ and $g_1 \in \mathcal{F}_{f_1}^o$, the difference between $\Delta_{f_1;3}^{(n)}(\kappa^{(n)o}(f_1, \theta, \hat{\sigma}_\#), \theta, \hat{\sigma}_\#)$ and $\Delta_{f_1;3}^{(n)}(\kappa_{g_1}(f_1, g_1), \theta, \sigma)$ is $o_P(1)$ under $P_{\theta, \sigma, 0; g_1}^{(n)}$. Letting (still for $f_1 \in \mathcal{F}_1^o$)

$$T_{f_1}^{(n)o}(\theta, \sigma) := \frac{1}{\sqrt{n\gamma^{(n)o}(f_1)}} \sum_{i=1}^n \phi_{f_1}(Z_i(\theta, \sigma)) \left(Z_i^2(\theta, \sigma) - \kappa^{(n)o}(f_1) \right) \quad (3.15)$$

where

$$\gamma^{(n)o}(f_1) = \gamma^{(n)o}(f_1, \theta, \sigma) := \mathcal{K}^{(n)}(f_1) - 2\kappa^{(n)o}(f_1)\mathcal{J}^{(n)}(f_1) + (\kappa^{(n)o}(f_1))^2\mathcal{I}^{(n)}(f_1),$$

we thus have the following result.

Proposition 3.2 *Let $f_1 \in \mathcal{F}_1^o$ and $g_1 \in \mathcal{F}_{f_1}^o$. Then,*

(i) $T_{f_1}^{(n)o}(\theta, \hat{\sigma}_\#) = T_{f_1}^{(n)o}(\theta, \sigma) + o_P(1)$ is asymptotically normal, with mean zero under $P_{\theta, \sigma, 0; g_1}^{(n)}$, mean

$$\tau \frac{\mathcal{K}_{g_1}(f_1, g_1) - \mathcal{J}_{g_1}(f_1, g_1)\kappa_{g_1}(f_1, g_1)}{[\mathcal{K}_{g_1}(f_1) - 2\mathcal{J}_{g_1}(f_1)\kappa_{g_1}(f_1, g_1) + \mathcal{I}_{g_1}(f_1)\kappa_{g_1}^2(f_1, g_1)]^{1/2}} \quad (3.16)$$

under $P_{\theta, \sigma, n^{-1/2}\tau; g_1}^{(n)}$, and variance one under both.

(ii) The sequence of tests rejecting the null hypothesis $\mathcal{H}_\theta^{(n)} := \bigcup_{g_1 \in \mathcal{F}_{f_1}^o} \mathcal{H}_{\theta, g_1}^{(n)}$ of symmetry (with specified location θ , unspecified scale σ and unspecified standardized density $g_1 \in \mathcal{F}_{f_1}^o$) whenever $T_{f_1}^{(n)o}(\theta, \hat{\sigma}_\#)$ exceeds the $(1 - \alpha)$ standard normal quantile z_α is locally asymptotically most powerful, at asymptotic level α , for $\mathcal{H}_\theta^{(n)}$ against $\bigcup_{\xi > 0} \bigcup_{\sigma \in \mathbb{R}_0^+} \{P_{\theta, \sigma, \xi; f_1}^{(n)}\}$.

The advantage of the test statistic (3.15) compared to (3.11) is that, irrespective of the underlying density g_1 , its behavior does not depend on the definition of the scale parameter. The case of a Gaussian reference density ($f_1 = \phi_1$), however, is slightly different, due to the particular form of the score function ϕ_{f_1} : see Section 3.3.

3.2.2 Unspecified location.

We now turn to the case under which both f_1 and the location θ are unspecified. Again, θ is to be replaced with some estimator, but additional care has to be taken about the asymptotic impact of this substitution. It follows from Le Cam's third Lemma that the impact, under $P_{\theta, \sigma, 0; g_1}^{(n)}$, of an estimated θ on $\Delta_{f_1;3}^{(n)}(\kappa)$ can be obtained from the asymptotic behavior of

$$\begin{pmatrix} \Delta_{f_1;3}^{(n)}(\kappa) \\ \Delta_{g_1;1}^{(n)}(\theta, \sigma, 0) \end{pmatrix} = n^{-1/2} \sum_{i=1}^n \begin{pmatrix} \phi_{f_1}(Z_i)(Z_i^2 - \kappa) \\ \sigma^{-1}\phi_{g_1}(Z_i) \end{pmatrix},$$

which is asymptotically normal with asymptotic covariance matrix

$$\begin{pmatrix} \gamma_{g_1}^\kappa(f_1) & \delta_{g_1}^\kappa(f_1, g_1) \\ \delta_{g_1}^\kappa(f_1, g_1) & \sigma^{-2}\mathcal{I}(g_1) \end{pmatrix}$$

where $\delta_{g_1}^\kappa(f_1, g_1) := \sigma^{-1}(\mathcal{J}_{g_1}(f_1, g_1) - \kappa \mathcal{I}_{g_1}(f_1, g_1))$. Clearly, this covariance $\delta_{g_1}^\kappa(f_1, g_1)$ vanishes iff $\kappa = \kappa_{g_1}(f_1, g_1)$ which, for $g_1 = f_1$, coincides with $\kappa(f_1)$.

Assuming that an estimate $\kappa^{(n)}(f_1)$ such that $\kappa^{(n)}(f_1) - \kappa_{g_1}(f_1, g_1) = o_P(1)$ under $P_{\theta, \sigma, 0; g_1}^{(n)}$ exists, $\Delta_{f_1; 3}^{(n)}(\kappa^{(n)}(f_1))$ is asymptotically equivalent to $\Delta_{f_1; 3}^{(n)}(\kappa(f_1))$ under $P_{\theta, \sigma, 0; f_1}^{(n)}$, and asymptotically uncorrelated with $\Delta_{g_1; 1}^{(n)}(\theta, \sigma, 0)$ and $\Delta_{g_1; 2}^{(n)}(\theta, \sigma, 0)$ —hence, asymptotically insensitive (in probability) to root- n perturbations of both θ and σ , under $P_{\theta, \sigma, 0; g_1}^{(n)}$. It follows from Section 3.2.1 that $\kappa^{(n)o}(f_1, \theta, \sigma)$ defined in (3.13) is such an estimator. The same reasoning as in Section 3.2.1 implies that this still holds when substituting, in $\Delta_{f_1; 3}^{(n)}(\kappa)$, any estimators $\hat{\theta}_\#$ and $\hat{\sigma}_\#$ satisfying (C1) and (C2) for θ and σ . Finally, Lemma 6.5 in the appendix ensures that $\Delta_{f_1; 3}^{(n)}(\kappa^{(n)o}(f_1, \hat{\theta}_\#, \hat{\sigma}_\#), \hat{\theta}_\#, \hat{\sigma}_\#)$ can be substituted for $\Delta_{f_1; 3}^{(n)}(\kappa_{g_1}(f_1, g_1), \theta, \sigma)$. We thus have shown the following result.

Proposition 3.3 *Let $f_1 \in \mathcal{F}_1^o$ and $g_1 \in \mathcal{F}_{f_1}^o$. Then,*

- (i) $T_{f_1}^{(n)o}(\hat{\theta}_\#, \hat{\sigma}_\#) = T_{f_1}^{(n)o}(\theta, \hat{\sigma}_\#) + o_P(1) = T_{f_1}^{(n)o}(\theta, \sigma) + o_P(1)$ is asymptotically normal, with mean zero under $P_{\theta, \sigma, 0; g_1}^{(n)}$, mean (3.16) under $P_{\theta, \sigma, n^{-1/2}\tau; g_1}^{(n)}$, and variance one under both.
- (ii) The sequence of tests rejecting the null hypothesis $\mathcal{H}^{(n)} := \bigcup_{g_1 \in \mathcal{F}_{f_1}^o} \bigcup_{\theta \in \mathbb{R}} \mathcal{H}_{\theta; g_1}^{(n)}$ of symmetry (with unspecified location θ , unspecified scale σ and unspecified standardized density g_1) whenever $T_{f_1}^{(n)o}(\hat{\theta}_\#, \hat{\sigma}_\#)$ exceeds the $(1-\alpha)$ standard normal quantile z_α is locally asymptotically most powerful, at asymptotic level α , for $\mathcal{H}^{(n)}$ against $\bigcup_{\xi > 0} \bigcup_{\theta \in \mathbb{R}} \bigcup_{\sigma \in \mathbb{R}_0^+} \{P_{\theta, \sigma, \xi; f_1}^{(n)}\}$.

This test is based on the same test statistic $T_{f_1}^{(n)o}$ as the specified-location test of Proposition 3.2, except that the (here unspecified) location θ is replaced by an estimator $\hat{\theta}_\#$. The local powers of the two tests coincide: asymptotically, again, there is no loss of efficiency due to the non-specification of θ .

3.3 Pseudo-Gaussian tests.

Particularizing the reference density f_1 as the standard normal one ϕ_1 in the tests of Sections 3.2.1 and 3.2.2 in principle yields *pseudo-Gaussian* tests, based on the test statistics $T_{\phi_1}^{(n)o}(\theta)$ or $T_{\phi_1}^{(n)o}(\hat{\theta})$. Due to the particular form of the Gaussian score function, however, the Gaussian statistic can be given a much simpler form. Indeed, $\mathcal{I}_{g_1}(\phi_1, g_1) = \mathcal{I}(\phi_1) = a$ does not depend on g_1 , and needs not be estimated, while $\mathcal{J}_{g_1}(\phi_1, g_1) = \mathcal{J}(\phi_1) = 3a\mu_2(g_1)$, so that $\kappa_{g_1}(f_1, g_1)$ is consistently estimated by $3m_2^{(n)}(\theta)/\sigma^2$. This, after elementary computation, yields the test statistic

$$T^{(n)\dagger}(\theta) := \frac{1}{\sqrt{n\gamma^{(n)\dagger}}} \sum_{i=1}^n (X_i - \theta) \left((X_i - \theta)^2 - 3m_2^{(n)}(\theta) \right), \quad (3.17)$$

where $\gamma^{(n)\dagger} := \gamma^{(n)\dagger}(\theta) := m_6^{(n)}(\theta) - 6m_2^{(n)}(\theta)m_4^{(n)}(\theta) + 9(m_2^{(n)}(\theta))^3$. For this test statistic $T^{(n)\dagger}(\theta)$, the asymptotic shift (3.16) under $P_{\theta, \sigma, n^{-1/2}\tau; g_1}^{(n)}$ now takes the form

$$\tau [5\mu_4(g_1) - 9\mu_2^2(g_1)][\mu_6(g_1) - 6\mu_2(g_1)\mu_4(g_1) + 9\mu_2^3(g_1)]^{-1/2};$$

this shift does not depend on a anymore, and still reduces to $\tau\sqrt{6/a}$ under $\mathbb{P}_{\theta,\sigma,n^{-1/2}\tau;\phi_1}^{(n)}$ (the same value as for $\hat{T}_{\phi_1}^{(n)}(\theta,\sigma)$, which confirms that optimality under Gaussian densities has been preserved); nor does it depend on the scale.

The tests based on the asymptotically standard normal null distribution of $T^{(n)\dagger}$ are optimal under Gaussian assumptions, but remain valid when those assumptions are violated. Again, a simple Slutsky argument allows for replacing θ (if unspecified) with any consistent estimator $\hat{\theta}$ without going through discretization; moreover, (3.17) does not depend on σ . The tests based on $T^{(n)\dagger}(\theta)$ and $T^{(n)\dagger}(\bar{X}^{(n)})$ both are closely related to the traditional test of symmetry based on $b_1^{(n)}$. More precisely, under any $\mathbb{P}_{\theta,\sigma,0;g_1}^{(n)}$, $g_1 \in (\mathcal{F}_{\phi_1}^o =) \mathcal{F}_{\phi_1}$ (note that the assumption $g_1 \in \mathcal{F}_{\phi_1}^o = \mathcal{F}_{\phi_1}$ implies that g_1 has finite moments of order six),

$$T^{(n)\dagger}(\theta) = T^{(n)\dagger}(\bar{X}^{(n)}) + o_{\mathbb{P}}(1) = S_2^{(n)} + o_{\mathbb{P}}(1),$$

where $S_2^{(n)}$ is the empirically standardized form (1.2) of $b_1^{(n)}$ (see (1.2)).

Summing up, we have the following result.

Proposition 3.4 *Let $g_1 \in \mathcal{F}_{\phi_1}$, $\hat{\theta} = \theta + O_{\mathbb{P}}(n^{-1/2})$; recall that $\mu_k(g_1) := \int_{-\infty}^{\infty} z^k g_1(z) dz$ stands for the moment of order k of g_1 . Then,*

(i) $T^{(n)\dagger}(\hat{\theta}) = T^{(n)\dagger}(\theta) + o_{\mathbb{P}}(1)$ is asymptotically normal, with mean zero under $\mathbb{P}_{\theta,\sigma,0;g_1}^{(n)}$, mean $\tau[5\mu_4(g_1) - 9\mu_2^2(g_1)]/[\mu_6(g_1) - 6\mu_2(g_1)\mu_4(g_1) + 9\mu_2^3(g_1)]^{1/2}$ under $\mathbb{P}_{\theta,\sigma,n^{-1/2}\tau;g_1}^{(n)}$, and variance one under both.

(ii) The sequence of tests rejecting the null hypothesis of symmetry (with specified location θ) $\mathcal{H}_{\theta}^{(n)} := \bigcup_{g_1 \in \mathcal{F}_{\phi_1}} \mathcal{H}_{\theta;g_1}^{(n)}$ whenever $T^{(n)\dagger}(\theta)$ exceeds the $(1-\alpha)$ standard normal quantile z_{α} is locally asymptotically most powerful, at asymptotic level α against $\bigcup_{\xi>0} \bigcup_{\sigma \in \mathbb{R}_0^+} \{\mathbb{P}_{\theta,\sigma,\xi;\phi_1}^{(n)}\}$.

(iii) The sequence of tests rejecting the null hypothesis of symmetry (with unspecified location) $\mathcal{H}^{(n)} := \bigcup_{g_1 \in \mathcal{F}_{\phi_1}} \bigcup_{\theta \in \mathbb{R}} \mathcal{H}_{\theta;g_1}^{(n)}$ whenever $T^{(n)\dagger}(\hat{\theta})$ exceeds the $(1-\alpha)$ standard normal quantile z_{α} is locally asymptotically most powerful, at asymptotic level α against $\bigcup_{\xi>0} \bigcup_{\theta \in \mathbb{R}} \bigcup_{\sigma \in \mathbb{R}_0^+} \{\mathbb{P}_{\theta,\sigma,\xi;\phi_1}^{(n)}\}$.

For the sake of completeness, we also provide (with the same notation) the following result on the asymptotic behavior of the (suboptimal) test based on $m_3^{(n)}(\theta)$. Details are left to the reader.

Proposition 3.5 *Let $g_1 \in \mathcal{F}_{\phi_1}$. Then, $S_1^{(n)} := n^{1/2}m_3^{(n)}(\theta)/(m_6^{(n)}(\theta))^{1/2}$ is asymptotically normal, with mean zero under $\mathbb{P}_{\theta,\sigma,0;g_1}^{(n)}$, mean $\tau[5\mu_4(g_1) - 3\kappa(g_1)\mu_2(g_1)]/\mu_6^{1/2}(g_1)$ under $\mathbb{P}_{\theta,\sigma,n^{-1/2}\tau;g_1}^{(n)}$, and variance one under both.*

Under Gaussian densities ($g_1 = \phi_1$), the asymptotic shifts of $T_{\phi_1}^{(n)o}(\theta)$ (Proposition 3.6 (i)) and $S_1^{(n)}$ (Proposition 3.5) are $16\tau/\sqrt{6}$ and $16\tau/\sqrt{15}$, respectively; the asymptotic relative efficiency of $T^{(n)\dagger}(\theta)$ with respect to $S_1^{(n)}$ is thus as high as 2.5 in the vicinity of Gaussian densities. This, which is not a small difference, confirms the suboptimality of $m_3^{(n)}(\theta)$ -based tests.

3.4 Laplace tests.

Replacing the Gaussian reference density ϕ_1 with the double-exponential one $f_{\mathcal{L}}$, we similarly obtain the *Laplace tests*. The assumption that $f_1 \in \mathcal{F}_1^\circ$ unfortunately rules out $f_{\mathcal{L}}$, since $\phi_{f_{\mathcal{L}}}(z) = \text{sign}(z)/d$ is not differentiable, so that the construction of $\kappa^{(n)\circ}(f_1)$ in (3.13) does not apply for $f_1 = f_{\mathcal{L}}$. Now, a direct construction is possible: $\mathcal{I}_{g_1}(f_{\mathcal{L}}, g_1)$ indeed reduces to $2g_1(0)/d$ —which is consistently estimated by $\mathcal{I}^{(n)\circ}(f_{\mathcal{L}}) := 2\hat{g}_1(0)/d$ (where \hat{g}_1 , for instance, is some kernel estimator of g_1). Similarly, $\mathcal{J}_{g_1}(f_{\mathcal{L}}, g_1)$ reduces to $(2/d) \int_{-\infty}^{\infty} |z|g_1(z) dz$ —which is consistently estimated by $\mathcal{J}^{(n)\circ}(f_{\mathcal{L}}) := (2/nd) \sum_{i=1}^n |Z_i(\theta, \hat{\sigma}_\#)|$; the scaling constant d is easily computed, yielding $d = 1/(\log 2) \approx 1.44$. Then,

$$\kappa^{(n)\circ}(f_{\mathcal{L}}) := \mathcal{J}^{(n)\circ}(f_{\mathcal{L}})/\mathcal{I}^{(n)\circ}(f_{\mathcal{L}}) = \frac{1}{n\hat{g}_1(0)} \sum_{i=1}^n |Z_i(\theta, \hat{\sigma}_\#)|$$

is such that $\kappa^{(n)\circ}(f_{\mathcal{L}}) - \kappa(f_{\mathcal{L}}) = o_{\mathbb{P}}(1)$ under $\mathbb{P}_{\theta, \sigma, 0; f_{\mathcal{L}}}^{(n)}$, as required.

The Laplace tests are based on $T_{\mathcal{L}}^{(n)\circ}(\theta)$ (specified θ) or $T_{\mathcal{L}}^{(n)\circ}(\hat{\theta})$ (unspecified θ), where

$$T_{\mathcal{L}}^{(n)\circ}(\theta) := \frac{1}{\sqrt{n\gamma^{(n)\circ}(f_{\mathcal{L}})}} \sum_{i=1}^n \text{sign}(Z_i(\theta, \hat{\sigma}_\#)) \left((Z_i(\theta, \hat{\sigma}_\#))^2 - \kappa^{(n)\circ}(f_{\mathcal{L}}) \right)$$

with

$$\gamma^{(n)\circ}(f_{\mathcal{L}}) = \frac{m_4^{(n)}}{\hat{\sigma}_\#^4} - 2 \frac{m_2^{(n)}}{n\hat{\sigma}_\#^2 \hat{g}_1(0)} \sum_{i=1}^n |Z_i(\theta, \hat{\sigma}_\#)| + \left(\frac{1}{n\hat{g}_1(0)} \sum_{i=1}^n |Z_i(\theta, \hat{\sigma}_\#)| \right)^2.$$

These tests share with the Gaussian Fechner test (see Cassart et al. 2008) the use of the score function $z \mapsto \text{sign}(z)z^2$. The orthogonalization however differs, since the Fechner and Edgeworth families the tests were built on are different. The following proposition summarizes their properties; details are left to the reader.

Proposition 3.6 *Let $g_1 \in \mathcal{F}_{f_{\mathcal{L}}}$, $\hat{\theta} = \theta + O_{\mathbb{P}}(n^{-1/2})$, and denote by $\mu_{|k|}(g_1) := \int_{-\infty}^{\infty} |z|^k g_1(z) dz$ the absolute moment of order k of g_1 . Then,*

(i) $T_{\mathcal{L}}^{(n)\circ}(\hat{\theta}) = T_{\mathcal{L}}^{(n)\circ}(\theta) + o_{\mathbb{P}}(1)$ is asymptotically normal, with mean zero under $\mathbb{P}_{\theta, \sigma, 0; g_1}^{(n)}$, mean

$$\tau [4\mu_{|3|}(g_1) - 2\mu_{|1|}^2(g_1)/g_1(0)] / [\mu_4(g_1) - 2\mu_2(g_1)\mu_{|1|}(g_1)/g_1(0) + \mu_{|1|}^2(g_1)/(g_1(0))^2]^{1/2}$$

under $\mathbb{P}_{\theta, \sigma, n^{-1/2}\tau; g_1}^{(n)}$, and variance one under both.

(ii) The sequence of tests rejecting the null hypothesis of symmetry (with specified location θ) $\mathcal{H}_{\theta}^{(n)} := \bigcup_{g_1 \in \mathcal{F}_{f_{\mathcal{L}}}} \mathcal{H}_{\theta; g_1}^{(n)}$ whenever $T_{\mathcal{L}}^{(n)\circ}(\theta)$ exceeds the $(1 - \alpha)$ standard normal quantile z_α is locally asymptotically most powerful, at asymptotic level α , against $\bigcup_{\xi > 0} \bigcup_{\sigma \in \mathbb{R}_0^+} \{\mathbb{P}_{\theta, \sigma, \xi; f_{\mathcal{L}}}^{(n)}\}$.

(iii) The sequence of tests rejecting the null hypothesis of symmetry (with unspecified location) $\mathcal{H}^{(n)} := \bigcup_{g_1 \in \mathcal{F}_{f_{\mathcal{L}}}} \bigcup_{\theta \in \mathbb{R}} \mathcal{H}_{\theta; g_1}^{(n)}$ whenever $T_{\mathcal{L}}^{(n)\circ}(\hat{\theta})$ exceeds the $(1 - \alpha)$ standard normal quantile z_α is locally asymptotically most powerful, at asymptotic level α , against $\bigcup_{\xi > 0} \bigcup_{\theta \in \mathbb{R}} \bigcup_{\sigma \in \mathbb{R}_0^+} \{\mathbb{P}_{\theta, \sigma, \xi; f_{\mathcal{L}}}^{(n)}\}$.

Comparing the asymptotic shifts of the pseudo-Gaussian tests and the Laplace ones yields asymptotic relative efficiency values; the asymptotic efficiency of tests based on $T^{(n)\dagger}$ with respect to those based on $T_{\mathcal{L}}^{(n)o}$ is 1.76 in the vicinity of Gaussian densities, and 0.7 in the vicinity of double exponential ones. Finally, note that the empirical median $X_{1/2}^{(n)}$ here provides a much more sensible estimator of θ than the empirical mean $\bar{X}^{(n)}$; it has been used for $\hat{\theta}$ in the simulations of $T_{\mathcal{L}}^{(n)o}(\hat{\theta})$ in Section 4.

4 Finite sample performances.

We performed a first simulation study on the basis of $N = 5,000$ independent samples of size $n = 100$ from (2.1), with normal and double-exponential densities f_1 and skewness parameter values $\xi = 0.1$ and $\xi = 0.2$. Each of those samples was subjected, at asymptotic level $\alpha = 5\%$, to the classical specified-location test of skewness based on $m_3^{(n)}(\theta)$ (that is, on (1.1)), the (optimal) pseudo-Gaussian tests based on $b_1^{(n)}$ (that is, on (1.2)) and the corresponding Laplace and Logistic tests. For the sake of completeness, the two *triples tests* proposed by Randles et al. (1980), which are based on the signs of $X_i + X_j - 2X_k$, $1 \leq i < j < k \leq n$, are also included in this simulation study. Those tests, which are location-invariant, do not follow from any argument of group invariance, and are not distribution-free.

Rejection frequencies are reported in Table 1.

| Test | $\mathcal{SN}(\xi)$ | | | $\mathcal{SL}(\xi)$ | | |
|---|---------------------|--------|--------|---------------------|--------|--------|
| | ξ | | | ξ | | |
| | 0 | 0.1 | 0.2 | 0 | 0.1 | 0.2 |
| $m_3^{(n)}(\theta)$ | 0.0372 | 0.1136 | 0.0996 | 0.0306 | 0.6938 | 0.8722 |
| $T^{(n)\dagger}(\theta)$ | 0.0434 | 0.7276 | 0.9958 | 0.0252 | 0.4596 | 0.6774 |
| $b_1^{(n)}$ | 0.0416 | 0.6986 | 0.9746 | 0.0444 | 0.7458 | 0.8930 |
| $T_{\mathcal{L}}^{(n)o}(\theta)$ | 0.0520 | 0.5424 | 0.9474 | 0.0406 | 0.9090 | 0.9998 |
| $T_{\mathcal{L}}^{(n)o}(X_{1/2}^{(n)})$ | 0.0280 | 0.4440 | 0.8360 | 0.0284 | 0.8838 | 0.9960 |
| $T_{\text{Log}}^{(n)o}(\theta)$ | 0.0492 | 0.7336 | 0.9954 | 0.0378 | 0.8516 | 0.9894 |
| $T_{\text{Log}}^{(n)o}(\bar{X}^{(n)})$ | 0.0362 | 0.6626 | 0.9716 | 0.0384 | 0.8516 | 0.9880 |
| $T_{R1}^{(n)}$ | 0.0518 | 0.6786 | 0.9606 | 0.0576 | 0.9276 | 0.9986 |
| $T_{R2}^{(n)}$ | 0.0608 | 0.6992 | 0.9640 | 0.0650 | 0.9350 | 0.9988 |

Table 1: Rejection frequencies (out of $N = 5,000$ replications), under various symmetric and skewed normal and double-exponential distributions from the Edgeworth families (2.1), with $\xi = 0, 0.1, 0.2$, of the classical tests of skewness, based on $m_3^{(n)}(\theta)$ and $b_1^{(n)}$, the Gaussian, Laplace and logistic tests, and the *triples tests* $T_{R1}^{(n)}$ and $T_{R2}^{(n)}$ of Randles et al. (1980).

Note that all tests considered here, except for Randles', are extremely conservative, and in most cases hardly reach the nominal 5% rejection frequency under the null. Randles' tests on the other hand significantly overreject, which does not facilitate comparisons. Despite of that, the tests based on $b_1^{(n)}$, $T_{\mathcal{L}}^{(n)o}(X_{1/2}^{(n)})$ and $T_{\text{Log}}^{(n)o}(\bar{X}^{(n)})$ exhibit excellent performances, and largely outperform those based on $m_3^{(n)}(\theta)$ (despite of the fact that the latter requires θ to be known).

The Edgeworth families considered throughout this paper, however, served as a theoretical guideline in the construction of our Edgeworth testing procedures, and never were meant as an actual data generating process. One could argue that analyzing performances under alternatives of the Edgeworth type creates an unfair bias in favor of our methods. Therefore, we also

generated $N = 5,000$ independent samples of size $n = 100$ from the skew-normal $\mathcal{SN}(\lambda)$ and skew- t $\mathcal{St}(\nu, \lambda)$ densities (with $\nu = 2$, $\nu = 4$ and $\nu = 8$ degrees of freedom) defined by Azzalini and Capitanio (2003), for various values of their skewness coefficient λ ($\lambda = 0$ implying symmetry); since the sign of λ is not directly related to that of ξ , we only performed two-sided tests. That class of skewed densities was chosen in view of its increasing popularity among practitioners.

| Test | $\mathcal{SN}(\lambda)$ | | | | $\mathcal{St}(2, \lambda)$ | | | |
|---|----------------------------|--------|--------|--------|----------------------------|--------|--------|--------|
| | λ | | | | λ | | | |
| | 0 | 1 | 2 | 3 | 0 | 2 | 4 | 6 |
| $m_3^{(n)}(\theta)$ | 0.0476 | 0.0482 | 0.0952 | 0.1936 | 0.0072 | 0.0106 | 0.0126 | 0.0144 |
| $T^{(n)\dagger}(\theta)$ | 0.0374 | 0.0634 | 0.2988 | 0.5942 | 0.0046 | 0.0118 | 0.0182 | 0.0268 |
| $b_1^{(n)}$ | 0.0418 | 0.0616 | 0.3066 | 0.6130 | 0.0172 | 0.0232 | 0.0308 | 0.0396 |
| $T_{\mathcal{L}}^{(n)\circ}(\theta)$ | 0.0460 | 0.0690 | 0.2682 | 0.5406 | 0.0180 | 0.0414 | 0.0740 | 0.0988 |
| $T_{\mathcal{L}}^{(n)\circ}(X_{1/2}^{(n)})$ | 0.0334 | 0.0472 | 0.2022 | 0.4736 | 0.0168 | 0.0288 | 0.0520 | 0.0678 |
| $T_{\text{Log}}^{(n)\circ}(\theta)$ | 0.0468 | 0.0742 | 0.3542 | 0.7010 | 0.0154 | 0.0286 | 0.0496 | 0.0666 |
| $T_{\text{Log}}^{(n)\circ}(\bar{X}^{(n)})$ | 0.0354 | 0.0568 | 0.2988 | 0.6426 | 0.0144 | 0.0256 | 0.0408 | 0.0492 |
| $T_{R1}^{(n)}$ | 0.0540 | 0.0778 | 0.3602 | 0.7082 | 0.0618 | 0.1032 | 0.1798 | 0.2312 |
| $T_{R2}^{(n)}$ | 0.0598 | 0.0886 | 0.3812 | 0.7258 | 0.0656 | 0.1098 | 0.1882 | 0.2424 |
| Test | $\mathcal{St}(4, \lambda)$ | | | | $\mathcal{St}(8, \lambda)$ | | | |
| | λ | | | | λ | | | |
| | 0 | 2 | 4 | 6 | 0 | 2 | 4 | 6 |
| $m_3^{(n)}(\theta)$ | 0.0192 | 0.0190 | 0.0298 | 0.0436 | 0.0316 | 0.0608 | 0.1302 | 0.1754 |
| $T^{(n)\dagger}(\theta)$ | 0.0144 | 0.0184 | 0.0586 | 0.1134 | 0.0260 | 0.1422 | 0.4078 | 0.5428 |
| $b_1^{(n)}$ | 0.0252 | 0.0302 | 0.0754 | 0.1298 | 0.0322 | 0.1604 | 0.4186 | 0.5484 |
| $T_{\mathcal{L}}^{(n)\circ}(\theta)$ | 0.0332 | 0.0406 | 0.1304 | 0.2514 | 0.0456 | 0.2054 | 0.5640 | 0.6906 |
| $T_{\mathcal{L}}^{(n)\circ}(X_{1/2}^{(n)})$ | 0.0206 | 0.0302 | 0.0950 | 0.1798 | 0.0304 | 0.1518 | 0.4834 | 0.6260 |
| $T_{\text{Log}}^{(n)\circ}(\theta)$ | 0.0236 | 0.0318 | 0.1082 | 0.2086 | 0.0342 | 0.2104 | 0.5846 | 0.7508 |
| $T_{\text{Log}}^{(n)\circ}(\bar{X}^{(n)})$ | 0.0228 | 0.0276 | 0.0882 | 0.1694 | 0.0288 | 0.1712 | 0.5046 | 0.6696 |
| $T_{R1}^{(n)}$ | 0.0508 | 0.0636 | 0.1842 | 0.3444 | 0.0530 | 0.2592 | 0.6766 | 0.8336 |
| $T_{R2}^{(n)}$ | 0.0556 | 0.0688 | 0.1938 | 0.3582 | 0.0598 | 0.2740 | 0.6940 | 0.8422 |

Table 2: Rejection frequencies (out of $N = 5,000$ replications), under various symmetric and related skew-normal and skew- t distributions (Azzalini and Capitanio 2003) $\mathcal{SN}(\lambda)$ and $\mathcal{St}(\nu, \lambda)$ ($\nu = 2, 4, 8$ and various λ) of the classical tests of skewness, based on $m_3^{(n)}(\theta)$ and $b_1^{(n)}$, the Gaussian, Laplace and logistic tests, and the *triples tests* $T_{R1}^{(n)}$ and $T_{R2}^{(n)}$ of Randles et al. (1980).

None of the tests considered in this simulation example are optimal in this Azzalini and Capitanio context. Inspection of Table 2 nevertheless reveals that the classical tests of skewness based on $m_3^{(n)}(\theta)$ and $b_1^{(n)}$ collapse under t_2 and t_4 , which have infinite sixth-order moments, and under the related $\mathcal{St}(2, \lambda)$ and $\mathcal{St}(4, \lambda)$ densities. The same tests fail to achieve the 5% nominal level under the Student distribution with 8 degrees of freedom (despite finite sixth-order moments), and show weak performance under the $\mathcal{St}(8, \lambda)$ density. Remark that the suboptimality of the test based on $m_3^{(n)}(\theta)$, which, as a consequence of Proposition 3.1, may be considered as an artificial consequence of the choice of skewed families of the Edgeworth type, nevertheless also very neatly appears here. The triples tests behave uniformly well; note, however, their tendency to overrejection, in particular under Student densities.

5 Conclusions and perspectives.

We have derived the optimal tests for testing the hypothesis of symmetry within families of skewed densities mimicking the type of local asymmetry observed in a central limit behaviour. The resulting tests were obtained under specified or unspecified densities, and for specified and unspecified location.

These tests naturally extend into nonparametric rank-based ones. The hypothesis of symmetry indeed enjoys strong group invariance features. The null hypothesis $\mathcal{H}_\theta^{(n)}$ of symmetry with respect to θ is generated by the group $\mathcal{G}_\theta^{(n),\circ}$ of all transformations ϱ_h of \mathbb{R}^n such that $\varrho_h(x_1, \dots, x_n) := (h(x_1), \dots, h(x_n))$, where $\lim_{x \rightarrow \pm\infty} h(x) = \pm\infty$, and $x \mapsto h(x)$ is continuous, monotone increasing, and skew-symmetric with respect to θ (that is, satisfy $h(\theta - z) - \theta = -(h(\theta + z) - \theta)$). A maximal invariant for that group is known to be the vector $(s_1(\theta), \dots, s_n(\theta))$, along with the vector $(R_{+,1}^{(n)}(\theta), \dots, R_{+,n}^{(n)}(\theta))$, where $s_i(\theta)$ is the sign of $X_i - \theta$ and $R_{+,i}^{(n)}(\theta)$ the rank of $|X_i - \theta|$ among $|X_1 - \theta|, \dots, |X_n - \theta|$. General results on semiparametric efficiency (Hallin and Werker 2003) indicate that, in such context, the expectation of the central sequence $\Delta_{f_1}^{(n)}(\boldsymbol{\vartheta})$ conditional on those *signed ranks* yields a version of the semiparametrically efficient (at f_1 and $\boldsymbol{\vartheta}$) central sequence.

That approach is adopted in a companion paper (Cassart et al. 2009). For instance, the rank-based counterpart of the specified- θ test statistic of Proposition 3.6(ii) is the (strictly distribution-free, irrespective of any moment assumptions) van der Waerden test based on

$$\tilde{T}_{\text{vdW}}^{(n)}(\theta) := \frac{1}{\sqrt{n\gamma^{(n)}(\phi_1)}} \sum_{i=1}^n s_i(\theta) \Phi^{-1}\left(\frac{n+1+R_{+,i}^{(n)}(\theta)}{2(n+1)}\right) \left(\left(\Phi^{-1}\left(\frac{n+1+R_{+,i}^{(n)}(\theta)}{2(n+1)}\right) \right)^2 - 3 \right),$$

where $\gamma^{(n)}(\phi_1) := n^{-1} \sum_{r=1}^n \Phi^{-1}\left(\frac{n+1+r}{2(n+1)}\right) \left(\left(\Phi^{-1}\left(\frac{n+1+r}{2(n+1)}\right) \right)^2 - 3 \right)^2$ and Φ stands for the standard normal distribution function. The unspecified θ case under such approach, however, is considerably more delicate.

6 Appendix.

6.1 Proof of Proposition 2.1.

The proof relies on Swensen (1985)'s Lemma 1 which involves a set of six jointly sufficient conditions. Most of them readily follow from the form of local likelihoods, and are left to the reader. The most delicate one is the quadratic mean differentiability of $(\theta, \sigma, \xi) \mapsto g_{\theta, \sigma, \xi; f_1}^{1/2}(x)$, which we establish in the following lemma, where $g_{\theta, \sigma, \xi; f_1}(x)$ is the density defined in (2.1).

Lemma 6.1 Let $f_1 \in \mathcal{F}_1$, $\theta \in \mathbb{R}$, $\sigma \in \mathbb{R}_0^+$ and $\xi \in \mathbb{R}$. Define

$$\begin{aligned} g_{\theta,\sigma,\xi;f_1}(x) &:= \sigma^{-1}f_1\left(\frac{x-\theta}{\sigma}\right) - \frac{\xi}{\sigma}\dot{f}_1\left(\frac{x-\theta}{\sigma}\right) \left(\left(\frac{x-\theta}{\sigma}\right)^2 - \kappa(f_1)\right) I[|x-\theta| \leq \sigma|z^*|] \\ &\quad - \text{sign}(\xi)\sigma^{-1}f_1\left(\frac{x-\theta}{\sigma}\right) \{I[x-\theta > \text{sign}(-\xi)\sigma|z^*|] - I[x-\theta < \text{sign}(\xi)\sigma|z^*|]\}, \\ D_\theta g_{\theta,\sigma,0;f_1}^{1/2}(x) &:= \frac{1}{2}\sigma^{-3/2}f_1^{1/2}\left(\frac{x-\theta}{\sigma}\right)\phi_{f_1}\left(\frac{x-\theta}{\sigma}\right), \\ D_\sigma g_{\theta,\sigma,0;f_1}^{1/2}(x) &:= \frac{1}{2}\sigma^{-3/2}f_1^{1/2}\left(\frac{x-\theta}{\sigma}\right)\left(\left(\frac{x-\theta}{\sigma}\right)\phi_{f_1}\left(\frac{x-\theta}{\sigma}\right) - 1\right), \end{aligned}$$

and

$$D_\xi g_{\theta,\sigma,\xi;f_1}^{1/2}(x)|_{\xi=0} := \frac{1}{2}\sigma^{-1/2}f_1^{1/2}\left(\frac{x-\theta}{\sigma}\right)\phi_{f_1}\left(\frac{x-\theta}{\sigma}\right)\left(\left(\frac{x-\theta}{\sigma}\right)^2 - \kappa(f_1)\right).$$

Then, as r, s , and $t \rightarrow 0$,

- (i) $\int \{g_{\theta+t,\sigma+s,r;f_1}^{1/2}(x) - g_{\theta+t,\sigma+s,0;f_1}^{1/2}(x) - rD_\xi g_{\theta+t,\sigma+s,\xi;f_1}^{1/2}(x)|_{\xi=0}\}^2 dx = o(r^2)$,
- (ii) $\int \left\{g_{\theta+t,\sigma+s,0;f_1}^{1/2}(x) - g_{\theta,\sigma,0;f_1}^{1/2}(x) - \begin{pmatrix} t \\ s \end{pmatrix}' \begin{pmatrix} D_\theta g_{\theta,\sigma,0;f_1}^{1/2}(x) \\ D_\sigma g_{\theta,\sigma,0;f_1}^{1/2}(x) \end{pmatrix}\right\}^2 dx = o\left(\left\|\begin{pmatrix} t \\ s \end{pmatrix}\right\|^2\right)$,
- (iii) $\int \left\{\left(D_\xi g_{\theta+t,\sigma+s,\xi;f_1}^{1/2}(x)|_{\xi=0} - D_\xi g_{\theta,\sigma,\xi;f_1}^{1/2}(x)|_{\xi=0}\right)\right\}^2 dx = o(1)$, and
- (iv) $\int \left\{g_{\theta+t,\sigma+s,r;f_1}^{1/2}(x) - g_{\theta,\sigma,0;f_1}^{1/2}(x) - \begin{pmatrix} t \\ s \\ r \end{pmatrix}' \begin{pmatrix} D_\theta g_{\theta,\sigma,0;f_1}^{1/2}(x) \\ D_\sigma g_{\theta,\sigma,0;f_1}^{1/2}(x) \\ D_\xi g_{\theta,\sigma,\xi;f_1}^{1/2}(x)|_{\xi=0} \end{pmatrix}\right\}^2 dx = o\left(\left\|\begin{pmatrix} t \\ s \\ r \end{pmatrix}\right\|^2\right)$.

Proof. (i) Decompose $\int \{g_{\theta+t,\sigma+s,r;f_1}^{1/2}(x) - g_{\theta+t,\sigma+s,0;f_1}^{1/2}(x) - rD_\xi g_{\theta+t,\sigma+s,\xi;f_1}^{1/2}(x)|_{\xi=0}\}^2 dx$ into $a_1 + 2a_2$ where

$$\begin{aligned} a_1 &= \int_{|u| < |z^*|} \left\{ \left(\frac{1}{\sigma+s}f_1(u)\right)^{1/2} \left[1 + r\phi_{f_1}(u)(u^2 - \kappa(f_1))\right]^{1/2} - \left(\frac{1}{\sigma+s}f_1(u)\right)^{1/2} \right. \\ &\quad \left. - \frac{r}{2}(\sigma+s)^{-1/2} \frac{\dot{f}_1(u)}{f_1^{1/2}(u)}(u^2 - \kappa(f_1)) \right\}^2 (\sigma+s) du \end{aligned}$$

and

$$a_2 = \int_{u > |z^*|} \left\{ \left((\sigma+s)^{-1}f_1(u)\right)^{1/2} - \frac{r}{2}(\sigma+s)^{-1/2} \frac{\dot{f}_1(u)}{f_1^{1/2}(u)}(u^2 - \kappa(f_1)) \right\}^2 (\sigma+s) du.$$

Since, for $|x| < 1$, $(1+x)^{1/2} = 1 + \frac{x}{2}(1+\lambda x)^{-1/2}$ for some $\lambda \in (0, 1)$, one easily obtains that

$$a_1 = \frac{r^2}{4} \int_{|u| < |z^*|} \left\{ (\sigma+s)^{-1/2} \frac{\dot{f}_1(u)}{f_1^{1/2}(u)}(u^2 - \kappa(f_1)) \left((1 + \lambda r \phi_{f_1}(u)(u^2 - \kappa(f_1)))^{-1/2} - 1 \right) \right\}^2 (\sigma+s) du.$$

For $|u| < 1$, one has $(1 - (1 + \lambda u)^{-1/2})^2 \leq 2\frac{2-\lambda}{1-\lambda}$, and the integrand is bounded by

$$2\frac{2-\lambda}{1-\lambda}(u^2 - \kappa(f_1))^2 \left(\frac{\dot{f}_1^{1/2}(u)}{f_1^{1/2}(u)} \right)^2,$$

which is square-integrable; the Lebesgue dominated convergence theorem thus implies that a_1 is $o(r^2)$. Turning to a_2 , we have that $a_2 \leq C((\sigma + s)^{-1}a_{21} + a_{22})$, where

$$a_{21} := \int_{u>|z^*|} f_1(u) du \quad \text{and} \quad a_{22} := \frac{r^2}{4} \int_{u>|z^*|} \left(\frac{\dot{f}_1(u)}{f_1^{1/2}(u)} \right)^2 (u^2 - \kappa(f_1))^2 du$$

The definition of \mathcal{F}_1 implies that $a_{21} = O((z^*)^{-\beta})$, hence that $a_{21} = o(r^2)$ if $r(z^*)^{\beta/2} \rightarrow \infty$ as $r \rightarrow 0$. This latter condition holds, since $\phi_{f_1}(z) = o(z^{\beta/2-2})$ and since the definition of z^* entails that

$$-1 = r(z^*)^{\beta/2} \frac{\phi_{f_1}(z^*)}{z^{*(\beta/2-2)}} \frac{(z^{*2} - \kappa(f_1))}{z^{*2}}.$$

An application of the Lebesgue dominated convergence theorem again yields $a_{22} = o(r^2)$.

(ii) This is a particular case of Lemma A.1 in Hallin and Paindaveine (2006) (here in a simpler univariate context).

(iii) The fact that $D_\xi g_{\theta, \sigma, \xi; f_1}^{1/2}(x)|_{\xi=0}$ is square integrable implies that

$$\|D_\xi g_{\theta+t, \sigma, \xi; f_1}^{1/2}(x)|_{\xi=0} - D_\xi g_{\theta, \sigma, \xi; f_1}^{1/2}(x)|_{\xi=0}\|_{L^2} = o(1)$$

as t tends to zero. Define $f_{1;\text{exp}}(x) := f_1(e^x)$ and $(f_{1;\text{exp}}^{1/2}(x))' := \frac{1}{2}f_1^{-1/2}(e^x)\dot{f}_1(e^x)e^x$. For the perturbation of σ , we have

$$\begin{aligned} & \int \left\{ \left(D_\xi g_{\theta, \sigma+s, \xi; f_1}^{1/2}(x)|_{\xi=0} - D_\xi g_{\theta, \sigma, \xi; f_1}^{1/2}(x)|_{\xi=0} \right) \right\}^2 dx \\ &= 2\sigma \int_0^\infty \left| \sigma^{-1/2} z \left(\left(1 + \frac{s}{\sigma}\right)^{-3/2} (f_{1;\text{exp}}^{1/2})'(\ln(z) - \ln(1 + \frac{s}{\sigma})) - (f_{1;\text{exp}}^{1/2})'(\ln(z)) \right) \right. \\ & \quad \left. - \sigma^{-1/2} z^{-1} \kappa(f_1) \left(\left(1 + \frac{s}{\sigma}\right)^{1/2} (f_{1;\text{exp}}^{1/2})'(\ln(z) - \ln(1 + \frac{s}{\sigma})) + (f_{1;\text{exp}}^{1/2})'(\ln(z)) \right) \right|^2 dz \\ &\leq C(c_1 + c_2), \end{aligned}$$

where

$$c_1 = \int_{-\infty}^\infty \left(e^{\frac{3}{2}(u - \ln(1 + \frac{s}{\sigma}))} (f_{1;\text{exp}}^{1/2})'(u - \ln(1 + \frac{s}{\sigma})) - e^{\frac{3}{2}u} (f_{1;\text{exp}}^{1/2})'(u) \right)^2 du$$

and

$$c_2 = \int_{-\infty}^\infty \left(e^{\frac{-1}{2}(u - \ln(1 + \frac{s}{\sigma}))} (f_{1;\text{exp}}^{1/2})'(u - \ln(1 + \frac{s}{\sigma})) - e^{\frac{-1}{2}u} (f_{1;\text{exp}}^{1/2})'(u) \right)^2 du.$$

Now, both $e^{\frac{-1}{2}u} (f_{1;\text{exp}}^{1/2})'(u)$ and $e^{\frac{3}{2}u} (f_{1;\text{exp}}^{1/2})'(u)$ are square-integrable since $f_1 \in \mathcal{F}_1$. Therefore, quadratic mean continuity implies that c_1 and c_2 are $o(1)$ when $s \rightarrow 0$.

(iv) The left-hand side in (iv) is bounded by $C(b_1 + b_2 + b_3)$, where

$$b_1 = \int \left\{ g_{\theta+t, \sigma+s, r; f_1}^{1/2}(x) - g_{\theta+t, \sigma+s, 0; f_1}^{1/2}(x) - r D_\xi g_{\theta+t, \sigma+s, \xi; f_1}^{1/2}(x) \right\}^2 dx,$$

$$b_2 = \int \left\{ g_{\theta+t, \sigma+s, 0; f_1}^{1/2}(x) - g_{\theta, \sigma, 0; f_1}^{1/2}(x) - (t, s) \begin{pmatrix} D_{\theta} g_{\theta, \sigma, 0; f_1}^{1/2}(x) \\ D_{\sigma} g_{\theta, \sigma, 0; f_1}^{1/2}(x) \end{pmatrix} \right\}^2 dx,$$

and

$$b_3 = \int \left\{ r \left(D_{\xi} g_{\theta+t, \sigma+s, \xi; f_1}^{1/2}(x) - D_{\xi} g_{\theta, \sigma, \xi; f_1}^{1/2}(x) \right) \right\}^2 dx.$$

The result then follows from (i), (ii) and (iii). \square

6.2 Asymptotic linearity.

6.2.1 Asymptotic linearity of $\Delta_{f_1;3}^{(n)}$.

The asymptotic linearity of $\Delta_{f_1;3}^{(n)}$ is required in the construction of the optimal parametric test of Section 3.2.2. Note that the proof below needs uniform local asymptotic normality in θ and σ only.

Proposition 6.1 *Let $f_1 \in \mathcal{F}_1$ and $g_1 \in \mathcal{F}_{f_1}$. Then, under $P_{\theta, \sigma, 0; g_1}^{(n)}$, as $n \rightarrow \infty$,*

(i) $\Delta_{f_1;3}^{(n)}(\theta + n^{-1/2}t, \sigma, 0) = \Delta_{f_1;3}^{(n)}(\theta, \sigma, 0) - t\sigma^{-1}(\mathcal{J}_{g_1}(f_1, g_1) - \kappa(f_1)\mathcal{I}_{g_1}(f_1, g_1)) + o_P(1)$ for all $t \in \mathbb{R}$, and

(ii) $\Delta_{f_1;3}^{(n)}(\theta, \sigma + n^{-1/2}s, 0) = \Delta_{f_1;3}^{(n)}(\theta, \sigma, 0) + o_P(1)$ for all $s \in \mathbb{R}$.

Proof. Define

$$D_{f_1;3}^{(n)}(\theta, \sigma) := n^{-1/2} \sum_{i=1}^n \phi_{f_1}(Z_i^{(n)}(\theta, \sigma))(Z_i^{(n)}(\theta, \sigma))^2.$$

Letting $K_{f_1}(u) := \phi_{f_1}(G_{1+}^{-1}(u)) (G_{1+}^{-1}(u))^2$, note that

$$D_{f_1;3}^{(n)}(\theta, \sigma, 0) = n^{-1/2} \sum_{i=1}^n s_i(\theta) K_{f_1}(G_{1+}(|Z_i^{(n)}(\theta, \sigma)|)).$$

Writing $\theta^{(n)}$ for $\theta + n^{-1/2}t$, $Z_i^{(n)}$ for $Z_i^{(n)}(\theta, \sigma)$, $s_i^{(n)}$ for $\text{sign}(Z_i^{(n)})$, $Z_{i;n}^{(n)}$ for $Z_i^{(n)}(\theta^{(n)}, \sigma)$ and $s_{i;n}^{(n)}$ for $\text{sign}(Z_{i;n}^{(n)})$, we show that

$$n^{-1/2} \sum_{i=1}^n s_{i;n}^{(n)} K_{f_1}(G_{1+}(|Z_{i;n}^{(n)}|)) - n^{-1/2} \sum_{i=1}^n s_i^{(n)} K_{f_1}(G_{1+}(|Z_i^{(n)}|)) + t\sigma^{-1} \mathcal{J}_{g_1}(f_1, g_1)$$

is $o_P(1)$; the proof of (ii) and that of

$$n^{-1/2} \sum_{i=1}^n \phi_{f_1}(Z_{i;n}^{(n)}) = n^{-1/2} \sum_{i=1}^n \phi_{f_1}(Z_i^{(n)}) - t\sigma^{-1} \mathcal{I}_{g_1}(f_1, g_1) + o_P(1)$$

are derived along the same lines and are therefore left to the reader. Let

$$\begin{aligned} K_{f_1}^{(l)}(u) &:= K_{f_1}\left(\frac{2}{l}\right)l\left(u - \frac{1}{l}\right)I\left[\frac{1}{l} < u \leq \frac{2}{l}\right] + K_{f_1}(u)I\left[\frac{2}{l} < u \leq 1 - \frac{2}{l}\right] \\ &\quad + K_{f_1}\left(1 - \frac{2}{l}\right)l\left(\left(1 - \frac{1}{l}\right) - u\right)I\left[1 - \frac{2}{l} < u \leq 1 - \frac{1}{l}\right]. \end{aligned}$$

Continuity of $u \mapsto K_{f_1}(u)$ implies continuity of $u \mapsto K_{f_1}^{(l)}(u)$ on the interval $]0, 1[$. Moreover, since this function is compactly supported, it is bounded, for any (sufficiently large) $l \in \mathbb{N}_0$, by the monotone increasing function $u \mapsto K_{f_1}(u)$. Let \mathbb{E}_0 denote expectation under $\mathbb{P}_{\theta, \sigma, 0; g_1}^{(n)}$. One shows easily that $D_{f_1; 3}^{(n)}(\theta, \sigma)$ decomposes into $D_1^{(n, m)} + D_2^{(n, m)} - R_1^{(n, m)} + R_2^{(n, m)} + R_3^{(m)}$, with $\mathcal{J}_{g_1}^{(l)}(f_1, g_1) := \int_0^1 K_{f_1}^{(l)}(u) \phi_{g_1}(G_1^{-1}(u)) du$,

$$\begin{aligned} D_1^{(n, l)} &= n^{-1/2} \sum_{i=1}^n s_{i;n} K_{f_1}^{(l)}(G_{1+}|Z_{i;n}^{(n)}|) - n^{-1/2} \sum_{i=1}^n s_i K_{f_1}^{(l)}(G_{1+}|Z_i^{(n)}|) - n^{1/2} \mathbb{E}_0[s_{i;n} K_{f_1}^{(l)}(G_{1+}|Z_{i;n}^{(n)}|)], \\ D_2^{(n, l)} &= n^{1/2} \mathbb{E}_0[s_{i;n} K_{f_1}^{(l)}(G_{1+}|Z_{i;n}^{(n)}|)] + t\sigma^{-1} \mathcal{J}_{g_1}^{(l)}(f_1, g_1), \\ R_1^{(n, l)} &= n^{-1/2} \sum_{i=1}^n s_i (K_{f_1}(G_{1+}|Z_i^{(n)}|) - K_{f_1}^{(l)}(G_{1+}|Z_i^{(n)}|)), \\ R_2^{(n, l)} &= n^{-1/2} \sum_{i=1}^n s_{i;n} (K_{f_1}(G_{1+}|Z_{i;n}^{(n)}|) - K_{f_1}^{(l)}(G_{1+}|Z_{i;n}^{(n)}|)), \end{aligned}$$

and

$$R_3^{(l)} = t\sigma^{-1} (\mathcal{J}_{g_1}(f_1, g_1) - \mathcal{J}_{g_1}^{(l)}(f_1, g_1)).$$

In order to conclude, we prove that $D_1^{(n, l)}$ and $D_2^{(n, l)}$ are $o_{\mathbb{P}}(1)$ under $\mathbb{P}_{\theta, \sigma, 0; g_1}^{(n)}$, as $n \rightarrow \infty$, for fixed l , and that $R_1^{(n, l)}$, $R_2^{(n, l)}$ and $R_3^{(l)}$ are $o_{\mathbb{P}}(1)$ under the same sequence of hypotheses, as $l \rightarrow \infty$, uniformly in n . For the sake of convenience, these three results are treated separately (Lemmas 6.2, 6.3 and 6.4).

Lemma 6.2 *For any fixed l , $D_1^{(n, l)} = o_{\mathbb{P}}(1)$ as $n \rightarrow \infty$, under $\mathbb{P}_{\theta, \sigma, 0; g_1}^{(n)}$.*

Lemma 6.3 *For any fixed l , $D_2^{(n, l)} = o_{\mathbb{P}}(1)$ as $n \rightarrow \infty$, under $\mathbb{P}_{\theta, \sigma, 0; g_1}^{(n)}$.*

Lemma 6.4 (i) *Under $\mathbb{P}_{\theta, \sigma, 0; g_1}^{(n)}$, $R_1^{(n, l)} = o_{\mathbb{P}}(1)$ as $l \rightarrow \infty$, uniformly in n ,*

(ii) *$R_2^{(n, l)} = o_{\mathbb{P}}(1)$ as $l \rightarrow \infty$, under $\mathbb{P}_{\theta, \sigma, 0; g_1}^{(n)}$ (for n sufficiently large), uniformly in n , and*

(iii) *$R_3^{(l)}$ is $o(1)$ as $l \rightarrow \infty$.*

Proof of Lemma 6.2. Consider the i.i.d. variables $T_i^{(n, l)} := s_{i;n} K_{f_1}^{(l)}(G_{1+}|Z_{i;n}^{(n)}|) - s_i K_{f_1}^{(l)}(G_{1+}|Z_i^{(n)}|)$. One easily verifies that $D_1^{(n, l)} = n^{-1/2} \sum_{i=1}^n (T_i^{(n, l)} - \mathbb{E}_0[T_i^{(n, l)}])$. Writing Var_0 for variances under $\mathbb{P}_{\theta, \sigma, 0; g_1}^{(n)}$, we have that

$$\begin{aligned} \mathbb{E}_0(D_1^{(n, l)}) &\leq n^{-1} \mathbb{E}_0[(\sum_{i=1}^n (T_i^{(n, l)} - \mathbb{E}_0[T_i^{(n, l)}]))^2] \\ &\leq n^{-1} \text{Var}_0[\sum_{i=1}^n (T_i^{(n, l)} - \mathbb{E}_0[T_i^{(n, l)}])] = \text{Var}_0[T_i^{(n, l)}] \leq \mathbb{E}_0[(T_i^{(n, l)})^2] \end{aligned}$$

and it only remains to show that

$$\mathbb{E}_0[(T_i^{(n, l)})^2] = \mathbb{E}_0[(s_{i;n} K_{f_1}^{(l)}(G_{1+}|Z_{i;n}^{(n)}|) - s_i K_{f_1}^{(l)}(G_{1+}|Z_i^{(n)}|))^2] = o(1)$$

as $n \rightarrow \infty$. Now,

$$\begin{aligned} & (s_{i;n}K_{f_1}^{(l)}(G_{1+}|Z_{i;n}^{(n)}|) - s_iK_{f_1}^{(l)}(G_{1+}|Z_i^{(n)}|))^2 \\ &= (s_{i;n}K_{f_1}^{(l)}(G_{1+}|Z_{i;n}^{(n)}|) - s_{i;n}K_{f_1}^{(l)}(G_{1+}|Z_i^{(n)}|) + s_{i;n}K_{f_1}^{(l)}(G_{1+}|Z_i^{(n)}|) - s_iK_{f_1}^{(l)}(G_{1+}|Z_i^{(n)}|))^2 \\ &\leq 2(K_{f_1}^{(l)}(G_{1+}|Z_{i;n}^{(n)}|) - K_{f_1}^{(l)}(G_{1+}|Z_i^{(n)}|))^2 + 2(K_{f_1}^{(l)}(G_{1+}|Z_i^{(n)}|))^2(s_{i;n} - s_i)^2. \end{aligned}$$

Because $u \mapsto K_{f_1}^{(l)}(u)$ is continuous and $|Z_{i;n}^{(n)} - Z_i^{(n)}|$ is $o_P(1)$, $K_{f_1}^{(l)}(G_{1+}|Z_{i;n}^{(n)}|) - K_{f_1}^{(l)}(G_{1+}|Z_i^{(n)}|)$ also is $o_P(1)$. Moreover, since $K_{f_1}^{(l)}$ is bounded, this convergence to zero also holds in quadratic mean. Similarly, $K_{f_1}^{(l)}(G_{1+}|Z_i^{(n)}|)(s_{i;n} - s_i) = o_P(1)$ since $K_{f_1}^{(l)}(G_{1+}|Z_i^{(n)}|)$ is bounded and $|s_{i;n} - s_i|$ is $o_P(1)$. Finally, both $s_{i;n}$ and s_i are bounded, implying that this convergence to zero also holds in quadratic mean. \square

Proof of Lemma 6.3. Let $B_1^{(n,l)} := n^{-1/2} \sum_{i=1}^n s_i K_{f_1}^{(l)}(G_{1+}(|Z_i^{(n)}|))$. As $n \rightarrow \infty$, under $P_{\theta,\sigma,0;g_1}^{(n)}$, $B_1^{(n,l)}$ is asymptotically $\mathcal{N}(0, E[(K_{f_1}^{(l)}(U))^2])$, where U stands for a random variable uniformly distributed over the unit interval. Also, letting $B_2^{(n,l)} := n^{-1/2} \sum_{i=1}^n s_{i;n} K_{f_1}^{(l)}(G_{1+}|Z_{i;n}^{(n)}|)$, it follows from ULAN that $B_2^{(n,l)} - t\sigma^{-1} \mathcal{J}_{g_1}^{(l)}(f_1, g_1)$ is asymptotically $\mathcal{N}(0, E[(K_{f_1}^{(l)}(U))^2])$ as $n \rightarrow \infty$, under $P_{\theta,\sigma,0;g_1}^{(n)}$. Since $D_1^{(n,l)} = B_2^{(n,l)} - B_1^{(n,l)} - E_0[B_2^{(n,l)}] = o_P(1)$, we have that $B_2^{(n,l)} - E_0[B_2^{(n,l)}]$ is asymptotically $\mathcal{N}(0, E[(K_{f_1}^{(l)}(U))^2])$ as $n \rightarrow \infty$, under $P_{\theta,\sigma,0;g_1}^{(n)}$. Therefore, still as $n \rightarrow \infty$, $D_2^{(n,l)} = E_0[B_2^{(n,l)}] - t\sigma^{-1} \mathcal{J}_{g_1}^{(l)}(f_1, g_1) = o(1)$. \square

Proof of Lemma 6.4. (i) We have that

$$\begin{aligned} E_0 \left[\left(R_1^{(n,l)} \right)^2 \right] &\leq CE_0 \left[\left(K_{f_1}^{(l)}(G_{1+}|Z_i^{(n)}|) - K_{f_1}^{(l)}(G_{1+}|Z_i^{(n)}|) \right)^2 \right] \\ &= C \int_{-\infty}^{\infty} \left(K_{f_1}^{(l)}(u) - K_{f_1}^{(l)}(u) \right)^2 du; \end{aligned}$$

for any $u \in]0, 1[$, $K_{f_1}^{(l)}(u)$ converges to $K_{f_1}(u)$ and the integrand is bounded (uniformly in l) by $4(K_{f_1}(u))^2$, which is integrable on $]0, 1[$. The Lebesgue dominated convergence theorem implies that $E_0[(R_1^{(n,l)})^2] = o(1)$ as $l \rightarrow \infty$, uniformly in n .

(ii) The claim here is the same as in (i), with $Z_{i;n}^{(n)}$ replacing $Z_i^{(n)}$. Accordingly, (ii) holds under $P_{\theta^{(n)}, \sigma, 0;g_1}^{(n)}$. That it also holds under $P_{\theta,\sigma,0;g_1}^{(n)}$ follows from Lemma 3.5 in Jurečková (1969).

(iii) Note that

$$\begin{aligned} \left| \mathcal{J}_{g_1}(f_1, g_1) - \mathcal{J}_{g_1}^{(l)}(f_1, g_1) \right|^2 &= \left| \int_0^1 \phi_{g_1}(G_1^{-1}(u))(K_{f_1}^{(l)}(u) - K_{f_1}(u)) du \right|^2 \\ &\leq \mathcal{I}(g_1) \int_0^1 ((K_{f_1}^{(l)}(u) - K_{f_1}(u))^2) du, \end{aligned}$$

where the integrand is bounded by $4(K_{f_1}(u))^2$, which is square-integrable. Pointwise convergence of $K_{f_1}^{(l)}(u)$ to $K_{f_1}(u)$ implies that $\mathcal{J}_{g_1}(f_1, g_1) - \mathcal{J}_{g_1}^{(l)}(f_1, g_1) = o(1)$ as $l \rightarrow \infty$. The result follows. \square

6.2.2 Substitution of $\Delta_{f_1;3}^{(n)}(\kappa^{(n)o}(f_1, \hat{\theta}_\#, \hat{\sigma}_\#), \hat{\theta}_\#, \hat{\sigma}_\#)$ for $\Delta_{f_1;3}^{(n)}(\kappa_{g_1}(f_1, g_1), \theta, \sigma)$.

Lemma 6.5 Let $f_1 \in \mathcal{F}_1^o$ and $g_1 \in \mathcal{F}_{f_1}^o$. Then, under $P_{\theta, \sigma, 0; g_1}^{(n)}$,

$$(i) \Delta_{f_1;3}^{(n)}(\kappa_{g_1}(f_1, g_1), \hat{\theta}_\#, \hat{\sigma}_\#) - \Delta_{f_1;3}^{(n)}(\kappa_{g_1}(f_1, g_1), \theta, \sigma) = o_P(1),$$

$$(ii) \Delta_{f_1;3}^{(n)}(\kappa^{(n)o}(f_1, \hat{\theta}_\#, \hat{\sigma}_\#), \hat{\theta}_\#, \hat{\sigma}_\#) - \Delta_{f_1;3}^{(n)}(\kappa_{g_1}(f_1, g_1), \hat{\theta}_\#, \hat{\sigma}_\#) = o_P(1), \text{ and}$$

$$(iii) \Delta_{f_1;3}^{(n)}(\kappa^{(n)o}(f_1, \hat{\theta}_\#, \hat{\sigma}_\#), \hat{\theta}_\#, \hat{\sigma}_\#) - \Delta_{f_1;3}^{(n)}(\kappa_{g_1}(f_1, g_1), \theta, \sigma) = o_P(1).$$

Proof. Part (i) is a direct consequence of Proposition 6.1. The left hand side in (ii) can be written as

$$T_1^{(n)} \times T_2^{(n)} := (\kappa^{(n)o}(f_1, \hat{\theta}_\#, \hat{\sigma}_\#) - \kappa_{g_1}(f_1, g_1)) \times n^{-1/2} \sum_{i=1}^n \phi_{f_1}(Z_i^{(n)}(\hat{\theta}_\#, \hat{\sigma}_\#)) \quad (6.18)$$

where $T_1^{(n)}$ is $o_P(1)$. Now, ULAN implies that

$$T_2^{(n)} = n^{-1/2} \sum_{i=1}^n \phi_{f_1}(Z_i^{(n)}(\theta, \sigma)) + (\sigma^{-1} \mathcal{I}_{g_1}(f_1, g_1) \ 0) n^{1/2} \left(\begin{pmatrix} \hat{\theta}_\# \\ \hat{\sigma}_\# \end{pmatrix} - \begin{pmatrix} \theta \\ \sigma \end{pmatrix} \right) + o_P(1), \quad (6.19)$$

as $n \rightarrow \infty$ under $P_{\theta, \sigma, 0; g_1}^{(n)}$. Hence, the central limit theorem and the root- n consistency of $\hat{\theta}_\#$ and $\hat{\sigma}_\#$ entail that (6.19) is $O_P(1)$; the result follows. As for (iii), it is a direct consequence of (i) and (ii). \square

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