# EFFECTIVE VISCOSITY OF RANDOM SUSPENSIONS WITHOUT UNIFORM SEPARATION

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ABSTRACT. This work is devoted to the definition and the analysis of the effective viscosity associated with a random suspension of small rigid particles in a steady Stokes fluid. While previous works on the topic have been conveniently assuming that particles are uniformly separated, we relax this restrictive assumption in form of mild moment bounds on interparticle distances.

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## 1. INTRODUCTION

Consider a colloidal suspension of small rigid particles in a Stokes fluid. Suspended particles act as obstacles, hindering the fluid flow and thus increasing the viscosity. In a recent contribution [10] with Gloria, we show in terms of homogenization theory that the suspension behaves at leading order like a Stokes fluid with some *effective* viscosity, and in [8] we establish optimal error estimates. In [7], we analyze the value of this effective viscosity in the low-density regime, in particular establishing the so-called Einstein formula and improving on several recent works on the topic [24, 15, 18, 17, 14]. In [9], we further investigate the collective sedimentation of suspended particles under gravity. In all those contributions, a crucial technical assumption is that particles are uniformly separated, which is necessary in various arguments, for instance when appealing to trace estimates and regularity theory at particle boundaries. This separation assumption is however unsatisfactory from the physical viewpoint, as it is incompatible with the steady-state behavior, e.g. [2, 1], and the present contribution aims at relaxing it as much as possible in form of mild inverse moment bounds on interparticle distances. We focus on the definition of the effective viscosity and on the qualitative homogenization result, and we further provide general tools that can be used to adapt some more advanced results; see e.g. [7, Section 2] and [17, Section 5] on the validity of Einstein's formula in the low-density regime without uniform separation.

In the case of smooth particles with some non-degeneracy condition, we essentially show in 3D that the effective viscosity is well-defined provided that  $\mathbb{E}\left[\rho^{-1}\right] < \infty$ , where  $\rho$  stands for the distance between two neighboring particles, and we prove qualitative homogenization under the stronger condition  $\mathbb{E}\left[\rho^{-3/2}\right] < \infty$ . Although likely optimal in a general stationary ergodic setting, these moment bounds on interparticle distances are still quite restrictive and unphysical, cf. [2, 1]. We may draw the link with the well-known paradox of absence of solid-solid contacts in a 3D Stokes flow, which is related to flaws in the modeling: real-life solid particles are slightly elastic, their boundary display some roughness, and no-slip boundary conditions are not exactly valid; see e.g. [16] and references therein. Such corrections are not considered in the present contribution and we rather provide a detailed analysis of the ideal Stokes model. In [6], with Gloria, we investigate another line of research: under suitable mixing conditions, large clusters of close particles are unlikely in view of subcritical percolation, which can be exploited to prove homogenization without any condition on interparticle distances. Finer geometric information might also be used in the spirit of [19].

Our approach in this contribution is mainly inspired by the work of Jikov [20, 21] on the homogenization problem for scalar elliptic equations with stiff inclusions; see also [22, Section 8.6]. In that scalar setting, however, required moment bounds on interparticle distances are much milder and only logarithmic moments are required in 3D. We emphasize two main differences:

- First, and most importantly, the incompressibility constraint in the present Stokes problem brings important rigidity and leads to completely different scalings. This is easily understood by noting that the incompressibility constraint can be eliminated by writing the Stokes equations as *fourth-order* elliptic equations on the vector potential; see e.g. [12]. As in [16], spatial cut-offs in this situation are then naturally to be performed on the vector potential, so that one derivative of cut-off functions is lost with respect to scalar and compressible settings, which explains the different scalings; see the proof of Proposition 3.1.
- Second, the vectorial character of the Stokes problem prohibits the use of scalar truncations: in contrast with e.g. [22, Section 8.6], this forces us to appeal to the Sobolev embedding and further deteriorates the required moment conditions.

We note some similarities with the homogenization problem for elliptic systems with degenerate random coefficients, e.g. [5, 3, 11, 4], where similar inverse moment conditions are required on coefficients.

Before stating our main results, we close this introduction by recalling the formulation of the Stokes model for a viscous fluid in presence of a random suspension of small rigid particles, e.g. [10]. We denote by  $d \ge 2$  the space dimension, and we consider a random ensemble of particles  $\mathcal{I} = \bigcup_n I_n \subset \mathbb{R}^d$ . Stationarity, ergodicity, and regularity assumptions are postponed to Section 2. In order to model a dense suspension of small particles, we rescale the random set  $\mathcal{I}$  by a small parameter  $\varepsilon > 0$  and consider  $\varepsilon \mathcal{I} = \bigcup_n \varepsilon I_n$ . We then view these small particles  $\{\varepsilon I_n\}_n$  as suspended in a solvent described by the steady Stokes equation: in a reference domain  $U \subset \mathbb{R}^d$ , given an internal force  $f \in L^2(U)^d$ , the fluid velocity  $u_{\varepsilon} \in H^1(U \setminus \varepsilon \mathcal{I})^d$  satisfies

$$-\Delta u_{\varepsilon} + \nabla S_{\varepsilon} = f, \qquad \operatorname{div}(u_{\varepsilon}) = 0, \qquad \operatorname{in} U \setminus \varepsilon \mathcal{I}, \tag{1.1}$$

with  $u_{\varepsilon} = 0$  on  $\partial U$ . (We implicitly assume here that no particle intersects the boundary.) The pressure field is only defined up to an additive constant and we choose  $S_{\varepsilon} \in L^1(U \setminus \varepsilon \mathcal{I})$ with  $\int_{U \setminus \varepsilon \mathcal{I}} S_{\varepsilon} = 0$ . Next, no-slip boundary conditions are imposed at particle boundaries: since particles are constrained to have rigid motions, this amounts to letting the velocity field  $u_{\varepsilon}$  be extended inside particles,  $u_{\varepsilon} \in H^1(U)^d$ , with the rigidity constraint

$$D(u_{\varepsilon}) = 0, \qquad \text{in } \varepsilon \mathcal{I}, \tag{1.2}$$

where  $D(u_{\varepsilon})$  stands for the symmetric gradient of  $u_{\varepsilon}$ . In other words, this condition means that the velocity field  $u_{\varepsilon}$  coincides with a rigid motion  $x \mapsto V_{\varepsilon,n} + \Theta_{\varepsilon,n} x$  inside each particle  $\varepsilon I_n$ , for some  $V_{\varepsilon,n} \in \mathbb{R}^d$  and some skew-symmetric matrix  $\Theta_{\varepsilon,n} \in \mathbb{R}^{d \times d}$ . Finally, assuming that the particles have the same mass density as the fluid, or in the absence of gravity, buoyancy forces vanish, and the force and torque balances on each particle take the form

$$\int_{\varepsilon \partial I_n} \sigma(u_\varepsilon, S_\varepsilon) \nu = 0, \tag{1.3}$$

$$\int_{\varepsilon \partial I_n} \Theta x \cdot \sigma(u_\varepsilon, S_\varepsilon) \nu = 0, \quad \text{for all skew-symmetric } \Theta \in \mathbb{R}^{d \times d}, \tag{1.4}$$

where  $\sigma(u_{\varepsilon}, S_{\varepsilon})$  is the Cauchy stress tensor

$$\sigma(u_{\varepsilon}, S_{\varepsilon}) = 2 \operatorname{D}(u_{\varepsilon}) - S_{\varepsilon} \operatorname{Id}, \qquad (1.5)$$

and where  $\nu$  stands for the outward unit normal vector at the particle boundaries. These equations (1.1)–(1.5) have the following weak formulation,

$$2\int_{U} \mathcal{D}(g) : \mathcal{D}(u_{\varepsilon}) = \int_{U} g \cdot f, \qquad \forall g \in C_{c}^{1}(U)^{d} : \operatorname{div}(g) = 0, \ \mathcal{D}(g)|_{\varepsilon \mathcal{I}} = 0.$$

This Stokes problem can also be viewed as a model for incompressible linear elasticity with stiff inclusions.

## Notation.

- For vector fields u, u' and matrix fields T, T', we set  $(\nabla u)_{ij} = \nabla_j u_i$ , div $(T) = \nabla_j T_{ij}$ ,  $T : T' = T_{ij}T'_{ij}$ ,  $(u \otimes u')_{ij} = u_i u'_j$ , where we systematically use Einstein's summation convention on repeated indices. For a matrix E, we write  $\nabla_E u = E : \nabla u$ .
- For a velocity field u and pressure field S, we denote by  $(D(u))_{ij} = \frac{1}{2}(\nabla_j u_i + \nabla_i u_j)$  the symmetric gradient and by  $\sigma(u, S) = 2 D(u) S$  Id the Cauchy stress tensor. At particle boundaries, we let  $\nu$  denote the outward unit normal vector.
- We denote by  $\mathbb{M}^{\text{sym}} \subset \mathbb{R}^{d \times d}$  the subset of symmetric matrices, by  $\mathbb{M}_0^{\text{sym}}$  the subset of symmetric trace-free matrices, and by  $\mathbb{M}^{\text{skew}}$  the subset of skew-symmetric matrices. We also write  $L^p(\mathbb{R}^d)_{\text{sym}}^{d \times d} = L^p(\mathbb{R}^d; \mathbb{M}^{\text{sym}})$ .
- We denote by  $C \ge 1$  any constant than only depends on the dimension d, on the reference domain U, and on the parameters appearing in the different assumptions (in particular on  $\delta$  in  $(\mathbf{H}^{\circ}_{\delta})-(\mathbf{H}'_{\delta})$  below). The value of the constant C is allowed to change from one line to another. We use the notation  $\lesssim$  (resp.  $\gtrsim$ ) for  $\leq C \times$  (resp.  $\geq \frac{1}{C} \times$ ) up to such a multiplicative constant C. We add subscripts to  $C, \lesssim, \gtrsim$  to indicate dependence on other parameters.
- The ball centered at x of radius r in  $\mathbb{R}^d$  is denoted by  $B_r(x)$ , and we simply write  $B(x) = B_1(x), B_r = B_r(0)$ , and  $B = B_1(0)$ .

### 2. Main results

We focus on the case d > 2 for the statement of the main results, while the 2D case has some important difference and is briefly discussed in Remark 3.4.

2.1. Assumptions. We start with the construction and suitable assumptions on the random ensemble of particles. Given an underlying probability space  $(\Omega, \mathcal{A}, \mathbb{P})$ , let  $\mathcal{P} = \{x_n\}_n$ be a random point process on  $\mathbb{R}^d$ , with a given enumeration, consider a collection of random shapes  $\{I_n^o\}_n$ , where each  $I_n^o$  is a connected random Borel subset of the unit ball  $B,^1$ and define the corresponding random inclusions  $I_n := x_n + I_n^o$ . We then consider the random set  $\mathcal{I} := \bigcup_n I_n$ , which is assumed to satisfy the following general conditions, for some deterministic constant  $\delta > 0$ .

Assumption  $(\mathbf{H}^{\circ}_{\delta})$  — General conditions.

- Stationarity and ergodicity: The point process  $\mathcal{P} = \{x_n\}_n$  and the associated random set  $\mathcal{I}$  are stationary and ergodic.<sup>2</sup>
- Uniform C<sup>2</sup> regularity: Random shapes {I<sub>n</sub><sup>o</sup>}<sub>n</sub> almost surely satisfy interior and exterior ball conditions with radius δ.
- Hardcore condition: There holds  $\overline{I}_n \cap \overline{I}_m = \emptyset$  almost surely for all  $n \neq m$ .

When particles are close, not only their distance matters, but also the order of their quasi-contact. We therefore need to refine the above hardcore condition, and we focus on the case of smooth particles with uniformly non-osculating boundaries. This is expressed below in form of some "parabolic" version of a cone condition. While always satisfied in case of spherical particles, this excludes for instance the case of particles that would almost touch on flat components, as it would correspond to a contact of infinite order; see Figures 1-2 below. Note that our analysis is easily adapted to intermediate situations with contacts of any fixed order: this would lead to stronger moment conditions on interparticle distances and is not pursued here.

Before we actually state relevant geometric conditions, we need to introduce some further notation. First, we construct neighborhoods  $\{I_n^+\}_n$  of the particles  $\{I_n\}_n$  in form of truncated Voronoi cells,

$$I_n^+ := (I_n + B_\delta) \cap \left\{ x \in \mathbb{R}^d : \operatorname{dist}(x, I_n) < \inf_{m: m \neq n} \operatorname{dist}(x, I_m) \right\}.$$
 (2.1)

In view of the uniform  $C^2$  regularity of the particles, cf.  $(\mathbf{H}^{\circ}_{\delta})$ , it is easily checked that these neighborhoods  $\{I_n^+\}_n$  are uniformly Lipschitz (with Lipschitz constant bounded by  $C/\delta$ ). Next, we define "model" parabolic domains that are enclosed by close paraboloids with different radii: given a distance  $\rho \geq 0$  and radii  $a_2 > a_1 > 0$ , we set

$$\Gamma_{a_1,a_2}^+(\rho) := B_{\delta} \cap \left\{ (x_1, x') \in \mathbb{R} \times \mathbb{R}^{d-1} : -\rho + \frac{1}{a_2} |x'|^2 < x_1 < \frac{1}{a_1} |x'|^2 \right\}, 
\Gamma_{a_1,a_2}^-(\rho) := B_{\delta} \cap \left\{ (x_1, x') \in \mathbb{R} \times \mathbb{R}^{d-1} : -\rho - \frac{1}{a_1} |x'|^2 < x_1 < -\frac{1}{a_2} |x'|^2 \right\},$$
(2.2)

<sup>1</sup>Letting  $\mathcal{B}(\mathbb{R}^d)$  denote the Borel  $\sigma$ -algebra on  $\mathbb{R}^d$ , we recall that a map  $I^{\circ}: \Omega \to \mathcal{B}(\mathbb{R}^d): \omega \mapsto I^{\circ}(\omega)$  is a random Borel subset of  $\mathbb{R}^d$  if the set  $\{(\omega, x): \omega \in \Omega, x \in I^{\circ}(\omega)\}$  belongs to the product  $\sigma$ -algebra  $\mathcal{A} \times \mathcal{B}(\mathbb{R}^d)$ , or alternatively if the indicator function  $\mathbb{1}_{I^{\circ}}$  is  $(\mathcal{A} \times \mathcal{B}(\mathbb{R}^d))$ -measurable on  $\Omega \times \mathbb{R}^d$ .

<sup>&</sup>lt;sup>2</sup>Stationarity means that the laws of the translated point process  $x + \mathcal{P}$  and of the translated random Borel set  $x + \mathcal{I}$  do not depend of the shift  $x \in \mathbb{R}^d$ . Ergodicity then means that, if a measurable function of  $\mathcal{P}$  or  $\mathcal{I}$  is almost surely unchanged when  $\mathcal{P}$  or  $\mathcal{I}$  is replaced by  $x + \mathcal{P}$  or  $x + \mathcal{I}$  for any  $x \in \mathbb{R}^d$ , then the function is almost surely constant.



FIGURE 1. This displays a configuration with close particles satisfying Assumption  $(H'_{\delta})$ . Disjoint neighborhoods  $\{I_n^+\}_n$  are represented as light gray areas around the particles. The zooms on the neighborhoods of quasicontact points show that particle boundaries are not osculating, as prescribed by Assumption  $(H'_{\delta})$ , with parabolic domains delimited by dotted lines.



FIGURE 2. This displays examples of configurations of close particles that are forbidden by Assumption  $(H'_{\delta})$  as their boundaries are osculating to infinite order.

In these terms, we formulate the following geometric condition, for some deterministic constant  $\delta > 0$ . It states that such parabolic domains can be included in the interparticle spacing  $I_n^+ \setminus I_n$  in the neighborhood of quasi-contact points, and the condition  $\frac{1}{a_1} - \frac{1}{a_2} \ge \delta$  means that paraboloids can be chosen to be  $\delta$ -uniformly not osculating; see Figures 1–2.

Assumption  $(\mathbf{H}'_{\delta})$  — Uniform non-degeneracy of contact points. For all n, for all  $x \in \partial I_n$ , there exists  $0 \leq \rho \leq \delta$ , there exist radii  $a_2 > a_1 \geq \delta$ with  $\frac{1}{a_1} - \frac{1}{a_2} \geq \delta$ , and there exists a rotation  $Q \in O(d)$ , such that the rotated parabolic domain  $x + Q\Gamma^+_{a_1,a_2}(\rho)$  or  $x + Q\Gamma^-_{a_1,a_2}(\rho)$  is contained in  $I^+_n \setminus I_n$ .

Finally, we turn to assumptions on interparticle distances. For all n, the (half) interparticle distance from  $I_n$  is given by

$$\rho_n^{\circ} := \min_{m:m \neq n} \frac{1}{2} \operatorname{dist}(I_n, I_m).$$
(2.3)

While previous works on the Stokes model (1.1)–(1.5) have focused on the convenient case of uniformly separated particles, that is,  $\inf_n \rho_n^{\circ} > 0$ , the present contribution aims at showing that this can be substantially weakened in form of mild inverse moment bounds. For that purpose, under Assumption  $(\mathbf{H}_{\delta})$ , we first need to introduce a better suited notion of interparticle distance  $\rho_n \leq \rho_n^{\circ}$ : for all  $x \in \partial I_n$ , we let  $\rho_n(x)$  denote the supremum of the admissible choices of  $\rho$  in  $(\mathbf{H}_{\delta})$ , and we then define

$$\rho_n := \inf_{x \in \partial I_n} \rho_n(x). \tag{2.4}$$

2.2. Construction of correctors. We start with the definition of correctors for the Stokes problem (1.1)–(1.5), thus adapting [10, Proposition 2.1] to the present setting without uniform particle separation. The proof relies on the construction of a suitable admissible test function for the variational problem (2.6) below, and we believe that the moment condition (2.5) is optimal in general. As is shown in the proof, existence and uniqueness of the corrector  $\psi_E$  also hold under (2.5) with  $\eta = 0$ , but existence of a stationary pressure field is based on a weak compactness argument in  $L^{1+}(\Omega)$  and therefore requires  $\eta > 0$ . Contacts between particles are allowed in dimension d > 5 as no moment condition is required in that case.

**Theorem 1** (Correctors). Let d > 2. On top of Assumptions  $(H^{\circ}_{\delta})$  and  $(H'_{\delta})$ , assume that interparticle distances  $\{\rho_n\}_n$ , cf. (2.4), satisfy the following moment condition, for some  $\eta > 0$ ,

$$\begin{aligned} & \text{for } d < 5 \quad : \quad \sum_{n} \mathbb{E} \left[ \rho_{n}^{-\frac{3-a}{2}-\eta} \mathbb{1}_{0 \in I_{n}} \right] & < \infty, \\ & \text{for } d = 5 \quad : \quad \sum_{n} \mathbb{E} \left[ |\log \rho_{n}|^{1+\eta} \mathbb{1}_{0 \in I_{n}} \right] & < \infty, \end{aligned}$$

while no moment condition is required in dimension d > 5. Then, for all  $E \in \mathbb{M}_0^{\text{sym}}$ , there exists a unique minimizer  $D(\psi_E)$  of the variational problem

$$\inf \left\{ \mathbb{E} \left[ |\mathbf{D}(\psi) + E|^2 \right] : \psi \in \mathbf{L}^2(\Omega; H^1_{\mathrm{loc}}(\mathbb{R}^d)^d), \nabla \psi \text{ stationary}, \\ \operatorname{div}(\psi) = 0, \ (\mathbf{D}(\psi) + E)|_{\mathcal{I}} = 0, \ \mathbb{E} \left[ \mathbf{D}(\psi) \right] = 0 \right\}, \quad (2.6)$$

and the minimum value defines a positive-definite symmetric linear map  $\bar{B}$  on  $\mathbb{M}_0^{\text{sym}}$ , which is the so-called effective viscosity,

$$E: \overline{B}E := \mathbb{E}\left[ |\mathbf{D}(\psi_E) + E|^2 \right].$$
(2.7)

Moreover, the minimizer  $D(\psi_E)$  can be characterized by the following PDE: there exist a unique random vector field  $\psi_E \in L^2(\Omega; H^1_{loc}(\mathbb{R}^d)^d)$ , with anchoring  $\int_B \psi_E = 0$ , and a unique associated pressure field  $\Sigma_E \in L^1(\Omega; L^1_{loc}(\mathbb{R}^d \setminus \mathcal{I}))$ , such that

• the following equations are almost surely satisfied in the strong sense,

$$\begin{cases} -\Delta \psi_E + \nabla \Sigma_E = 0, & \text{in } \mathbb{R}^d \setminus \mathcal{I}, \\ \operatorname{div}(\psi_E) = 0, & \operatorname{in } \mathbb{R}^d, \\ D(\psi_E + Ex) = 0, & \text{in } \mathcal{I}, \\ \int_{\partial I_n} \sigma(\psi_E + Ex, \Sigma_E)\nu = 0, & \forall n, \\ \int_{\partial I_n} \Theta(x - x_n) \cdot \sigma(\psi_E + Ex, \Sigma_E)\nu = 0, & \forall n, \forall \Theta \in \mathbb{M}^{\text{skew}}, \end{cases}$$
(2.8)

•  $\nabla \psi_E$  and  $\Sigma_E \mathbb{1}_{\mathbb{R}^d \setminus \mathcal{I}}$  are stationary, with the following estimates, for some  $\eta > 0$ ,

$$\begin{aligned} & \mathbb{E}[|\nabla\psi_E|^2] &\lesssim |E|^2, \qquad \mathbb{E}[\nabla\psi_E] &= 0, \\ & \mathbb{E}[|\Sigma_E|^{1+\eta}\mathbb{1}_{\mathbb{R}^d\setminus\mathcal{I}}] &\lesssim |E|^{1+\eta}, \qquad \mathbb{E}[\Sigma_E\mathbb{1}_{\mathbb{R}^d\setminus\mathcal{I}}] &= 0. \end{aligned}$$

In particular, the following convergences hold almost surely as  $\varepsilon \downarrow 0$ ,

$$\begin{aligned} (\nabla\psi_E)(\frac{\cdot}{\varepsilon}) &\rightharpoonup 0, & weakly & in \ \mathrm{L}^2_{\mathrm{loc}}(\mathbb{R}^d), \\ (\Sigma_E \mathbb{1}_{\mathbb{R}^d \setminus \mathcal{I}})(\frac{\cdot}{\varepsilon}) &\rightharpoonup 0, & weakly & in \ \mathrm{L}^{1+\eta}_{\mathrm{loc}}(\mathbb{R}^d), \\ \varepsilon\psi_E(\frac{\cdot}{\varepsilon}) &\to 0, & strongly & in \ \mathrm{L}^q_{\mathrm{loc}}(\mathbb{R}^d), & for \ all \ q < \frac{2d}{d-2}. \end{aligned}$$

In contrast with the case of uniformly separated particles, cf. [10, Proposition 2.1], we emphasize that under the moment condition (2.5) the pressure field  $\Sigma_E$  above is only defined in  $L^{1+\eta}(\Omega)$  for some  $\eta > 0$ , and not in  $L^2(\Omega)$ . Improving on this integrability naturally requires a stronger moment condition, as shown in the following.

**Proposition 2** (Integrability of the pressure). Let d > 2 and let  $\gamma := \frac{2d(d+1)}{d^2+5d-2}$  for abbreviation. On top of Assumptions  $(H^{\circ}_{\delta})$  and  $(H'_{\delta})$ , given  $1 < \alpha < 2$ , let one of the following conditions hold for interparticle distances  $\{\rho_n\}_n$ :

• in case  $\alpha \leq \frac{d}{d-1}$  with  $d \leq 5$ , assume that

$$\begin{aligned} & \text{for } d < 5 \quad : \quad \sum_{n} \mathbb{E} \left[ \rho_{n}^{-\frac{\alpha}{2-\alpha} - \frac{\beta-d}{2}} \mathbb{1}_{0 \in I_{n}} \right] & < \quad \infty, \\ & \text{for } d = 5 \quad : \quad \sum_{n} \mathbb{E} \left[ |\log \rho_{n}|^{\frac{\alpha}{2-\alpha}} \, \mathbb{1}_{0 \in I_{n}} \right] & < \quad \infty, \end{aligned}$$

- in case  $\alpha < \gamma$  with d > 5, no moment condition is required;
- in case  $\frac{d}{d-1} \lor \gamma < \alpha < 2$ , with  $\alpha \neq \frac{d}{d-2}$ , assume that

$$\sum_{n} \mathbb{E} \left[ \rho_n^{-\frac{\alpha}{2-\alpha} \left(\frac{1}{\gamma} - \frac{1}{\alpha}\right)(d+1)} \mathbb{1}_{0 \in I_n} \right] < \infty.$$

Then for all  $E \in \mathbb{M}_0^{\text{sym}}$  the pressure field  $\Sigma_E$  constructed in Theorem 1 satisfies

$$\mathbb{E}\left[|\Sigma_E|^{\alpha}\mathbb{1}_{\mathbb{R}^d\setminus\mathcal{I}}\right] \lesssim |E|^{\alpha}$$

and there holds almost surely  $(\Sigma_E \mathbb{1}_{\mathbb{R}^d \setminus \mathcal{I}})(\frac{\cdot}{\varepsilon}) \rightharpoonup 0$  weakly in  $L^{\alpha}_{\text{loc}}(\mathbb{R}^d)$  as  $\varepsilon \downarrow 0$ .

2.3. Homogenization result. We turn to the homogenization result for the Stokes problem (1.1)–(1.5). For that purpose, we first define admissible random ensembles of particles in a given bounded Lipschitz domain  $U \subset \mathbb{R}^d$ : the proof indeed requires to control the distance of particles to the boundary  $\partial U$  similarly as interparticle distances. We let  $\mathcal{N}_{\varepsilon}(U) \subset \mathbb{N}$  denote a random subset of indices such that

$$\left\{n: I_n \subset \frac{1}{\varepsilon}U, \operatorname{dist}(I_n, \partial_{\varepsilon}^{\frac{1}{\varepsilon}}U) \geq \delta\right\} \subset \mathcal{N}_{\varepsilon}(U) \subset \left\{n: I_n \subset \frac{1}{\varepsilon}U\right\},\$$

and we define the associated random ensemble of particles in U,

$$\mathcal{I}_{\varepsilon}(U) := \bigcup_{n \in \mathcal{N}_{\varepsilon}(U)} \varepsilon I_n.$$
(2.10)

In this setting, we consider corresponding neighborhoods  $\{I_{n:U\varepsilon}^+\}_n$  of the particles  $\{I_n\}_n$ ,

$$I_{n;U,\varepsilon}^+ := I_n^+ \cap \frac{1}{\varepsilon} U,$$

we assume that Assumption  $(\mathbf{H}'_{\delta})$  holds with neighborhoods  $\{I_n^+\}_n$  replaced by  $\{I_{n;U,\varepsilon}^+\}_n$ , and we define the corresponding distances  $\{\rho_{n;U,\varepsilon}\}_n$  as in (2.4). With this notation, we may now formulate the homogenization result for (1.1)-(1.5). The proof is based on a div-curl argument together with an extension result for fluxes as inspired by the work of Jikov [20, 21]. Due to non-uniform particle separation, extended fluxes are only controlled in  $L^{\alpha}$  for some integrability  $\alpha < 2$  depending on the moment condition on interparticle distances; see Theorem 4. In view of the Sobolev embedding, Jikov's div-curl argument can then be performed provided  $\alpha \geq \frac{2d}{d+2}$ . This restriction leads to the moment condition (2.11) below, which is expected to be optimal in general and coincides with the one in Proposition 2 with  $\alpha = \frac{2d}{d+2}$ . We emphasize that this condition becomes more stringent in large dimension as the Sobolev exponent  $\frac{2d}{d+2}$  increases to 2. Not surprisingly, the condition is stronger than the one for the existence of the corrector in Theorem 1 since defining correctors only requires to construct an admissible test function for the variational problem (2.6).

**Theorem 3** (Homogenization result). Let d > 2. On top of Assumption  $(\mathbb{H}^{\circ}_{\delta})$ , given a bounded Lipschitz domain  $U \subset \mathbb{R}^d$ , let Assumption  $(\mathbb{H}'_{\delta})$  hold for  $\{I^+_{n;U,\varepsilon}\}_n$ , and assume that interparticle distances  $\{\rho_{n;U,\varepsilon}\}_n$  satisfy almost surely

$$for \ d = 3 \quad : \quad \limsup_{\varepsilon \downarrow 0} \varepsilon^d \sum_{n \in \mathcal{N}_{\varepsilon}(U)} (\rho_{n;U,\varepsilon})^{-\frac{3}{2}} < \infty,$$
  
$$for \ d \ge 4 \quad : \quad \limsup_{\varepsilon \downarrow 0} \varepsilon^d \sum_{n \in \mathcal{N}_{\varepsilon}(U)} (\rho_{n;U,\varepsilon})^{-(\frac{d}{2}-1)} < \infty,$$

$$(2.11)$$

where in case d = 6 the exponent  $\frac{d}{2} - 1 = 2$  must be replaced by some exponent > 2. Denote by  $\lambda := \mathbb{E}[\mathbb{1}_{\mathcal{I}}]$  the volume fraction of the suspension, let  $\psi, \Sigma, \bar{B}$  be defined as in Theorem 1, and define the following effective constant  $\bar{b} \in \mathbb{M}_0^{\text{sym}}$ : for all  $E \in \mathbb{M}_0^{\text{sym}}$ ,

$$\bar{\boldsymbol{b}}: E := \frac{1}{d} \mathbb{E} \bigg[ \sum_{n} \frac{\mathbb{1}_{I_n}}{|I_n|} \int_{\partial I_n} (x - x_n) \cdot \sigma(\psi_E + Ex, \Sigma_E) \nu \bigg].$$
(2.12)

Given an internal force  $f \in L^2(U)^d$ , let the velocity field  $u_{\varepsilon} \in L^2(\Omega; H^1_0(U)^d)$  and the associated pressure field  $S_{\varepsilon} \in L^1(\Omega; L^1(U \setminus \mathcal{I}_{\varepsilon}(U)))$ , with anchoring  $\int_{U \setminus \mathcal{I}_{\varepsilon}(U)} S_{\varepsilon} = 0$ , be almost surely the unique solutions of the Stokes problem (1.1)–(1.5), that is,

$$\begin{cases} -\Delta u_{\varepsilon} + \nabla S_{\varepsilon} = f, & \text{in } U \setminus \mathcal{I}_{\varepsilon}(U), \\ \operatorname{div}(u_{\varepsilon}) = 0, & \operatorname{in } U, \\ D(u_{\varepsilon}) = 0, & \text{in } \mathcal{I}_{\varepsilon}(U), \\ \int_{\varepsilon \partial I_{n}} \sigma(u_{\varepsilon}, S_{\varepsilon})\nu = 0, & \forall n, \\ \int_{\varepsilon \partial I_{n}} \Theta(x - \varepsilon x_{n}) \cdot \sigma(u_{\varepsilon}, S_{\varepsilon})\nu = 0, & \forall n, \forall \Theta \in \mathbb{M}^{\mathrm{skew}}. \end{cases}$$

$$(2.13)$$

Then we have almost surely, as  $\varepsilon \downarrow 0$ ,

$$\begin{aligned} u_{\varepsilon} - \bar{u} & \rightharpoonup & 0, \quad \text{weakly in } H^1_0(U), \\ (S_{\varepsilon} - \bar{S} - \bar{b} : \mathrm{D}(\bar{u})) \mathbb{1}_{U \setminus \mathcal{I}_{\varepsilon}(U)} & \rightharpoonup & 0, \quad \text{weakly in } \mathrm{L}^{\frac{2d}{d+2}}(U), \end{aligned}$$

where the limiting velocity field  $\bar{u} \in H_0^1(U)^d$  and the associated pressure field  $\bar{S} \in L^2(U)$ , with anchoring  $\int_U \bar{S} = 0$ , are the unique solutions of the following homogenized equation,

$$\begin{cases} -\operatorname{div}(2\bar{\boldsymbol{B}}\operatorname{D}(\bar{u})) + \nabla \bar{S} = (1-\lambda)f, & \text{in } U, \\ \operatorname{div}(\bar{u}) = 0, & \text{in } U. \end{cases}$$
(2.14)

In addition, provided that  $f \in L^p(U)^d$  for some p > d, the following corrector results hold almost surely, as  $\varepsilon \downarrow 0$ ,

$$\left\| u_{\varepsilon} - \bar{u} - \sum_{E \in \mathcal{E}} \varepsilon \psi_{E}(\frac{\cdot}{\varepsilon}) \nabla_{E} \bar{u} \right\|_{H^{1}(U)} \to 0,$$
  
$$\inf_{c \in \mathbb{R}} \left\| S_{\varepsilon} - \bar{S} - \bar{b} : \mathcal{D}(\bar{u}) - \sum_{E \in \mathcal{E}} \Sigma_{E}(\frac{\cdot}{\varepsilon}) \nabla_{E} \bar{u} - c \right\|_{\mathcal{L}^{\frac{2d}{d+2}}(U \setminus \varepsilon \mathcal{I})} \to 0,$$
(2.15)

where  $\mathcal{E}$  stands for an orthonormal basis of  $\mathbb{M}_0^{\text{sym}}$ .

2.4. Further technical tools. On top of the definition of the effective viscosity and the above qualitative homogenization result, we wish to further extend more advanced results such as the validity of Einstein's formula for the effective viscosity at low density [7, 17], optimal quantitative error estimates for homogenization [8], and the analysis of sedimentation [9]. To this aim, we provide a couple of technical tools for the analysis of suspensions without uniform separation. These tools are used in [7, Section 2] and [17, Section 5] for the validity of Einstein's formula.

We start with the following extension result for fluxes in presence of rigid particles, which constitutes the main technical tool in our proof of Theorem 3. Starting from a notion of flux q that accounts for the behavior outside rigid particles, we construct an extension  $\tilde{q}$ that is defined nontrivially inside the particles in such a way that the continuity equation holds globally, cf. (2.18). For that purpose, one views the suspension of rigid particles as the limit of a suspension of droplets with diverging shear viscosity, and extended fluxes are then naturally defined as limits of corresponding fluxes; see Remark 4.2. This construction is inspired by a corresponding scalar result by Jikov [20, 21] in the context of scalar elliptic equations with stiff inclusions (see also [22, Section 3.5]), but additional care is needed here to deal with the incompressibility constraint.

**Theorem 4** (Extension of fluxes). Let d > 2, let Assumptions  $(\mathbf{H}^{\circ}_{\delta})$  and  $(\mathbf{H}'_{\delta})$  hold, and let a realization of the random set  $\mathcal{I}$  be fixed. Given  $\beta \in (1, \infty)$  and  $f \in \mathrm{L}^{\beta}_{\mathrm{loc}}(\mathbb{R}^d)^d$ , let  $q \in \mathrm{L}^{\beta}_{\mathrm{loc}}(\mathbb{R}^d)_{\mathrm{sym}}^{d \times d}$  with  $\mathrm{tr}(q) = 0$  satisfy

$$2\int_{\mathbb{R}^d} \mathcal{D}(g) : q = \int_{\mathbb{R}^d} g \cdot f, \qquad \forall g \in C_c^1(\mathbb{R}^d)^d : \operatorname{div}(g) = 0, \ \mathcal{D}(g)|_{\mathcal{I}} = 0.$$
(2.16)

Then, for all  $\alpha$ , r chosen as follows,

$$r \geq \frac{\beta}{\beta-1}, \qquad \text{with} \quad \left\{ \begin{array}{l} r < \frac{d\beta}{\beta-d}, & \text{if } \beta > d, \\ r \neq \frac{d\beta}{d\beta-d-\beta}, & \text{if } \beta > \frac{d}{d-1}, \\ \alpha < \frac{d}{d-1}, & \text{if } r = \frac{\beta}{\beta-1}, \end{array} \right.$$

there exists an extension  $\tilde{q} \in L^{\alpha}_{loc}(\mathbb{R}^d)^{d \times d}_{sym}$  with  $tr(\tilde{q}) = 0$ , as well as an associated pressure field  $\tilde{S} \in L^{\alpha}_{loc}(\mathbb{R}^d)$ , such that

$$\widetilde{q}|_{\mathbb{R}^d \setminus \mathcal{I}} = q|_{\mathbb{R}^d \setminus \mathcal{I}}, \quad and \quad -\operatorname{div}(2\widetilde{q} - \widetilde{S}\operatorname{Id}) = f, \quad in \ \mathbb{R}^d, \tag{2.18}$$

and such that the following estimate holds, for all  $R \ge 1$ ,

$$\|\tilde{q}\|_{\mathcal{L}^{\alpha}(B_{R})} + \|\tilde{S} - f_{B_{R}}\tilde{S}\|_{\mathcal{L}^{\alpha}(B_{R})} \lesssim_{\alpha,\beta,r} \Lambda(B_{R};r,\frac{\beta\alpha}{\beta-\alpha}) \Big(\|f\|_{\mathcal{L}^{\frac{d\beta}{d+\beta}}(\widehat{B}_{R})} + \|q\|_{\mathcal{L}^{\beta}(\widehat{B}_{R}\setminus\mathcal{I})}\Big),$$
(2.19)

where we have set  $\widehat{B}_R := B_R \cup \bigcup_{n:I_n \cap B_R \neq \emptyset} I_n^+$  and

$$\Lambda(D; r, p) := \left( |D| + \sum_{n: I_n \cap D \neq \emptyset} \mu_r(\rho_n)^p \right)^{\frac{1}{p}},$$
(2.20)

in terms of

$$\mu_r(\rho) := \begin{cases} \rho^{\frac{d+1}{2r} - \frac{3}{2}} : r > \frac{d+1}{3}, \\ |\log \rho|^{\frac{1}{r}} : r = \frac{d+1}{3}, \\ 1 : r < \frac{d+1}{3}. \end{cases}$$
(2.21)

As applications of this extension result, we establish a trace estimate at particle boundaries and a version of Caccioppoli's inequality.

**Corollary 5** (Trace estimate). Let d > 2, let Assumptions  $(\mathbb{H}^{\circ}_{\delta})$  and  $(\mathbb{H}'_{\delta})$  hold, and let a realization of the random set  $\mathcal{I}$  be fixed. Let the velocity field  $u \in H^{1}_{loc}(\mathbb{R}^{d})^{d}$  and the associated pressure field  $S \in L^{1}_{loc}(\mathbb{R}^{d} \setminus \mathcal{I})$  satisfy the homogeneous Stokes problem

$$\begin{cases} -\Delta u + \nabla S = 0, & \text{in } \mathbb{R}^d \setminus \mathcal{I}, \\ \operatorname{div}(u) = 0, & \operatorname{in } \mathbb{R}^d, \\ D(u) = 0, & \text{in } \mathcal{I}, \\ \int_{\partial I_n} \sigma(u, S)\nu = 0, & \forall n, \\ \int_{\partial I_n} \Theta(x - x_n) \cdot \sigma(u, S)\nu = 0, & \forall n, \forall \Theta \in \mathbb{M}^{\mathrm{skew}}. \end{cases}$$

$$(2.22)$$

Then for all n and  $g \in W^{1,\infty}(I_n^+)^d$  we have for all  $\eta > 0$ ,

$$\begin{split} \left| \int_{\partial I_n} g \cdot \sigma(u, S) \nu \right| &\lesssim_{\eta} \|g\|_{W^{1,\infty}(I_n^+ \setminus I_n)} \left( \int_{I_n^+ \setminus I_n} |\mathcal{D}(u)|^2 \right)^{\frac{1}{2}} \\ &\times \begin{cases} \rho_n^{\frac{1}{4d}(d+1)(d+2) - \frac{5}{2} - \eta} & : & d \le 6, \\ 1 & : & d > 6. \end{cases} \end{split}$$

**Corollary 6** (Caccioppoli's inequality). Let d > 2, let Assumptions  $(H^{\circ}_{\delta})$  and  $(H'_{\delta})$  hold, and let a realization of the random set  $\mathcal{I}$  be fixed. Then, for all  $\eta > 0$ , there exists  $s < \frac{2d}{d-2}$ such that any solution (u, S) of the homogeneous Stokes problem (2.22) satisfies, for all  $R \geq 5$  and  $K \geq 1$ ,

$$\begin{split} \left( \int_{B_R} |\nabla u|^2 \right)^{\frac{1}{2}} \\ \lesssim_{s,\eta} \left( KR^{-1} \Big( \int_{B_{2R}} \left| u - \int_{B_{2R}} u \right|^s \Big)^{\frac{1}{s}} + \left( K^{-1} + R^{-\frac{d}{2}(\frac{1}{s} - \frac{d-2}{2d})} \right) \Big( \int_{B_{2R}} |\nabla u|^2 \Big)^{\frac{1}{2}} \Big) \\ \times \begin{cases} 1 + R^{-d} \sum_{n:I_n \cap B_{2R} \neq \varnothing} \rho_n^{\frac{1}{4}(d+1)(d+2) - \frac{5}{2}d - \eta} & : d \le 5, \\ 1 + R^{-d} \sum_{n:I_n \cap B_{2R} \neq \varnothing} \rho_n^{1 - \frac{d}{2} - \eta} & : d > 5. \end{cases} \end{split}$$

### 3. EXTENSION OF FLUXES

This section is devoted to the proof of Theorem 4. The argument relies on the following local extension result for incompressible fields, which is of independent interest.

**Proposition 3.1.** Let d > 2, let Assumptions  $(\mathbf{H}^{\circ}_{\delta})$  and  $(\mathbf{H}'_{\delta})$  hold, and let a realization of the random set  $\mathcal{I}$  be fixed. Let  $1 < s \leq r < \infty$ , with  $r \neq \frac{ds}{d-s}$  if s < d, and with  $r < \frac{ds}{d+s-ds}$  if  $s < \frac{d}{d-1}$ . Then, for all n, there exists an extension operator  $P_n$  such that for all  $g \in C^1_h(I_n)^d$  with div(g) = 0 the extension  $P_ng \in W^{1,s}_0(I_n^+)^d$  satisfies

$$D(P_ng)|_{I_n} = D(g), \quad and \quad \operatorname{div}(P_ng) = 0, \quad in \ I_n^+, \quad (3.1)$$

and for all  $p \ge s \lor \frac{drs}{d(r-s)+rs}$ , with p > d if r = s,

$$\left\|\nabla P_n g\right\|_{\mathcal{L}^s(I_n^+)} \lesssim_{p,r,s} \mu_r(\rho_n) \left\|\mathcal{D}(g)\right\|_{\mathcal{L}^p(I_n)},\tag{3.2}$$

where we recall the notation (2.21) for  $\mu_r$ .

For future reference, we also highlight the following key tool for pressure estimates. It follows from the above local extension result combined with a standard use of the Bogovskii operator. Note that the restriction on the geometry of the domain D and the associated constant K(D) can be refined as e.g. in [13, Lemma III.3.2 and Theorem III.3.1].

**Lemma 3.2.** Let d > 2, let Assumptions  $(\mathbb{H}^{\circ}_{\delta})$  and  $(\mathbb{H}'_{\delta})$  hold, and let a realization of the random set  $\mathcal{I}$  be fixed. Let  $D \subset \mathbb{R}^d$  be a bounded Lipschitz domain that is star-like with respect to every point in some ball of radius  $R_0$ , and set  $K(D) := \frac{1}{R_0} \operatorname{diam}(D)$ . Let  $1 < s \leq r < \infty$ , with  $r \neq \frac{ds}{d-s}$  if s < d, and with  $r < \frac{ds}{d+s-ds}$  if  $s < \frac{d}{d-1}$ . Then, for all  $h \in C_b(D)$  with  $\int_{D \setminus \mathcal{I}} h = 0$ , there exists  $z \in W_0^{1,s}(D)^d$  such that

$$\mathbf{D}(z)|_{\mathcal{I}} = 0, \qquad and \qquad \mathrm{div}(z) = h \mathbbm{1}_{D \setminus \mathcal{I}}, \quad in \ D,$$

and for all  $p \ge s \lor \frac{drs}{d(r-s)+rs}$ , with p > d if r = s,

$$\|\nabla z\|_{\mathcal{L}^{s}(D)} \lesssim_{p,r,s} K(D)^{d+1} \Lambda(D;r,\frac{ps}{p-s}) \|h\|_{\mathcal{L}^{p}(D\setminus\mathcal{I})},$$
(3.3)

where we recall the definition (2.20)–(2.21) of  $\Lambda$ .

3.1. Cut-off functions. We start with the construction of suitable cut-off functions for the inclusions  $\{I_n\}_n$  in their neighborhoods  $\{I_n^+\}_n$ . The open subsets  $\{J_n^j\}_j$  in the statement below are neighborhoods of quasi-contact points, that is, neighborhoods where  $\partial I_n$ and  $\partial I_n^+$  are very close; see Figure 3. The proof is inspired by the work of Jikov on homogenization problems with stiff inclusions, e.g. [22, Section 3.2], and is also analogous to computations by Gérard-Varet and Hillairet in [16] for the drag force on a sphere close to a wall. This result is easily adapted beyond Assumption  $(\mathbf{H}'_{\delta})$  to cover higher-order quasicontacts between the particles, then leading to a worse dependence on the distance  $\rho_n$ .

**Lemma 3.3** (Cut-off functions). Let Assumptions  $(\mathbf{H}^{\circ}_{\delta})$  and  $(\mathbf{H}'_{\delta})$  hold, and let a realization of the random set  $\mathcal{I}$  be fixed. For all n, there exists a function  $w_n \in W^{1,\infty}_0(I_n^+; [0,1])$  with  $w_n|_{I_n} = 1$  such that for all  $r \geq 1$ ,

$$\|\nabla w_n\|_{\mathbf{L}^r(I_n^+)} \lesssim_r \begin{cases} \rho_n^{\frac{d+1}{2r}-1} & : r > \frac{d+1}{2}, \\ |\log \rho_n|^{\frac{1}{r}} & : r = \frac{d+1}{2}, \\ 1 & : r < \frac{d+1}{2}, \end{cases}$$
(3.4)

and

$$\|\nabla^2 w_n\|_{\mathcal{L}^r(I_n^+)} \lesssim_r \begin{cases} \rho_n^{\frac{d+1}{2r}-2} & : r > \frac{d+1}{4}, \\ |\log \rho_n|^{\frac{1}{r}} & : r = \frac{d+1}{4}, \\ 1 & : r < \frac{d+1}{4}. \end{cases}$$
(3.5)



FIGURE 3. This displays a configuration of close particles. Disjoint neighborhoods  $\{I_n^+\}_n$  are represented around the particles, and suitable neighborhoods  $\{J_n^j\}_j$  of quasi-contact points are drawn in light gray.

In addition, there is a collection  $\{J_n^j\}_{j=1}^{M_n}$  of open subsets of the form  $J_n^j = B(x_n^j, \frac{1}{C}\delta) \cap I_n^+$ , with  $M_n \lesssim 1$  and  $\operatorname{dist}(J_n^j, J_n^k) \geq \frac{1}{C}\delta$  for all  $j \neq k$ , such that

$$\|w_n\|_{W^{2,\infty}(I_n^+\setminus\bigcup_{j=1}^{M_n}J_n^j)} \lesssim 1,$$

and for all  $r \geq 1$ ,

$$\max_{1 \le j \le M_n} \| |\cdot -x_n^j | \nabla^2 w_n \|_{\mathbf{L}^r(J_n^j)} \lesssim_r \begin{cases} \rho_n^{\frac{d+1}{2r} - \frac{3}{2}} & : r > \frac{d+1}{3}, \\ |\log \rho_n|^{\frac{1}{r}} & : r = \frac{d+1}{3}, \\ 1 & : r < \frac{d+1}{3}. \end{cases}$$
(3.6)

Proof. Under Assumption  $(\mathbf{H}'_{\delta})$ , the construction of the neighborhoods  $\{J^{j}_{n}\}_{j=1}^{M_{n}}$  is transparent, cf. Figure 3, and we only need to construct  $w_{n}$  in one of those sets. In view of the definition of the parabolic domains  $\Gamma^{\pm}_{a_{1},a_{2}}(\rho)$ , cf. (2.2), it suffices to construct a cut-off function  $w^{\rho}_{a_{1},a_{2}}$  in  $B_{\delta} \subset \mathbb{R} \times \mathbb{R}^{d-1}$  such that  $w^{\rho}_{a_{1},a_{2}} = 0$  for  $x_{1} < -\rho + \frac{1}{a_{2}}|x'|^{2}$  and  $w^{\rho}_{a_{1},a_{2}} = 1$  for  $x_{1} > \frac{1}{a_{1}}|x'|^{2}$ . By assumption we consider  $a_{2} > a_{1} \ge \delta$  with  $\frac{1}{a_{1}} - \frac{1}{a_{2}} \ge \delta$ , and by scaling it suffices to consider  $a_{1} = 1$ . More precisely, we consider the set

$$E = \left\{ (x_1, x') \in \mathbb{R} \times \mathbb{R}^{d-1} : x_1 \ge -1, \ |x'| \le \frac{1}{2} \right\}$$

and, given  $\rho > 0$  and a > 1 with  $1 - \frac{1}{a} \ge \delta$ , we construct a cut-off function  $w_a^{\rho} \in C_b^{1,1}(E)$ such that  $w_a^{\rho} = 0$  for  $x_1 < -\rho + \frac{1}{a}|x'|^2$  and  $w_a^{\rho} = 1$  for  $x_1 > |x'|^2$ , and such that for all  $r \ge 1$ ,

$$\|\nabla w_a^{\rho}\|_{\mathcal{L}^r(E)} \lesssim_r \begin{cases} \rho^{\frac{d+1}{2r}-1} & : r > \frac{d+1}{2}, \\ |\log \rho|^{\frac{1}{r}} & : r = \frac{d+1}{2}, \\ 1 & : r < \frac{d+1}{2}, \end{cases}$$
(3.7)

$$\|\nabla^2 w_a^{\rho}\|_{\mathbf{L}^r(E)} \lesssim_r \begin{cases} \rho^{\frac{d+1}{2r}-2} : r > \frac{d+1}{4}, \\ |\log \rho|^{\frac{1}{r}} : r = \frac{d+1}{4}, \\ 1 : r < \frac{d+1}{4}, \end{cases}$$
(3.8)

$$\| |\cdot|\nabla^2 w_a^{\rho} \|_{\mathrm{L}^r(E)} \lesssim_r \begin{cases} \rho^{\frac{d+1}{2r} - \frac{3}{2}} : r > \frac{d+1}{3}, \\ |\log \rho|^{\frac{1}{r}} : r = \frac{d+1}{3}, \\ 1 : r < \frac{d+1}{3}. \end{cases}$$
(3.9)

In other words, we need to construct a suitable interpolation between 1 and 0 in the domain enclosed by the two parabolas,

$$\{(x_1, x') \in \mathbb{R} \times \mathbb{R}^{d-1} : -\rho + \frac{1}{a}|x'|^2 < x_1 < |x'|^2, \ |x'| \le \frac{1}{2}\}.$$

As we aim to construct a  $C^{1,1}$  test function, we cannot use linear interpolation: instead of the linear function  $h^0(t) = t$  with  $h^0(0) = 0$  and  $h^0(1) = 1$ , we rather consider as in [16] the cubic function

$$h(t) := t^2(3-2t),$$

with h(0) = 0, h(1) = 1, and h'(0) = h'(1) = 0. We then define

$$w_a^{\rho}(x) := w_a^{\rho}(x_1, x') := \begin{cases} 0 & : \quad x_1 \le -\rho + \frac{1}{a} |x'|^2, \\ h\left(\frac{1}{\theta_a^{\rho}(x')}(\rho + x_1 - \frac{1}{a} |x'|^2)\right) & : \quad -\rho + \frac{1}{a} |x'|^2 \le x_1 \le |x'|^2, \\ 1 & : \quad x_1 \ge |x'|^2, \end{cases}$$

where for abbreviation we denote by  $\theta_a^{\rho}$  the horizontal distance between the two parabolas,

$$\theta_a^{\rho}(x') := \rho + (1 - \frac{1}{a})|x'|^2.$$

We check that  $w_a^{\rho}$  belongs to  $C^{1,1}(E)$  and it remains to establish the estimates (3.7)–(3.9). Recalling the assumption  $1 - \frac{1}{a} \ge \delta$ , a direct computation shows that there holds for  $-\rho + \frac{1}{a}|x'|^2 \le x_1 \le |x'|^2$ ,

$$|\nabla w_a^{\rho}(x)| \lesssim (\rho + |x'|^2)^{-1}, \qquad |\nabla^2 w_a^{\rho}(x)| \lesssim (\rho + |x'|^2)^{-2}.$$
 (3.10)

We start with the proof of (3.7). Using (3.10), evaluating the integral over  $x_1$ , and using radial coordinates, we find

$$\int_{E} |\nabla w_{a}^{\rho}|^{r} \lesssim_{r} \int_{|x'| \leq \frac{1}{2}} (\rho + |x'|^{2})^{1-r} dx' \lesssim \int_{0}^{\frac{1}{2}} \frac{s^{d-2}}{(\rho + s^{2})^{r-1}} ds,$$

which proves (3.7) after evaluating the integral. The proof of (3.8) follows the same line and is skipped.

We turn to the proof of (3.9). For 
$$-\rho + \frac{1}{a}|x'|^2 \le x_1 \le |x'|^2$$
 and  $|x'| \le \frac{1}{2}$ , we find  
 $|x| \le |x_1| + |x'| \le \rho + |x'|.$ 

Combining this with (3.10), evaluating the integral over  $x_1$ , and using radial coordinates, we find

$$\begin{split} \int_{E} |\cdot|^{r} |\nabla^{2} w_{a}^{\rho}|^{r} &\lesssim_{r} \rho^{r} \int_{|x'| \leq \frac{1}{2}} (\rho + |x'|^{2})^{1-2r} \, dx' + \int_{|x'| \leq \frac{1}{2}} |x'|^{r} \, (\rho + |x'|^{2})^{1-2r} \, dx' \\ &\lesssim \rho^{r} \int_{0}^{\frac{1}{2}} \frac{s^{d-2}}{(\rho + s^{2})^{2r-1}} \, ds + \int_{0}^{\frac{1}{2}} \frac{s^{d+r-2}}{(\rho + s^{2})^{2r-1}} \, ds \end{split}$$

which proves (3.9) after evaluating the integrals.

3.2. **Proof of Proposition 3.1.** Starting from a Stein extension of g, the argument relies on the cut-off function constructed in Lemma 3.3 in order to make this extension vanish on the boundary  $\partial I_n^+$ . A naïve cut-off would however break the incompressibility property and cause serious troubles especially close to quasi-contact points. Instead, in the spirit of [12], taking inspiration from calculations by Gérard-Varet and Hillairet in [16], we take cut-offs at the level of the vector potential. We split the proof into three main steps.

Step 1. Extension to  $I_n^+$ .

Given  $g \in C_b^1(I_n)^d$  with  $\operatorname{div}(g) = 0$ , we construct an extension  $P_n^1 g \in H_0^1(I_n + B)^d$  such that

 $\mathcal{D}(P_n^1 g)|_{I_n} = \mathcal{D}(g), \quad \text{and} \quad \operatorname{div}(P_n^1 g) = 0, \quad \text{in } I_n + B, \quad (3.11)$ and for all  $1 < s < \infty$ ,

$$\|\nabla P_n^1 g\|_{\mathbf{L}^s(I_n+B)} \lesssim_s \|\mathbf{D}(g)\|_{\mathbf{L}^s(I_n)}.$$
(3.12)

For that purpose, let us first choose  $V_g \in \mathbb{R}^d$  and  $\Theta_g \in \mathbb{M}^{\text{skew}}$  such that Korn's inequality yields for all  $1 < s < \infty$ ,

$$\|g - V_g - \Theta_g x\|_{W^{1,s}(I_n)} \lesssim_s \|\mathbf{D}(g)\|_{\mathbf{L}^s(I_n)}.$$
(3.13)

Next, in view of the  $C^2$  regularity of  $I_n$ , cf. Assumption  $(\mathbf{H}^{\circ}_{\delta})$ , we can choose a Stein extension  $P_n^0 g \in C_b^1(I_n + B)^d$  with  $P_n^0 g|_{I_n} = g - V_g - \Theta_g x$ , such that for all  $s \ge 1$ ,

$$||P_n^0g||_{W^{1,s}(I_n+B)} \lesssim_s ||g-V_g-\Theta_g x||_{W^{1,s}(I_n)}$$

and thus, by (3.13), for all  $1 < s < \infty$ ,

$$\|P_n^0 g\|_{W^{1,s}(I_n+B)} \lesssim_s \|\mathbf{D}(g)\|_{\mathbf{L}^s(I_n)}.$$
(3.14)

It remains to apply a cut-off to  $P_n^0 g$  to make it vanish on the boundary  $\partial(I_n + B)$  while keeping the properties in (3.11). For that purpose, choose a cut-off function  $\chi \in C_c^{\infty}(I_n+B)$ with  $\chi|_{I_n} = 1$  and  $\|\chi\|_{W^{1,\infty}(I_n+B)} \leq 1$ . By a standard construction based on the Bogovskii operator, e.g. [13, Theorem III.3.1], since the following compatibility relation holds,

$$\int_{(I_n+B)\backslash I_n} \operatorname{div}(\chi P_n^0 g) = -\int_{\partial I_n} g \cdot \nu = -\int_{I_n} \operatorname{div}(g) = 0,$$

there exists  $z_n(g) \in H^1_0((I_n + B) \setminus I_n)^d$  such that

$$\operatorname{div}(z_n(g)) = \operatorname{div}(\chi P_n^0 g), \quad \text{in } (I_n + B) \setminus I_n$$

and for all  $1 < s < \infty$ ,

$$\|\nabla z_n(g)\|_{\mathrm{L}^s((I_n+B)\setminus I_n)} \lesssim_s \|\mathrm{div}(\chi P_n^0 g)\|_{\mathrm{L}^s((I_n+B)\setminus I_n)}.$$

Expanding the divergence in the right-hand side of this estimate, and using (3.14), we find for all  $1 < s < \infty$ ,

$$\|\nabla z_n(g)\|_{\mathcal{L}^s((I_n+B)\setminus I_n)} \lesssim_s \|P_n^0 g\|_{W^{1,s}(I_n+B)} \lesssim_s \|\mathcal{D}(g)\|_{\mathcal{L}^s(I_n)}.$$
(3.15)

Now we define

$$P_n^1 g := \chi P_n^0 g - z_n(g) \in H_0^1(I_n + B)^d$$

which indeed satisfies  $P_n^1 g|_{I_n} = P_n^0 g|_{I_n} = g - V_g - \Theta_g x$  and  $\operatorname{div}(P_n^1 g) = 0$ , hence (3.11). In addition, combining (3.14) and (3.15) yields for all  $1 < s < \infty$ ,

 $\|\nabla P_n^1 g\|_{L^s(I_n+B)} \lesssim \|P_n^0 g\|_{W^{1,s}(I_n+B)} + \|\nabla z_n(g)\|_{L^s((I_n+B)\setminus I_n)} \lesssim_s \|\mathbf{D}(g)\|_{L^s(I_n)},$ that is, (3.12). Step 2. Matrix potential for  $P_n^1 g$ . We construct a matrix field  $\sigma[P_n^1 g] \in C^1(\mathbb{R}^d)^{d \times d}_{\text{skew}}$  that decays at infinity such that

$$\operatorname{div}(\sigma[P_n^1 g])|_{I_n^+} = P_n^1 g|_{I_n^+}, \qquad (3.16)$$

and such that for all  $\frac{d}{d-1} < s < \infty$  and p > d,

$$\begin{aligned} \|\nabla\sigma[P_n^1g]\|_{\mathcal{L}^s(\mathbb{R}^d)} &\lesssim_s \|\mathcal{D}(g)\|_{\mathcal{L}^{\frac{ds}{d+s}}(I_n)}, \\ \|\nabla\sigma[P_n^1g]\|_{\mathcal{L}^\infty(\mathbb{R}^d)} &\lesssim_p \|\mathcal{D}(g)\|_{\mathcal{L}^p(I_n)}. \end{aligned}$$
(3.17)

For that purpose, we extend  $P_n^1 g$  by 0 to  $\mathbb{R}^d$ , viewing it as a compactly supported element of  $H^1(\mathbb{R}^d)^d$ , and for all i, j we define  $\nabla \sigma_{ij}[P_n^1 g] \in L^2(\mathbb{R}^d)^d$  as the unique solution of

$$-\Delta\sigma_{ij}[P_n^1g] = \partial_i(P_n^1g)_j - \partial_j(P_n^1g)_i, \quad \text{in } \mathbb{R}^d.$$
(3.18)

In view of (3.12), Calderón–Zygmund potential theory yields  $\nabla \sigma_{ij}[P_n^1g] \in W^{1,s}(\mathbb{R}^d)^d$  for all  $1 < s < \infty$ . Moreover, as  $P_n^1g$  is compactly supported, Riesz potential theory ensures that  $\sigma_{ij}[P_n^1g]$  can itself be uniquely chosen as a decaying element in  $C^1(\mathbb{R}^d)$ . Uniqueness and the form of the right-hand side in (3.18) ensure that  $\sigma[P_n^1g]$  is skew-symmetric. Taking the divergence in (3.18), and using that  $\operatorname{div}(P_n^1g) = 0$ , we find

$$-\Delta \operatorname{div}(\sigma[P_n^1 g]) = -\Delta P_n^1 g, \quad \text{in } \mathbb{R}^d,$$

which entails

$$\operatorname{div}(\sigma[P_n^1 g]) = P_n^1 g,$$

that is, (3.16). It remains to check (3.17). First, for all  $\frac{d}{d-1} \leq s < \infty$  and p > d, the Sobolev embedding gives

$$\begin{split} \|\nabla\sigma[P_n^1g]\|_{\mathcal{L}^s(\mathbb{R}^d)} &\lesssim & \|\nabla^2\sigma[P_n^1g]\|_{\mathcal{L}^{\frac{ds}{d+s}}(\mathbb{R}^d)},\\ |\nabla\sigma[P_n^1g]\|_{\mathcal{L}^\infty(\mathbb{R}^d)} &\lesssim & \|\nabla\sigma[P_n^1g]\|_{W^{1,p}(\mathbb{R}^d)}. \end{split}$$

Second, for all  $1 < s < \infty$ , Calderón–Zygmund potential theory for (3.18) gives

$$\begin{aligned} \|\nabla^2 \sigma[P_n^1 g]\|_{\mathcal{L}^s(\mathbb{R}^d)} &\lesssim_s \|\nabla P_n^1 g\|_{\mathcal{L}^s(\mathbb{R}^d)}, \\ \|\nabla \sigma[P_n^1 g]\|_{\mathcal{L}^s(\mathbb{R}^d)} &\lesssim_s \|P_n^1 g\|_{\mathcal{L}^s(\mathbb{R}^d)}. \end{aligned}$$
(3.19)

Combining these two ingredients, appealing to Poincaré's inequality for  $P_n^1 g$  supported in  $I_n + B$ , and using (3.12), the claim (3.17) follows. For future reference, we note that a similar argument also gives, for all  $\frac{d}{d-1} < s < \infty$  and p > d,

$$\|P_n^1 g\|_{\mathcal{L}^s(\mathbb{R}^d)} \lesssim_s \|\mathcal{D}(g)\|_{\mathcal{L}^{\frac{ds}{d+s}}(I_n)},$$
  
$$\|P_n^1 g\|_{\mathcal{L}^\infty(\mathbb{R}^d)} \lesssim_p \|\mathcal{D}(g)\|_{\mathcal{L}^p(I_n)}.$$
(3.20)

Step 3. Conclusion.

Recall the cut-off function  $w_n \in H_0^1(I_n^+)$  that we have constructed in Lemma 3.3, as well as the collection of neighborhoods of quasi-contact points  $J_n^j = B(x_n^j, \frac{1}{C}\delta) \cap I_n^+, 1 \le j \le M_n$ . Recalling that  $\operatorname{dist}(J_n^j, J_n^k) \ge \frac{1}{C}\delta$  for  $j \ne k$ , we further define enlarged neighborhoods

$$J_n^j \quad \subset \quad J_n^{j,+} := B(x_n^j, \tfrac{6}{5C}\delta) \cap I_n^+ \quad \subset \quad J_n^{j,++} := B(x_n^j, \tfrac{7}{5C}\delta) \cap I_n^+,$$

which then satisfy  $\operatorname{dist}(J_n^{j,++}, J_n^{k,++}) \geq \frac{1}{5C}\delta$  for  $j \neq k$ , and we write for abbreviation

$$J_n := \bigcup_{j=1}^{M_n} J_n^j, \qquad J_n^+ := \bigcup_{j=1}^{M_n} J_n^{j,+}, \qquad J_n^{++} := \bigcup_{j=1}^{M_n} J_n^{j,++}$$

We split the proof into two further substeps, first constructing the extension  $P_n g$  close to quasi-contact points in  $J_n^+$ , and then completing the construction globally.

Substep 3.1. Construction of  $P_n g$  close to quasi-contact points. Given  $1 < s \le r < \infty$  with  $r \ne \frac{ds}{d-s}$  if s < d, and with  $r < \frac{ds}{d+s-ds}$  if  $s < \frac{d}{d-1}$ , we construct a vector field  $P_n^2 g \in H_0^1(I_n^+)^d$  such that

$$P_n^2 g|_{I_n \cap J_n^+} = P_n^1 g|_{I_n \cap J_n^+}, \quad \text{and} \quad \operatorname{div}(P_n^2 g) = 0, \quad \text{in } I_n^+, \quad (3.21)$$

and for all  $p \ge s \lor \frac{drs}{d(r-s)+rs}$ , with p > d if r = s,

$$\|\nabla P_n^2 g\|_{\mathbf{L}^s(I_n^+)} \lesssim_{p,r,s} \mu_r(\rho_n) \|\mathbf{D}(g)\|_{\mathbf{L}^p(I_n)},$$
(3.22)

where we recall the notation (2.21) for  $\mu_r$ . For all j we first choose a smooth cut-off function  $\chi_n^j \in C^\infty(I_n^+)$  such that

$$\chi_n^j|_{J_n^{j,+}} = 1, \qquad \chi_n^j|_{I_n^+ \setminus J_n^{j,++}} = 0, \qquad \|\chi_n^j\|_{W^{2,\infty}(I_n^+)} \lesssim 1.$$

Given a collection of matrices  $\{\Theta_n^j\}_{j=1}^{M_n} \subset \mathbb{M}^{\text{skew}}$  to be fixed later, we then define

$$P_n^2 g := \sum_{j=1}^{M_n} \operatorname{div} \left( w_n \chi_n^j (\sigma[P_n^1 g] - \Theta_n^j) \right).$$
(3.23)

By definition of  $w_n$ , this is supported in  $I_n^+$  and satisfies, in view of (3.16),

$$P_n^2 g|_{I_n \cap J_n^+} = \operatorname{div}(\sigma[P_n^1 g])|_{I_n \cap J_n^+} = P_n^1 g|_{I_n \cap J_n^+}.$$

Moreover, since  $\sigma[P_n^1g] - \Theta_n^j$  is skew-symmetric, we obviously have  $\operatorname{div}(P_n^2g) = 0$ . It remains to estimate the norm of  $\nabla P_n^2g$ . To this aim, using (3.16) again, we compute

$$\nabla P_n^2 g = \sum_{j=1}^{M_n} \nabla (w_n \chi_n^j P_n^1 g) + \sum_{j=1}^{M_n} \nabla \left( (\sigma [P_n^1 g] - \Theta_n^j) \nabla (w_n \chi_n^j) \right)$$

Expanding the gradients, smuggling in the weights  $x \mapsto |x - x_n^j|$ , and using Hölder's inequality, we find for all  $r \ge s \ge 1$ ,

$$\begin{aligned} \|\nabla P_{n}^{2}g\|_{\mathrm{L}^{s}(I_{n}^{+})} &\lesssim \|\nabla P_{n}^{1}g\|_{\mathrm{L}^{s}(I_{n}^{+})} + \|\nabla(w_{n}\chi_{n}^{j})\|_{\mathrm{L}^{r}(I_{n}^{+})} \|(P_{n}^{1}g, \nabla\sigma[P_{n}^{1}g])\|_{\mathrm{L}^{\frac{rs}{r-s}}(I_{n}^{+})} \\ &+ \sum_{j=1}^{M_{n}} \||\cdot -x_{n}^{j}|\nabla^{2}(w_{n}\chi_{n}^{j})\|_{\mathrm{L}^{r}(J_{n}^{j,++})} \||\cdot -x_{n}^{j}|^{-1} (\sigma[P_{n}^{1}g] - \Theta_{n}^{j})\|_{\mathrm{L}^{\frac{rs}{r-s}}(J_{n}^{j,++})}, \quad (3.24) \end{aligned}$$

and thus, inserting the estimates of Lemma 3.3 for norms of the cut-off function  $w_n$ , and recalling the definition (2.21) of  $\mu_r$ ,

$$\begin{aligned} \|\nabla P_{n}^{2}g\|_{\mathrm{L}^{s}(I_{n}^{+})} &\lesssim_{r} \mu_{r}(\rho_{n}) \bigg( \|\nabla P_{n}^{1}g\|_{\mathrm{L}^{s}(I_{n}^{+})} + \|(P_{n}^{1}g, \nabla\sigma[P_{n}^{1}g])\|_{\mathrm{L}^{\frac{rs}{r-s}}(I_{n}^{+})} \\ &+ \sum_{j=1}^{M_{n}} \||\cdot -x_{n}^{j}|^{-1} (\sigma[P_{n}^{1}g] - \Theta_{n}^{j})\|_{\mathrm{L}^{\frac{rs}{r-s}}(J_{n}^{j,++})} \bigg). \end{aligned}$$
(3.25)

We estimate the right-hand side in two different ways, corresponding to two different choices of the constants  $\{\Theta_n^j\}_{j=1}^{M_n}$  and allowing for complementary ranges of exponents.

• Case 1: choosing  $\Theta_n^j = 0$  for all j, given 1 < s < d and  $r > \frac{ds}{d-s}$ , with  $r < \frac{ds}{d+s-ds}$  if  $s < \frac{d}{d-1}$ , we obtain for all  $p \ge s \lor \frac{drs}{d(r-s)+rs}$ ,

$$\|\nabla P_n^2 g\|_{\mathbf{L}^s(I_n^+)} \lesssim_{r,s} \mu_r(\rho_n) \|\mathbf{D}(g)\|_{\mathbf{L}^p(I_n)}.$$
(3.26)

For that purpose, we appeal to Hardy's inequality in the following form, see e.g. [25, Sections 1.3 and 12.8], for all  $x_0 \in \mathbb{R}^d$  and  $1 \leq p < d$ ,

$$\||\cdot -x_0|^{-1}\sigma[P_n^1g]\|_{\mathcal{L}^p(\mathbb{R}^d)} \lesssim_p \|\nabla\sigma[P_n^1g]\|_{\mathcal{L}^p(\mathbb{R}^d)}$$

Choosing  $\Theta_n^j = 0$ , and inserting this estimate into (3.25), we find for all  $r \ge s \ge 1$  with  $\frac{rs}{r-s} < d$ ,

$$\|\nabla P_{n}^{2}g\|_{\mathrm{L}^{s}(I_{n}^{+})} \lesssim_{r,s} \mu_{r}(\rho_{n}) \left(\|\nabla P_{n}^{1}g\|_{\mathrm{L}^{s}(\mathbb{R}^{d})} + \|(P_{n}^{1}g,\nabla\sigma[P_{n}^{1}g])\|_{\mathrm{L}^{\frac{rs}{r-s}}(\mathbb{R}^{d})}\right)$$

and the claim (3.26) follows from (3.12), (3.17), and (3.20).

• Case 2: choosing  $\Theta_n^j = \sigma[P_n^1 g](x_n^j)$  for all j, given  $1 < s \le r < \infty$ , with  $r < \frac{ds}{d-s}$  if s < d, we obtain for all  $p \ge s \lor \frac{drs}{d(r-s)+rs}$ , with p > d if r = s,

$$\|\nabla P_n^2 g\|_{\mathbf{L}^s(I_n^+)} \lesssim_{p,r,s} \mu_r(\rho_n) \|\mathbf{D}(g)\|_{\mathbf{L}^p(I_n)}.$$
(3.27)

For that purpose, we appeal to Hardy's inequality in the following form, see e.g. [25, Sections 1.3 and 12.8], for all  $x_0 \in I_n^+$  and d ,

$$\||\cdot -x_0|^{-1}(\sigma[P_n^1g] - \sigma[P_n^1g](x_0))\|_{\mathcal{L}^p(I_n^+)} \lesssim_p \|\nabla \sigma[P_n^1g]\|_{\mathcal{L}^p(\mathbb{R}^d)}$$

Choosing  $\Theta_n^j = \sigma[P_n^1 g](x_n^j)$ , and inserting this estimate into (3.25), we find for all  $r \ge s \ge 1$  with  $\frac{rs}{r-s} > d$ ,

$$\|\nabla P_{n}^{2}g\|_{\mathbf{L}^{s}(I_{n}^{+})} \lesssim_{r,s} \mu_{r}(\rho_{n}) \Big(\|\nabla P_{n}^{1}g\|_{\mathbf{L}^{s}(\mathbb{R}^{d})} + \|(P_{n}^{1}g, \nabla\sigma[P_{n}^{1}g])\|_{\mathbf{L}^{\frac{rs}{r-s}}(\mathbb{R}^{d})}\Big),$$

and the claim (3.27) follows from (3.12), (3.17), and (3.20).

Combining (3.26) and (3.27), and choosing the constants  $\{\Theta_n^j\}_{j=1}^{M_n}$  accordingly in the definition (3.23) of  $P_n^2 g$ , the claim (3.22) follows.

Substep 3.2. Construction of  $P_n g$  away from contact points. Let  $1 < s \leq r < \infty$  be fixed, with  $r \neq \frac{ds}{d-s}$  if s < d, and with  $r < \frac{ds}{d+s-ds}$  if  $s < \frac{d}{d-1}$ . Choosing a cut-off function  $\zeta \in C_c^{\infty}(I_n^+ \setminus J_n)$  with  $\zeta|_{I_n \setminus J_n^+} = 1$  and  $\|\zeta\|_{W^{1,\infty}(I_n^+ \setminus J_n)} \lesssim 1$ , we consider the vector field

$$Q_ng := \zeta (P_n^1 g - P_n^2 g),$$

and we note that in view of (3.21) it satisfies

$$Q_n g|_{I_n} = (P_n^1 g - P_n^2 g)|_{I_n}, (3.28)$$

hence in particular  $\operatorname{div}(Q_n g)|_{I_n} = 0$ . As this yields the following relation,

$$\int_{I_n^+ \setminus (I_n \cup J_n)} \operatorname{div}(Q_n g) = - \int_{\partial (I_n \setminus J_n)} (Q_n g) \cdot \nu = - \int_{I_n \setminus J_n} \operatorname{div}(Q_n g) = 0,$$

we can appeal to the same construction based on the Bogovskii operator as in Step 1: there exists  $t_n(g) \in H_0^1(I_n^+ \setminus (I_n \cup J_n))^d$  such that

$$\operatorname{div}(t_n(g)) = \operatorname{div}(Q_n g), \quad \text{in } I_n^+ \setminus (I_n \cup J_n),$$

and

$$\|\nabla t_n(g)\|_{\mathcal{L}^s(I_n^+ \setminus (I_n \cup J_n))} \lesssim_s \|\operatorname{div}(Q_n g)\|_{\mathcal{L}^s(I_n^+ \setminus J_n)}.$$
(3.29)

Here comes the restriction to d > 2 as the set  $I_n^+ \setminus (I_n \cup J_n)$  is typically not connected in dimension d = 2; see Remark 3.4 below. In these terms, we finally define

$$P_ng := P_n^2g + Q_ng - t_n(g) \in H_0^1(I_n^+),$$

which satisfies, in view of (3.28),

$$P_n g|_{I_n} = P_n^2 g|_{I_n} + (P_n^1 g - P_n^2 g)|_{I_n} = P_n^1 g|_{I_n},$$

and also div $(P_ng) = 0$  by definition of  $t_n(g)$ . In addition, combining (3.29) with the definition of  $Q_ng$ , we find

$$\|\nabla P_n g\|_{\mathcal{L}^s(I_n^+)} \lesssim_s \|\nabla P_n^2 g\|_{\mathcal{L}^s(I_n^+)} + \|\nabla Q_n g\|_{\mathcal{L}^s(I_n^+)} \lesssim \|(P_n^1 g, P_n^2 g)\|_{W^{1,s}(I_n^+)},$$

hence, using Poincaré's inequality and inserting (3.12) and (3.22), for all  $p \ge s \lor \frac{drs}{d(r-s)+rs}$ , with p > d if r = s,

 $\left\|\nabla P_n g\right\|_{\mathcal{L}^s(I_n^+)} \lesssim_{p,r,s} \mu_r(\rho_n) \left\|\mathcal{D}(g)\right\|_{\mathcal{L}^p(I_n)}.$ 

This concludes the proof.

**Remark 3.4** (2D case). The restriction to d > 2 is due to the impossibility to fix a stream function  $\sigma[P_n^1g]$  that would vanish at all quasi-contact points. More precisely, in Case 2 of the above proof, we adapt the stream function  $\sigma[P_n^1g]$  locally by making it vanish at each quasi-contact point (cf. choice of  $\Theta_n^j$  in (3.23)), and modifications are then glued together in  $I_n^+ \setminus J_n$  while the field must remain divergence-free and keep the same symmetric gradient in  $I_n$ . In 2D this is not possible since  $I_n^+ \setminus (I_n \cup J_n)$  is not connected whenever  $I_n$  has multiple quasi-contact points. Due to this geometric rigidity in 2D, the above proof is no longer valid: we must abandon the cancellation of the stream function at quasi-contact points and rather consider the extension operator

$$Pg := \operatorname{div}(w_n \sigma[P_n^1 g])$$

The bound (3.24) then becomes, for all  $r \ge s \ge 1$ , with  $r < \frac{2s}{2-s}$  if s < 2,

$$\begin{split} \|\nabla Pg\|_{\mathcal{L}^{s}(I_{n}^{+})} \\ \lesssim & \|\nabla P_{n}^{1}g\|_{\mathcal{L}^{s}(I_{n}^{+})} + \|\nabla w_{n}\|_{W^{1,r}(I_{n}^{+})} \Big(\|P_{n}^{1}g\|_{\mathcal{L}^{\frac{rs}{r-s}}(\mathbb{R}^{2})} + \|\sigma[P_{n}^{1}g]\|_{W^{1,\frac{rs}{r-s}}(\mathbb{R}^{2})}\Big) \\ \lesssim_{r,s} & \|\nabla P_{n}^{1}g\|_{\mathcal{L}^{s}(I_{n}^{+})} + \|\nabla w_{n}\|_{W^{1,r}(I_{n}^{+})}\|P_{n}^{1}g\|_{\mathcal{L}^{\frac{rs}{r-s}}(I_{n}+B)} \end{split}$$

where we used the Sobolev embedding, the bound (3.19) on  $\sigma[P_n^1g]$ , and Jensen's inequality. Combining this with (3.5), (3.12), and (3.20), we deduce for all  $r \ge s \ge 1$ , with  $r < \frac{2s}{2-s}$  if s < 2, and for all  $p \ge s \lor \frac{2rs}{2(r-s)+rs}$ , with p > 2 if r = s,

$$\|\nabla \widetilde{P}g\|_{\mathbf{L}^{s}(I_{n}^{+})} \lesssim_{p,r,s} \rho_{n}^{\frac{3}{2r}-2} \|\mathbf{D}(g)\|_{\mathbf{L}^{p}(I_{n})}.$$

Replacing Proposition 3.1 by this extension result would lead to corresponding 2D versions of our main results; we skip the detail for shortness.

3.3. **Proof of Lemma 3.2.** Starting point is the following standard construction based on the Bogovskii operator, e.g. [13, Theorem III.3.1]: given a domain D as in the statement, and given  $h \in C_b(D)$  with  $\int_{D\setminus\mathcal{I}} h = 0$ , there exists  $z^0 \in H_0^1(D)^d$  such that

$$\operatorname{div}(z^0) = h \mathbb{1}_{D \setminus \mathcal{I}}, \quad \text{in } D,$$

and for all  $1 < s < \infty$ ,

$$\|\nabla z^{0}\|_{\mathcal{L}^{s}(D)} \lesssim_{s} K(D)^{d+1} \|h\|_{\mathcal{L}^{s}(D\setminus\mathcal{I})}.$$
(3.30)

Next, given  $1 < s \leq r < \infty$ , with  $r \neq \frac{ds}{d-s}$  if s < d, and with  $r < \frac{ds}{d+s-ds}$  if  $s < \frac{d}{d-1}$ , we appeal to the extension operator  $P_n$  that we have constructed in Proposition 3.1, and we define

$$z := z^0 - \sum_n P_n(z^0|_{I_n}).$$

By the properties of  $P_n$ , we find

$$D(z)|_{\mathcal{I}} = 0$$
, and  $\operatorname{div}(z) = \operatorname{div}(z^0) = h \mathbb{1}_{D \setminus h}$ , in  $D$ ,

and for all  $p \ge s \lor \frac{drs}{d(r-s)+rs}$ , with p > d if r = s,

$$\begin{aligned} \|\nabla z\|_{\mathbf{L}^{s}(D)}^{s} &\lesssim & \|\nabla z^{0}\|_{\mathbf{L}^{s}(D)}^{s} + \sum_{n:I_{n}\cap D\neq\varnothing} \|\nabla P_{n}(z^{0}|_{I_{n}})\|_{\mathbf{L}^{s}(I_{n}^{+})}^{s} \\ &\lesssim_{p,r,s} & \|\nabla z^{0}\|_{\mathbf{L}^{s}(D)}^{s} + \sum_{n:I_{n}\cap D\neq\varnothing} \mu_{r}(\rho_{n})^{s}\|\mathbf{D}(z^{0})\|_{\mathbf{L}^{p}(I_{n})}^{s} \\ &\lesssim & \left(|D| + \sum_{n:I_{n}\cap D\neq\varnothing} \mu_{r}(\rho_{n})^{\frac{ps}{p-s}}\right)^{1-\frac{s}{p}} \|\nabla z^{0}\|_{\mathbf{L}^{p}(D)}^{s}. \end{aligned}$$

where the last bound follows from Hölder's inequality. Combined with (3.30), this yields the conclusion.

3.4. **Proof of Theorem 4.** We split the proof into three steps.

Step 1. Given q, S, f as in (2.16), and given  $1 < \beta < \infty$  and  $\alpha, r$  as in (2.17), we show that for all n there exists  $z_n \in W^{1,\alpha}(I_n)^d$  such that

$$2\int_{I_n} \mathcal{D}(g) : \mathcal{D}(z_n) = \int_{I_n^+} g \cdot f - 2\int_{I_n^+ \setminus I_n} \mathcal{D}(g) : q, \quad \forall g \in C_c^1(I_n^+)^d : \operatorname{div}(g) = 0, \quad (3.31)$$

and

$$\|\mathbf{D}(z_n)\|_{\mathbf{L}^{\alpha}(I_n)} \lesssim_{\alpha,\beta,r} \mu_r(\rho_n) \left( \|f\|_{W^{-1,\beta}(I_n^+)} + \|q\|_{\mathbf{L}^{\beta}(I_n^+ \setminus I_n)} \right).$$
(3.32)

While the left-hand side in (3.31) only involves the restriction  $g|_{I_n} \in C_b^1(I_n)^d$  of the test function g, the right-hand side involves its extension  $g \in C_c^1(I_n^+)^d$ . In view of the condition (2.16), the choice of the extension does not matter. Given  $1 < s \leq r < \infty$ , with  $r \neq \frac{ds}{d-s}$  if s < d, and with  $r < \frac{ds}{d+s-ds}$  if  $s < \frac{d}{d-1}$ , we recall the extension operator  $P_n$  that we have constructed in Proposition 3.1, and the problem (3.31) then reads

$$2\int_{I_n} \mathcal{D}(g) : \mathcal{D}(z_n) = \mathcal{F}_n(g), \qquad \forall g \in C_b^1(I_n)^d : \operatorname{div}(g) = 0, \tag{3.33}$$

where we have set for abbreviation

$$\mathcal{F}_n(g) := \int_{I_n^+} (P_n g) \cdot f - 2 \int_{I_n^+ \setminus I_n} \mathcal{D}(P_n g) : q.$$

By Proposition 3.1, we find for all  $p \ge s \lor \frac{drs}{d(r-s)+rs}$ , with p > d if r = s,

$$\begin{aligned} |\mathcal{F}_{n}(g)| &\lesssim \left( \|f\|_{W^{-1,s'}(I_{n}^{+})} + \|q\|_{L^{s'}(I_{n}^{+}\setminus I_{n})} \right) \|\nabla P_{n}g\|_{L^{s}(I_{n}^{+})} \\ &\lesssim_{p,r,s} \ \mu_{r}(\rho_{n}) \left( \|f\|_{W^{-1,s'}(I_{n}^{+})} + \|q\|_{L^{s'}(I_{n}^{+}\setminus I_{n})} \right) \|\mathcal{D}(g)\|_{L^{p}(I_{n})}. \end{aligned}$$

Appealing to the  $L^{p'}$  theory for the Stokes equation, e.g. [13, Section IV.6], we deduce that there exists a solution  $z_n \in W^{1,p'}(I_n)^d$  of the problem (3.33) (unique up to a rigid motion), and that it satisfies

$$\|\mathbf{D}(z_n)\|_{\mathbf{L}^{p'}(I_n)} \lesssim_{p,r,s} \mu_r(\rho_n) \Big( \|f\|_{W^{-1,s'}(I_n^+)} + \|q\|_{\mathbf{L}^{s'}(I_n^+ \setminus I_n)} \Big)$$

Setting  $\alpha := p'$  and  $\beta := s'$ , this yields the claim (3.31)–(3.32).

Step 2. Construction of extended flux. Given  $1 < \beta < \infty$  and  $\alpha, r$  as in (2.17), define

$$\tilde{q} := q \mathbb{1}_{\mathbb{R}^d \setminus \mathcal{I}} + \sum_n \mathcal{D}(z_n) \mathbb{1}_{I_n}$$

with  $z_n$  as constructed in Step 1. Given  $g \in C_c^1(\mathbb{R}^d)^d$  with  $\operatorname{div}(g) = 0$ , we may decompose

$$g = g_{\circ} + \sum_{n} g_{n}, \qquad g_{\circ} := g - \sum_{n} P_{n}g, \qquad g_{n} := P_{n}g.$$

Using (2.16) with test function  $g_{\circ}$ , and using (3.33) with test function  $g_n$ , we are led to the following integral identity,

$$2\int_{\mathbb{R}^d} \mathcal{D}(g) : \tilde{q} = \int_{\mathbb{R}^d} g \cdot f, \qquad \forall g \in C_c^1(\mathbb{R}^d)^d: \operatorname{div}(g) = 0.$$
(3.34)

Next, we prove the bound (2.19) for  $\tilde{q}$ . Given a bounded domain  $D \subset \mathbb{R}^d$ , summing (3.32) over all particles, appealing to Hölder's inequality, and using the Sobolev embedding  $L^{d\beta/(d+\beta)} \hookrightarrow W^{-1,\beta}$ , we find

$$\begin{split} \|\tilde{q}\|_{\mathrm{L}^{\alpha}(D)}^{\alpha} &\leq \|q\|_{\mathrm{L}^{\alpha}(D\setminus\mathcal{I})}^{\alpha} + \sum_{n:I_{n}\cap D\neq\varnothing} \|\mathrm{D}(z_{n})\|_{\mathrm{L}^{\alpha}(I_{n})}^{\alpha} \\ &\lesssim_{\alpha,\beta,r} \|q\|_{\mathrm{L}^{\alpha}(D\setminus\mathcal{I})}^{\alpha} + \sum_{n:I_{n}\cap D\neq\varnothing} \mu_{r}(\rho_{n})^{\alpha} \Big(\|f\|_{W^{-1,\beta}(I_{n}^{+})}^{\beta} + \|q\|_{\mathrm{L}^{\beta}(I_{n}^{+}\setminus I_{n})}^{\beta} \Big)^{\frac{\alpha}{\beta}} \\ &\lesssim \Big(|D| + \sum_{n:I_{n}\cap D\neq\varnothing} \mu_{r}(\rho_{n})^{\frac{\beta\alpha}{\beta-\alpha}} \Big)^{1-\frac{\alpha}{\beta}} \Big(\|f\|_{\mathrm{L}^{\frac{d\beta}{d+\beta}}(\widehat{D})}^{\alpha} + \|q\|_{\mathrm{L}^{\beta}(\widehat{D}\setminus\mathcal{I})}^{\alpha} \Big), \quad (3.35)$$

where we recall the notation  $\widehat{D} = D \cup \bigcup_{n:I_n \cap D \neq \varnothing} I_n^+$ .

Step 3. Construction of extended pressure.

In view of e.g. [22, Proposition 12.10], the relation (3.34) for the extension  $\tilde{q}$  ensures the existence of an associated pressure field  $\tilde{S} \in L^1_{loc}(\mathbb{R}^d)$ , uniquely defined up to a global additive constant, such that

$$\int_{\mathbb{R}^d} \mathcal{D}(g) : \left(2\tilde{q} - \tilde{S}\operatorname{Id}\right) = \int_{\mathbb{R}^d} g \cdot f, \qquad \forall g \in C_c^1(\mathbb{R}^d)^d,$$
(3.36)

that is,  $-\operatorname{div}(2\tilde{q} - \tilde{S}\operatorname{Id}) = f$  in  $\mathbb{R}^d$ . It remains to prove the bound (2.19) for  $\tilde{S}$ . For all  $R \geq 1$ , by a standard use of the Bogovskii operator, e.g. [13, Theorem III.3.1], we can

construct  $z_R \in W_0^{1,\alpha'}(B_R)^d$  such that

$$\operatorname{div}(z_R) = \left( T_R |T_R|^{\alpha - 2} - \oint_{B_R} T_R |T_R|^{\alpha - 2} \right) \mathbb{1}_{B_R}, \qquad T_R := \tilde{S} - \oint_{B_R} \tilde{S},$$

and

$$\|\nabla z_R\|_{L^{\alpha'}(B_R)} \lesssim_{\alpha} \|T_R|T_R|^{\alpha-2}\|_{L^{\alpha'}(B_R)} \lesssim \|\tilde{S} - f_{B_R}\tilde{S}\|_{L^{\alpha}(B_R)}^{\alpha-1}.$$

Testing (3.36) with  $g = z_R$ , we find

$$\int_{\mathbb{R}^d} \tilde{S} \operatorname{div}(z_R) = 2 \int_{\mathbb{R}^d} \mathcal{D}(z_R) : \tilde{q} - \int_{\mathbb{R}^d} z_R \cdot f,$$

and thus, using the properties of  $z_R$ ,

$$\|\tilde{S} - \oint_{B_R} \tilde{S}\|_{L^{\alpha}(B_R)} \lesssim \|f\|_{W^{-1,\alpha}(B_R)} + \|\tilde{q}\|_{L^{\alpha}(B_R)}.$$

Combined with (3.35), this yields the conclusion (2.19).

#### 4. Homogenization

This section is devoted to the proof of Theorems 1 and 3. While Tartar's oscillating test function method as used in [10] is not quite appropriate to the present setting without uniform separation, we provide an alternative argument based on div-curl ideas combined with the extension result in Theorem 4, as inspired by the work of Jikov [20, 21] on homogenization problems with stiff inclusions (see also [22, Section 3.2]).

4.1. Construction of correctors. We start with the proof of Theorem 1, which we shall deduce from our results in [10] for uniformly separated particles, via an approximation argument together with suitable a priori estimates. The improved pressure estimates in Proposition 2 are deduced simultaneously.

Proof of Theorem 1 and Proposition 2. Given  $2 \leq r \neq \frac{2d}{d-2}$  and  $1 \leq \alpha \leq 2 \wedge \frac{2dr}{r(d-2)+2d}$ , with  $\alpha < \frac{d}{d-1}$  if r = 2, we assume that interparticle distances satisfy

$$\sum_{n} \mathbb{E} \left[ \mu_r(\rho_n)^{\frac{2\alpha}{2-\alpha}} \mathbb{1}_{0 \in I_n} \right] < \infty, \tag{4.1}$$

and we shall then prove Theorem 1, with pressure  $\Sigma_E$  in  $L^{\alpha}(\Omega)$  provided  $\alpha > 1$ . Optimizing in r further yields Proposition 2. We split the proof into two main steps.

Step 1. Approximations with uniformly separated particles. For  $0 < \kappa \leq \frac{\delta}{2}$ , we consider the restricted inclusions

$$I_n^{\kappa} := \{ x \in I_n : \operatorname{dist}(x, \partial I_n) > \kappa \}, \qquad \mathcal{I}^{\kappa} := \bigcup_n I_n^{\kappa},$$

which still satisfy Assumptions  $(\mathbf{H}_{\delta}^{\circ})$  and  $(\mathbf{H}_{\delta}')$  with  $\delta$  replaced by  $\frac{\delta}{2}$  and with minimal interparticle distance  $\rho_n^{\circ} \geq \kappa$ , cf. (2.3), that is,  $(I_n^{\kappa} + \kappa B) \cap (I_m^{\kappa} + \kappa B) = \emptyset$  for all  $n \neq m$ . In this context with uniformly separated particles, we may apply [10, Proposition 2.1], which ensures the existence and uniqueness of a corrector  $\psi_E^{\kappa}$  and of an associated pressure  $\Sigma_E^{\kappa}$  that satisfy the different properties stated in Theorem 1 with  $\mathcal{I}$  replaced by  $\mathcal{I}^{\kappa}$ . In addition, we show that the following moment bounds hold uniformly with respect to the parameter  $\kappa > 0$ : for  $\alpha$  as in the moment condition (4.1),

$$\mathbb{E}\left[|\nabla\psi_E^{\kappa}|^2\right] \lesssim |E|^2, \tag{4.2}$$

$$\mathbb{E}\left[|\Sigma_E^{\kappa}|^{\alpha} \mathbb{1}_{\mathbb{R}^d \setminus \mathcal{I}^{\kappa}}\right] \lesssim |E|^{\alpha}.$$
(4.3)

These two estimates are established in the following two substeps.

Substep 1.1. Proof of (4.2).

In terms of the extension operator  $P_n$  that we have constructed in Proposition 3.1, we consider the following stationary random vector field,

$$\phi_E^\circ := -\sum_n P_n(E(x-x_n)),$$

and we show that it satisfies

 $(\mathcal{D}(\phi_E^{\circ}) + E)|_{\mathcal{I}} = 0, \quad \operatorname{div}(\phi_E^{\circ}) = 0, \quad \mathbb{E}\left[|\mathcal{D}(\phi_E^{\circ})|^2\right] \lesssim |E|^2, \quad \mathbb{E}\left[\mathcal{D}(\phi_E^{\circ})\right] = 0.$  (4.4) The first two properties follow from the construction of  $P_n$  with  $\mathcal{D}(P_n(E(x - x_n)))|_{I_n} = E$ and  $\operatorname{div}(P_n(E(x - x_n))) = 0$ . Next, stationarity allows to write

$$\mathbb{E}\left[|\mathbf{D}(\phi_E^{\circ})|^2\right] = \mathbb{E}\left[\int_B |\mathbf{D}(\phi_E^{\circ})|^2\right] = \mathbb{E}\left[\frac{1}{|B|}\sum_n \int_{I_n^+ \cap B} |\mathbf{D}(P_n(E(x-x_n)))|^2\right],$$

hence, by Proposition 3.1,

$$\mathbb{E}\left[|\mathbf{D}(\phi_E^{\circ})|^2\right] \lesssim |E|^2 \mathbb{E}\left[\frac{1}{|B|} \sum_{n: I_n^+ \cap B \neq \varnothing} \mu_2(\rho_n)^2\right].$$

This can then be estimated as follows, by stationarity,

$$\mathbb{E}\left[|\mathbf{D}(\phi_E^{\circ})|^2\right] \lesssim |E|^2 \mathbb{E}\left[\frac{1}{|B|} \int_{B_3} \sum_n \mu_2(\rho_n)^2 \mathbb{1}_{I_n}\right] \lesssim |E|^2 \mathbb{E}\left[\sum_n \mu_2(\rho_n)^2 \mathbb{1}_{0 \in I_n}\right],$$

so that the third property in (4.4) follows from the moment assumption (4.1) with r = 2 and  $\alpha = 1$ . Finally, stationarity allows to write for all R > 0,

$$\mathbb{E}\left[\mathcal{D}(\phi_E^{\circ})\right] = \mathbb{E}\left[\int_{B_R} \mathcal{D}(\phi_E^{\circ})\right],$$

hence, inserting the definition of  $D(\phi_E^{\circ}) \in L^2(\Omega)$ , and letting  $R \uparrow \infty$  to neglect boundary terms,

$$\mathbb{E}\left[\mathrm{D}(\phi_{E}^{\circ})\right] = -\lim_{R\uparrow\infty} \mathbb{E}\left[|B_{R}|^{-1} \sum_{n:I_{n}^{+}\subset B_{R}} \int_{I_{n}^{+}} \mathrm{D}(P_{n}(E(x-x_{n})))\right].$$

Combined with the observation that  $\int_{I_n^+} D(P_n(E(x-x_n))) = 0$ , this concludes the proof of the last property in (4.4).

With this construction at hand, and noting that  $\mathcal{I}^{\kappa} \subset \mathcal{I}$ , testing the variational problem (2.6) for  $\psi_E^{\kappa}$  with the test function  $\phi_E^{\circ}$  yields

$$\mathbb{E}\left[|\mathbf{D}(\psi_E^{\kappa}) + E|^2\right] \le \mathbb{E}\left[|\mathbf{D}(\phi_E^{\circ}) + E|^2\right] \lesssim |E|^2.$$
(4.5)

It remains to turn this into an a priori estimate on the full gradient  $\nabla \psi_E^{\kappa}$ . For that purpose, we decompose

$$|\nabla \psi_E^{\kappa}|^2 = 2|\mathbf{D}(\psi_E^{\kappa})|^2 - \nabla_j(\psi_E^{\kappa})_i \nabla_i(\psi_E^{\kappa})_j.$$
(4.6)

For all  $R \geq 1$ , choose a smooth averaging function  $\chi_R \in C_c^{\infty}(\mathbb{R}^d; \mathbb{R}^+)$  such that  $\chi_R$  is constant in  $B_R$ , vanishes outside  $B_{2R}$ , and satisfies  $\int_{\mathbb{R}^d} \chi_R = 1$  and  $|\nabla \chi_R| \leq R^{-d-1}$ . An integration by parts together with the constraint  $\operatorname{div}(\psi_E^{\kappa}) = 0$  yields

$$\int_{\mathbb{R}^d} \chi_R \nabla_j (\psi_E^\kappa)_i \nabla_i (\psi_E^\kappa)_j = - \int_{\mathbb{R}^d} (\nabla \chi_R \otimes \psi_E^\kappa) : \nabla \psi_E^\kappa,$$

and thus, by definition of  $\chi_R$  and by scaling,

$$\left|\int_{\mathbb{R}^d} \chi_R \nabla_j(\psi_E^{\kappa})_i \nabla_i(\psi_E^{\kappa})_j\right| \lesssim \|R^{-1} \psi_E^{\kappa}(R\cdot)\|_{\mathrm{L}^2(B_2)} \|\nabla \psi_E^{\kappa}(R\cdot)\|_{\mathrm{L}^2(B_2)}$$

Passing to the limit  $R \uparrow \infty$  and appealing to the ergodic theorem, in view of the stationarity of  $\nabla \psi_E^{\kappa}$  and the sublinearity of  $\psi_E^{\kappa}$ , cf. (2.9), we deduce  $\mathbb{E}\left[\nabla_j(\psi_E^{\kappa})_i \nabla_i(\psi_E^{\kappa})_j\right] = 0$ , so that the decomposition (4.6) entails  $\mathbb{E}\left[|\nabla \psi_E^{\kappa}|^2\right] = 2\mathbb{E}\left[|D(\psi_E^{\kappa})|^2\right]$  and the bound (4.5) yields the claim (4.2).

Substep 1.2. Proof of (4.3).

We appeal to Lemma 3.2 in the following form (with s = 2 and  $p = \alpha'$ , with  $\alpha, r$  as in the moment condition (4.1)): there exists  $z_R^{\kappa} \in H_0^1(B_R)^d$  such that  $D(z_R^{\kappa})|_{\mathcal{I}^{\kappa}} = 0$  and

$$\operatorname{div}(z_R^{\kappa}) = \left(T_R^{\kappa} |T_R^{\kappa}|^{\alpha-2} - f_{B_R \setminus \mathcal{I}^{\kappa}} T_R^{\kappa} |T_R^{\kappa}|^{\alpha-2}\right) \mathbb{1}_{B_R \setminus \mathcal{I}^{\kappa}}, \qquad T_R^{\kappa} := \Sigma_E^{\kappa} - f_{B_R \setminus \mathcal{I}^{\kappa}} \Sigma_E^{\kappa},$$

and such that

$$\begin{aligned} \|\nabla z_R^{\kappa}\|_{\mathrm{L}^2(B_R)} &\lesssim_{\alpha,r} \quad \Lambda(B_R; r, \frac{2\alpha}{2-\alpha}) \|T_R^{\kappa}|T_R^{\kappa}|^{\alpha-2}\|_{\mathrm{L}^{\alpha'}(B_R \setminus \mathcal{I}^{\kappa})} \\ &\lesssim \quad \Lambda(B_R; r, \frac{2\alpha}{2-\alpha}) \|\Sigma_E^{\kappa} - \int_{B_R \setminus \mathcal{I}^{\kappa}} \Sigma_E^{\kappa}\|_{\mathrm{L}^{\alpha}(B_R \setminus \mathcal{I}^{\kappa})}^{\alpha-1} \end{aligned}$$

Testing the corrector equation (2.8) for  $(\psi_E^{\kappa}, \Sigma_E^{\kappa})$  with this test function  $z_R^{\kappa}$ , we find

$$\int_{B_R} \Sigma_E^{\kappa} \operatorname{div}(z_R^{\kappa}) = 2 \int_{B_R} \mathcal{D}(z_R^{\kappa}) : \mathcal{D}(\psi_E^{\kappa}),$$

and thus, using the above properties of  $z_R^{\kappa}$ ,

$$\|\Sigma_E^{\kappa} - \int_{B_R \setminus \mathcal{I}^{\kappa}} \Sigma_E^{\kappa}\|_{\mathcal{L}^{\alpha}(B_R \setminus \mathcal{I}^{\kappa})} \lesssim_{\alpha, r} \Lambda(B_R; r, \frac{2\alpha}{2-\alpha}) \|\mathcal{D}(\psi_E^{\kappa})\|_{\mathcal{L}^2(B_R)}.$$
(4.7)

Dividing both sides by  $R^{d/\alpha}$ , recalling the definition (2.20)–(2.21) of  $\Lambda$ , passing to the limit  $R \uparrow \infty$ , and appealing to the ergodic theorem, recalling that  $\nabla \psi_E^{\kappa}$  and  $\Sigma_E^{\kappa}$  are stationary with vanishing expectation, and using (4.2), we deduce

$$\mathbb{E}\left[|\Sigma_E^{\kappa}|^{\alpha}\mathbb{1}_{\mathbb{R}^d\setminus\mathcal{I}^{\kappa}}\right]^{\frac{1}{\alpha}} \lesssim |E|\left(1+\sum_n \mathbb{E}\left[\mu_r(\rho_n)^{\frac{2\alpha}{2-\alpha}}\mathbb{1}_{0\in I_n}\right]\right)^{\frac{2-\alpha}{2\alpha}}.$$

and the claim (4.3) follows from the moment assumption (4.1).

## Step 2. Conclusion.

In view of the uniform bounds (4.2) and (4.3), provided  $\alpha > 1$ , we may consider some weak limit point  $(\nabla \psi_E, \Sigma_E \mathbb{1}_{\mathbb{R}^d \setminus \mathcal{I}})$  of  $\{(\nabla \psi_E^{\kappa}, \Sigma_E^{\kappa} \mathbb{1}_{\mathbb{R}^d \setminus \mathcal{I}^{\kappa}})\}_{\kappa>0}$  in  $L^2(\Omega)^{d \times d} \times L^{\alpha}(\Omega)$  as  $\kappa \downarrow 0$ . It follows that  $\nabla \psi_E$  is stationary with vanishing expectation and finite second moments, that it satisfies div $(\psi_E) = 0$  and  $(D(\psi_E) + E)|_{\mathcal{I}} = 0$ , and that  $D(\psi_E)$  is the unique solution of the limiting variational problem (2.6). Moreover, passing to the limit in the weak formulation of (2.8), we find

$$2\int_{\mathbb{R}^d} \mathcal{D}(g) : \mathcal{D}(\psi_E) = \int_{\mathbb{R}^d} \Sigma_E \operatorname{div}(g), \qquad \forall g \in C_c^1(\mathbb{R}^d)^d : \mathcal{D}(g)|_{\mathcal{I}} = 0,$$
(4.8)

hence, in particular,

$$-\Delta \psi_E + \nabla \Sigma_E = 0, \qquad \text{in } \mathbb{R}^d \setminus \mathcal{I}.$$
(4.9)

The pressure field  $\Sigma_E$  in this equation is uniquely defined up to a global constant in view of the almost sure connectedness of  $\mathbb{R}^d \setminus \mathcal{I}$ , and is thus fully determined by the condition  $\mathbb{E}[\Sigma_E \mathbb{1}_{\mathbb{R}^d \setminus \mathcal{I}}] = 0$ . In addition, in view of the regularity of the particle boundaries, cf. Assumption  $(\mathbf{H}^{\circ}_{\delta})$ , the regularity theory for the Stokes equation (e.g. [13, Section IV])

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entails that  $(\psi_E, \Sigma_E)$  is  $C^2$  smooth in  $\mathbb{R}^d \setminus \mathcal{I}$  up to the boundary, and equation (4.9) is thus satisfied in the strong sense. Next, for all n, for all  $V \in \mathbb{R}^d$  and  $\Theta \in \mathbb{M}^{\text{skew}}$ , in terms of the cut-off function  $w_n$  that we have constructed in Lemma 3.3, we may test equation (4.8) with  $g = w_n(V + \Theta(x - x_n)) \in W_0^{1,\alpha'}(I_n^+)$ , which indeed satisfies  $D(g)|_{\mathcal{I}} = 0$ , and an integration by parts then yields

$$0 = \int_{\mathbb{R}^d} D\left(w_n(V + \Theta(x - x_n))\right) : \sigma(\psi_E + Ex, \Sigma_E)$$
$$= -\int_{\partial I_n} (V + \Theta(x - x_n)) \cdot \sigma(\psi_E + Ex, \Sigma_E)\nu,$$

showing that the boundary conditions in (2.8) are almost surely satisfied in a pointwise sense. Finally, the weak convergence of  $(\nabla \psi_E, \Sigma_E \mathbb{1}_{\mathbb{R}^d \setminus \mathcal{I}})(\frac{\cdot}{\varepsilon})$  to 0 in (2.9) follows from  $\mathbb{E}[(\nabla \psi_E, \Sigma_E \mathbb{1}_{\mathbb{R}^d \setminus \mathcal{I}})] = 0$  by the ergodic theorem, while the sublinearity of  $\psi_E$  in form of the strong convergence of  $\varepsilon \psi_E(\frac{\cdot}{\varepsilon})$  to 0 is a standard result for random fields with stationary gradient having vanishing expectation, e.g. [22, Section 7].

4.2. Extension of fluxes. Applying Theorem 4 to the corrector  $\psi_E$ , cf. (2.8), and to the solution  $u_{\varepsilon}$  of the Stokes problem (2.13), we obtain the following useful extension result for the fluxes

$$q_E := D(\psi_E) + E, \qquad p_\varepsilon := D(u_\varepsilon).$$

**Corollary 4.1.** On top of Assumptions  $(\mathbf{H}^{\circ}_{\delta})$  and  $(\mathbf{H}'_{\delta})$ , given a bounded Lipschitz domain  $U \subset \mathbb{R}^d$ , and given  $2 \leq r \neq \frac{2d}{d-2}$  and  $1 < \alpha \leq 2 \land \frac{2dr}{r(d-2)+2d}$ , with  $\alpha < \frac{d}{d-1}$  if r = 2, assume that interparticle distances satisfy the following moment condition, almost surely,

$$\limsup_{\varepsilon \downarrow 0} \varepsilon^d \sum_{n \in \mathcal{N}_{\varepsilon}(U)} \mu_r(\rho_{n;U,\varepsilon})^{\frac{2\alpha}{2-\alpha}} < \infty.$$
(4.10)

Then the following properties hold.

(i) For all  $E \in \mathbb{M}_0^{\text{sym}}$ , there exist a stationary element  $\tilde{q}_E \in L^{\alpha}(\Omega; L^{\alpha}_{\text{loc}}(\mathbb{R}^d)_{\text{sym}}^{d \times d})$  with  $\operatorname{tr}(\tilde{q}_E) = 0$ , and an associated stationary pressure field  $\tilde{\Sigma}_E \in L^{\alpha}(\Omega; L^{\alpha}_{\text{loc}}(\mathbb{R}^d))$ , such that almost surely

$$\begin{aligned} & (\tilde{q}_E, \tilde{\Sigma}_E)|_{\mathbb{R}^d \setminus \mathcal{I}} = (q_E, \Sigma_E)|_{\mathbb{R}^d \setminus \mathcal{I}}, \\ & -\operatorname{div}(2\tilde{q}_E - \tilde{\Sigma}_E \operatorname{Id}) = 0, \quad in \ \mathbb{R}^d, \end{aligned}$$
(4.11)

and

 $\|\tilde{q}_E\|_{\mathcal{L}^{\alpha}(\Omega)} + \|\tilde{\Sigma}_E - \mathbb{E}\big[\tilde{\Sigma}_E\big]\|_{\mathcal{L}^{\alpha}(\Omega)} \lesssim_{\alpha, r} |E|.$ 

(ii) There exists  $\tilde{p}_{\varepsilon} \in L^{\alpha}(\Omega; L^{\alpha}(U)_{\text{sym}}^{d \times d})$  with  $\operatorname{tr}(\tilde{p}_{\varepsilon}) = 0$ , and an associated pressure field  $\tilde{S}_{\varepsilon} \in L^{\alpha}(\Omega; L^{\alpha}(U))$ , such that almost surely

$$(\tilde{p}_{\varepsilon}, S_{\varepsilon})|_{U \setminus \mathcal{I}_{\varepsilon}(U)} = (p_{\varepsilon}, S_{\varepsilon})|_{U \setminus \mathcal{I}_{\varepsilon}(U)},$$
  
$$-\operatorname{div}(2\tilde{p}_{\varepsilon} - \tilde{S}_{\varepsilon} \operatorname{Id}) = f \mathbb{1}_{U \setminus \mathcal{I}_{\varepsilon}(U)}, \quad in \ U,$$
(4.12)

and

$$\limsup_{\varepsilon \downarrow 0} \left( \|\tilde{p}_{\varepsilon}\|_{\mathrm{L}^{\alpha}(U)} + \|\tilde{S}_{\varepsilon} - f_{U}\tilde{S}_{\varepsilon}\|_{\mathrm{L}^{\alpha}(U)} \right) \lesssim_{U,\alpha,r} \|f\|_{\mathrm{L}^{\frac{2d}{d+2}}(U)}$$

*Proof.* We split the proof into two steps.

Step 1. Proof of (i)

The corrector equation (2.8) ensures that the flux  $q_E = D(\psi_E) + E \in L^2(\Omega; L^2_{loc}(\mathbb{R}^d)^{d \times d}_{sym})$ satisfies  $tr(q_E) = 0$  and

$$\int_{\mathbb{R}^d} \mathcal{D}(g) : q_E = 0, \qquad \forall g \in C_c^1(\mathbb{R}^d)^d : \operatorname{div}(g) = 0, \, \mathcal{D}(g)|_{\mathcal{I}} = 0.$$

Given  $\alpha, r$  as in (4.10), Theorem 4 provides an extension  $\tilde{q}_E \in L^{\alpha}(\Omega; L^{\alpha}_{\text{loc}}(\mathbb{R}^d)^{d \times d}_{\text{sym}})$  with  $\operatorname{tr}(\tilde{q}_E) = 0$ , and an associated pressure field  $\tilde{\Sigma}_E \in L^{\alpha}(\Omega; L^{\alpha}_{\text{loc}}(\mathbb{R}^d))$ , such that

$$\widetilde{q}_E|_{\mathbb{R}^d\setminus\mathcal{I}} = q_E|_{\mathbb{R}^d\setminus\mathcal{I}}, \quad \text{and} \quad -\operatorname{div}(2\widetilde{q}_E - \widetilde{\Sigma}_E \operatorname{Id}) = 0, \quad \text{in } \mathbb{R}^d, \quad (4.13)$$

and such that the following estimate holds, for all  $R \ge 1$ ,

$$\|\tilde{q}_E\|_{\mathcal{L}^{\alpha}(B_R)} + \|\tilde{\Sigma}_E - f_{B_R}\tilde{\Sigma}_E\|_{\mathcal{L}^{\alpha}(B_R)} \lesssim_{\alpha,r} \Lambda(B_R; r, \frac{2\alpha}{2-\alpha}) \|q_E\|_{\mathcal{L}^2(\widehat{B}_R \setminus \mathcal{I})}.$$
(4.14)

In addition, the construction in the proof of Theorem 4 ensures that  $\tilde{q}_E$  can be chosen stationary. Since  $\tilde{q}_E$  coincides with  $q_E = D(\psi_E) + E$  on  $\mathbb{R}^d \setminus \mathcal{I}$ , we deduce from (4.13), in particular,

$$-\Delta \psi_E + \nabla \tilde{\Sigma}_E = 0, \qquad \text{in } \mathbb{R}^d \setminus \mathcal{I}.$$

In view of (2.8), recalling that  $\mathbb{R}^d \setminus \mathcal{I}$  is almost surely connected, we deduce that the pressure  $\tilde{\Sigma}_E$  must coincide with  $\Sigma_E$  in  $\mathbb{R}^d \setminus \mathcal{I}$  up to a global constant. Therefore,  $\tilde{\Sigma}_E$  is uniquely determined for instance by the choice  $\tilde{\Sigma}_E|_{\mathbb{R}^d \setminus \mathcal{I}} = \Sigma_E|_{\mathbb{R}^d \setminus \mathcal{I}}$ . For this choice, as  $\tilde{q}_E$  and  $\Sigma_E \mathbb{1}_{\mathbb{R}^d \setminus \mathcal{I}}$  are stationary, uniqueness entails that  $\tilde{\Sigma}_E$  is also stationary.

Dividing both sides of (4.14) by  $R^{d/\alpha}$ , recalling the definition (2.20) of  $\Lambda$ , passing to the limit  $R \uparrow \infty$ , appealing to the ergodic theorem, in view of the stationarity of  $\tilde{q}_E, \tilde{\Sigma}_E$ , and using the energy bound  $\mathbb{E}\left[|q_E|^2\right] \lesssim |E|^2$ , we obtain

$$\|\tilde{q}_E\|_{\mathcal{L}^{\alpha}(\Omega)} + \|\tilde{\Sigma}_E - \mathbb{E}\big[\tilde{\Sigma}_E\big]\|_{\mathcal{L}^{\alpha}(\Omega)} \lesssim_{\alpha, r} |E| \Big(1 + \sum_n \mathbb{E}\big[\mu_r(\rho_n)^{\frac{2\alpha}{2-\alpha}} \mathbb{1}_{0 \in I_n}\big]\Big)^{\frac{2-\alpha}{2\alpha}}$$

Combined with the moment condition (4.10), with  $\mu_r(\rho_n) \leq \mu_r(\rho_{n;U,\varepsilon})$ , this yields the conclusion.

Step 2. Proof of (ii).

Equation (2.13) ensures that the flux  $p_{\varepsilon} = D(u_{\varepsilon}) \in L^2(\Omega; L^2(U)_{sym}^{d \times d})$  satisfies  $tr(p_{\varepsilon}) = 0$ and

$$2\int_{U} \mathcal{D}(g) : p_{\varepsilon} = \int_{U \setminus \mathcal{I}_{\varepsilon}(U)} g \cdot f, \qquad \forall g \in C_{c}^{1}(U)^{d} : \operatorname{div}(g) = 0, \ \mathcal{D}(g)|_{\mathcal{I}_{\varepsilon}(U)} = 0.$$

Given  $\alpha, r$  as in (4.10), Theorem 4 provides an extension  $\tilde{p}_{\varepsilon} \in L^{\alpha}(\Omega; L^{\alpha}(U)^{d \times d}_{sym})$  with  $tr(\tilde{p}_{\varepsilon}) = 0$ , and an associated pressure field  $\tilde{S}_{\varepsilon} \in L^{\alpha}(\Omega; L^{\alpha}(U))$ , such that

$$\tilde{p}_{\varepsilon}|_{U\setminus\mathcal{I}_{\varepsilon}(U)} = p_{\varepsilon}|_{U\setminus\mathcal{I}_{\varepsilon}(U)}, \quad \text{and} \quad -\operatorname{div}(2\tilde{p}_{\varepsilon}-\tilde{S}_{\varepsilon}\operatorname{Id}) = f\mathbb{1}_{U\setminus\mathcal{I}_{\varepsilon}(U)}, \quad \text{in } U,$$

and by scaling, the estimate (2.19) takes on the following guise,

$$\begin{split} \|\tilde{p}_{\varepsilon}\|_{\mathcal{L}^{\alpha}(U)} + \|S_{\varepsilon} - f_{U} S_{\varepsilon}\|_{\mathcal{L}^{\alpha}(U)} \\ \lesssim_{U,\alpha,r} \left( |U| + \varepsilon^{d} \sum_{n \in \mathcal{N}_{\varepsilon}(U)} \mu_{r}(\rho_{n;U,\varepsilon})^{\frac{2\alpha}{2-\alpha}} \right)^{\frac{2-\alpha}{2\alpha}} \left( \|f\|_{\mathcal{L}^{\frac{2d}{d+2}}(U)} + \|p_{\varepsilon}\|_{\mathcal{L}^{2}(U \setminus \mathcal{I}_{\varepsilon}(U))} \right). \end{split}$$

Combined with the energy bound  $\|p_{\varepsilon}\|_{L^{2}(U\setminus\mathcal{I}_{\varepsilon}(U))} \lesssim \|f\|_{L^{2d/(d+2)}(U)}$ , and with the moment condition (4.10), this yields the conclusion.

**Remark 4.2.** In view of the construction in the proof of Theorem 4, it is easily checked that the above-constructed extended fluxes  $\tilde{q}_E$ ,  $\tilde{p}_{\varepsilon}$  can be viewed as limiting fluxes for corresponding Stokes problems with a suspension of droplets with diverging shear viscosity. More precisely, for all  $\kappa > 0$ , we consider the following corrector problem

$$\begin{cases} -\operatorname{div}(2(\mathbb{1}_{\mathbb{R}^d\setminus\mathcal{I}}+\kappa\mathbb{1}_{\mathcal{I}})(\mathrm{D}(\psi_E^{\kappa})+E))+\nabla\Sigma_E^{\kappa}=0, & \text{in } \mathbb{R}^d,\\ \operatorname{div}(\psi_E^{\kappa})=0, & \text{in } \mathbb{R}^d. \end{cases}$$

Under the assumptions of Corollary 4.1, in the limit  $\kappa \uparrow \infty$ , there holds  $D(\psi_E^{\kappa}) \rightarrow D(\psi_E)$  in  $L^2(\Omega)$  and corresponding fluxes converge,

$$2(\mathbb{1}_{\mathbb{R}^d \setminus \mathcal{I}} + \kappa \mathbb{1}_{\mathcal{I}})(\mathrm{D}(\psi_E^{\kappa}) + E) - \Sigma_E^{\kappa} \mathrm{Id} \quad \rightharpoonup \quad \tilde{q}_E, \qquad \mathrm{in } \mathrm{L}^{\alpha}(\Omega),$$

and a similar result holds for  $\tilde{p}_{\varepsilon}$ . We skip the detail for shortness.

Next, we compute  $\mathbb{E}[\tilde{q}_E]$  and  $\mathbb{E}[\tilde{\Sigma}_E]$ , which happen to provide alternative definitions of the effective constants  $\bar{B}, \bar{b}$ . Note in particular that these ensemble averages do not depend on the actual choice of the extension  $\tilde{q}_E$  in Corollary 4.1(i).

**Lemma 4.3** (Effective constants). On top of Assumptions  $(\mathbf{H}^{\circ}_{\delta})$  and  $(\mathbf{H}'_{\delta})$ , let  $(\tilde{q}_E, \tilde{\Sigma}_E)$  be defined as in Corollary 4.1(i) for some  $\alpha > 1$ . Then we have almost surely, as  $\varepsilon \downarrow 0$ ,

 $\tilde{q}_E(\frac{\cdot}{\varepsilon}) \to \mathbb{E}\left[\tilde{q}_E\right] = \bar{B}E, \qquad \tilde{\Sigma}_E(\frac{\cdot}{\varepsilon}) \to \mathbb{E}\left[\tilde{\Sigma}_E\right] = -\bar{b}: E, \qquad weakly \ in \ \mathcal{L}^{\alpha}_{\mathrm{loc}}(\mathbb{R}^d).$ (4.15) In addition, provided  $\alpha \geq \frac{2d}{d+2}$ , these convergences are almost surely strong in  $H^{-1}_{\mathrm{loc}}(\mathbb{R}^d).$ 

*Proof.* We split the proof into two steps.

Step 1. Proof of weak convergences (4.15).

As  $\tilde{q}_E$  and  $\Sigma_E$  are stationary, the ergodic theorem implies almost surely the weak convergences  $\tilde{q}_E(\frac{\cdot}{\varepsilon}) \rightarrow \mathbb{E}[\tilde{q}_E]$  and  $\tilde{\Sigma}_E(\frac{\cdot}{\varepsilon}) \rightarrow \mathbb{E}[\tilde{\Sigma}_E]$  in  $\mathcal{L}^{\alpha}_{\text{loc}}(\mathbb{R}^d)$ , and it remains to compute these two expectations. For that purpose, up to an approximation argument as in the proof of Theorem 1, we may assume without loss of generality  $\alpha > \frac{2d}{d+2}$ . We split the proof into two further substeps.

Substep 1.1. Proof that  $\bar{B}E = \mathbb{E}[\tilde{q}_E]$ .

For all  $R \geq 1$ , we set  $\chi_R := R^{-d}\chi(\frac{1}{R}\cdot)$ , for some smooth averaging function  $\chi \in C_c^{\infty}(\mathbb{R}^d; \mathbb{R}^+)$ such that  $\chi$  is constant in B, vanishes outside  $B_2$ , and satisfies  $\int_{\mathbb{R}^d} \chi = 1$ . Given  $E' \in \mathbb{M}_0^{\text{sym}}$ , as  $q_E = D(\psi_E) + E$  is stationary, the definition (2.7) of  $\bar{B}$  and the ergodic theorem yield almost surely,

$$E': \bar{\boldsymbol{B}}E = \mathbb{E}\left[q_{E'}: q_E\right] = \lim_{R \uparrow \infty} \int_{\mathbb{R}^d} \chi_R q_{E'}: q_E.$$
(4.16)

Since  $q_{E'}$  vanishes in  $\mathcal{I}$ , cf. (2.8), and since  $q_E$  coincides with its extension  $\tilde{q}_E$  in  $\mathbb{R}^d \setminus \mathcal{I}$ , we find

$$q_{E'}: q_E = q_{E'}: \tilde{q}_E = E': \tilde{q}_E + \mathcal{D}(\psi_{E'}): \tilde{q}_E.$$

Inserting this identity into (4.16), and noting that the ergodic theorem implies the almost sure convergence  $\int_{\mathbb{R}^d} \chi_R \tilde{q}_E \to \mathbb{E}[\tilde{q}_E]$ , we find

$$E': \bar{\boldsymbol{B}}E = E': \mathbb{E}\left[\tilde{q}_E\right] + \lim_{R\uparrow\infty} \int_{\mathbb{R}^d} \chi_R \, \mathcal{D}(\psi_{E'}): \tilde{q}_E.$$
(4.17)

In order to prove the claim  $\bar{B}E = \mathbb{E}[\tilde{q}_E]$ , it remains to show that the last limit vanishes,

$$\lim_{R\uparrow\infty} \int_{\mathbb{R}^d} \chi_R \, \mathcal{D}(\psi_{E'}) : \tilde{q}_E = 0.$$
(4.18)

Integrating by parts, using the properties (4.11) of the extensions  $(\tilde{q}_E, \Sigma_E)$ , and using the constraint div $(\psi_{E'}) = 0$ , we find

$$\int_{\mathbb{R}^d} \chi_R D(\psi_{E'}) : \tilde{q}_E = \int_{\mathbb{R}^d} D(\chi_R \psi_{E'}) : \tilde{q}_E - \int_{\mathbb{R}^d} (\nabla \chi_R \otimes \psi_{E'}) : \tilde{q}_E$$
$$= \frac{1}{2} \int_{\mathbb{R}^d} \tilde{\Sigma}_E \operatorname{div}(\chi_R \psi_{E'}) - \int_{\mathbb{R}^d} (\nabla \chi_R \otimes \psi_{E'}) : \tilde{q}_E$$
$$= -\frac{1}{2} \int_{\mathbb{R}^d} (\nabla \chi_R \otimes \psi_{E'}) : (2\tilde{q}_E - \tilde{\Sigma}_E \operatorname{Id}).$$

The relation  $\operatorname{div}(\psi_{E'}) = 0$  entails  $\int_{\mathbb{R}^d} \nabla \chi_R \cdot \psi_{E'} = 0$ , which allows to add any constant to the pressure  $\tilde{\Sigma}_E$  in the right-hand side. In view of the properties of the averaging function  $\chi_R$ , Hölder's inequality leads to

$$\left| \int_{\mathbb{R}^{d}} \chi_{R} \operatorname{D}(\psi_{E'}) : \tilde{q}_{E} \right| \lesssim \int_{B_{2}} \left| \frac{1}{R} \psi_{E'}(R \cdot) \right| \left( \left| \tilde{q}_{E}(R \cdot) \right| + \left| \tilde{\Sigma}_{E}(R \cdot) - \int_{B_{2}} \tilde{\Sigma}_{E}(R \cdot) \right| \right)$$

$$\lesssim \left\| \frac{1}{R} \psi_{E'}(R \cdot) \right\|_{\operatorname{L}^{\alpha'}(B_{2})} \left( \left\| \tilde{q}_{E}(R \cdot) \right\|_{\operatorname{L}^{\alpha}(B_{2})} + \left\| \tilde{\Sigma}_{E}(R \cdot) - \int_{B_{2}} \tilde{\Sigma}_{E}(R \cdot) \right\|_{\operatorname{L}^{\alpha}(B_{2})} \right).$$

$$(4.19)$$

As the choice  $\alpha > \frac{2d}{d+2}$  entails  $\alpha' < \frac{2d}{d-2}$ , we can use the sublinearity of  $\psi_{E'}$  in  $\mathcal{L}^{\alpha'}$ , cf. (2.9), together with the boundedness of  $\{(\tilde{q}_E, \tilde{\Sigma}_E(R\cdot) - \int_{B_2} \tilde{\Sigma}_E(R\cdot))\}_R$  in  $\mathcal{L}^{\alpha}(B_2)$ , cf. Corollary 4.1(i), and the claim (4.18) follows.

Substep 1.2. Proof that  $\bar{\boldsymbol{b}}: E = -\mathbb{E}[\tilde{\Sigma}_E].$ 

In terms of the cut-off function  $w_n$  that we have constructed in Lemma 3.3, integrating by parts, and recalling that the corrector equation (2.8) yields  $\operatorname{div}(\sigma(\psi_E + Ex, \Sigma_E)) = 0$  in  $I_n^+ \setminus I_n$ , the definition (2.12) of  $\bar{\boldsymbol{b}}$  becomes

$$\begin{split} \bar{\boldsymbol{b}} : E &= \frac{1}{d} \mathbb{E} \bigg[ \sum_{n} \frac{\mathbbm{1}_{I_n}}{|I_n|} \int_{\partial I_n} (x - x_n) \cdot \sigma(\psi_E + Ex, \Sigma_E) \nu \bigg] \\ &= -\frac{1}{d} \mathbb{E} \bigg[ \sum_{n} \frac{\mathbbm{1}_{I_n}}{|I_n|} \int_{I_n^+ \setminus I_n} \operatorname{div} \big( w_n \, \sigma(\psi_E + Ex, \Sigma_E) \, (x - x_n) \big) \big] \\ &= -\frac{1}{d} \mathbb{E} \bigg[ \sum_{n} \frac{\mathbbm{1}_{I_n}}{|I_n|} \int_{I_n^+ \setminus I_n} \mathrm{D} \left( (x - x_n) w_n \right) : \sigma(\psi_E + Ex, \Sigma_E) \bigg] \end{split}$$

Writing  $\sigma(\psi_E + Ex, \Sigma_E) = 2q_E - \Sigma_E \operatorname{Id} \operatorname{in} I_n^+ \setminus I_n$ , and using the extensions  $\tilde{q}_E$  and  $\tilde{\Sigma}_E$  as in (4.11), we are led to

$$\bar{\boldsymbol{b}}: E = \frac{1}{d} \mathbb{E} \bigg[ \sum_{n} \frac{\mathbbm{1}_{I_n}}{|I_n|} \int_{I_n} \mathcal{D} \left( (x - x_n) w_n \right) : \left( 2\tilde{q}_E - \tilde{\Sigma}_E \operatorname{Id} \right) \bigg].$$

Since  $D((x - x_n)w_n) = Id$  in  $I_n$  and since  $tr(\tilde{q}_E) = 0$ , we deduce

$$\bar{\boldsymbol{b}}: E = -\mathbb{E}\bigg[\sum_{n} \frac{\mathbb{1}_{I_n}}{|I_n|} \int_{I_n} \tilde{\Sigma}_E\bigg],$$

and the claim  $\bar{\boldsymbol{b}}: E = -\mathbb{E}[\tilde{\Sigma}_E]$  easily follows by stationarity.

Step 2. Proof of strong convergences in  $H_{\text{loc}}^{-1}(\mathbb{R}^d)$ . For  $\alpha > \frac{2d}{d+2}$ , strong convergences in  $H_{\text{loc}}^{-1}(\mathbb{R}^d)$  follow from (4.15) and the compact Rellich embedding. It remains to consider the critical case  $\alpha = \frac{2d}{d+2}$ , for which we appeal to a two-scale argument inspired by [23, Lemma 1.15]. By stationarity, it suffices to prove  $\tilde{\alpha}_{\Sigma}(\dot{z}) \rightarrow \bar{B}E$  and  $\tilde{\Sigma}_{\Sigma}(z) \rightarrow \bar{B}$ . Extractly in  $H^{-1}(D)$  is the stationarity of  $\Delta z$  is  $\tilde{q}_E(\frac{\cdot}{\varepsilon}) \to \bar{B}E$  and  $\tilde{\Sigma}_E(\frac{\cdot}{\varepsilon}) \to -\bar{b}: E$  strongly in  $H^{-1}(B)$  almost surely as  $\varepsilon \downarrow 0$ . As the argument is the same for  $\tilde{q}_E$  and for  $\tilde{\Sigma}_E$ , we may focus on the former.

Let  $h \in H^1(B)$  be momentarily fixed. Given  $\eta > 0$ , we choose a partition  $\{Q_i\}_i$  of B into Lipschitz subsets with  $|Q_i| \simeq \eta^d$ . In these terms, we can decompose

$$\int_{B} h\left(\tilde{q}_{E}(\frac{\cdot}{\varepsilon}) - \bar{\boldsymbol{B}}E\right) = \sum_{i} \left(\int_{Q_{i}} h\right) \oint_{Q_{i}} \left(\tilde{q}_{E}(\frac{\cdot}{\varepsilon}) - \bar{\boldsymbol{B}}E\right) + \sum_{i} \int_{Q_{i}} \left(h - \oint_{Q_{i}} h\right) \left(\tilde{q}_{E}(\frac{\cdot}{\varepsilon}) - \bar{\boldsymbol{B}}E\right). \quad (4.20)$$

On the one hand, for all  $s \in (1, \infty)$ , noting that  $\mathbb{1}_{Q_i}$  belongs to  $W^{\frac{1}{s},s}(B)$ , we can bound

$$\left| \int_{Q_i} \left( \tilde{q}_E(\frac{\cdot}{\varepsilon}) - \bar{\boldsymbol{B}}E \right) \right| \leq \left\| \frac{\mathbb{1}_{Q_i}}{|Q_i|} \right\|_{W^{\frac{1}{s},s}(B)} \| \tilde{q}_E(\frac{\cdot}{\varepsilon}) - \bar{\boldsymbol{B}}E \|_{W^{-\frac{1}{s},s'}(B)}$$

and thus, further using the Sobolev embedding in form of  $\|h\|_{L^1(B)} \lesssim \|h\|_{H^1(B)}$ , we deduce for the first right-hand side term in (4.20),

$$\left|\sum_{i} \left(\int_{Q_{i}} h\right) \oint_{Q_{i}} \left(\tilde{q}_{E}(\frac{\cdot}{\varepsilon}) - \bar{\boldsymbol{B}}E\right)\right| \\ \lesssim \|h\|_{H^{1}(B)} \left(\sup_{i} \left\|\frac{\mathbb{1}_{Q_{i}}}{|Q_{i}|}\right\|_{W^{\frac{1}{s},s}(B)}\right) \|\tilde{q}_{E}(\frac{\cdot}{\varepsilon}) - \bar{\boldsymbol{B}}E\|_{W^{-\frac{1}{s},s'}(B)}. \quad (4.21)$$

On the other hand, using Hölder's inequality and the Poincaré–Sobolev embedding, the second right-hand side term in (4.20) can be estimated as

$$\begin{split} \left| \sum_{i} \int_{Q_{i}} \left( h - \oint_{Q_{i}} h \right) \left( \tilde{q}_{E}(\frac{\cdot}{\varepsilon}) - \bar{\boldsymbol{B}}E \right) \right| &\leq \sum_{i} \left\| h - \oint_{Q_{i}} h \right\|_{\mathrm{L}^{\frac{2d}{d-2}}(Q_{i})} \left\| \tilde{q}_{E}(\frac{\cdot}{\varepsilon}) - \bar{\boldsymbol{B}}E \right\|_{\mathrm{L}^{\frac{2d}{d+2}}(Q_{i})} \\ &\lesssim \sum_{i} \left\| \nabla h \right\|_{\mathrm{L}^{2}(Q_{i})} \left\| \tilde{q}_{E}(\frac{\cdot}{\varepsilon}) - \bar{\boldsymbol{B}}E \right\|_{\mathrm{L}^{\frac{2d}{d+2}}(Q_{i})} \\ &\leq \left\| \nabla h \right\|_{\mathrm{L}^{2}(B)} \left( \sum_{i} \left\| \tilde{q}_{E}(\frac{\cdot}{\varepsilon}) - \bar{\boldsymbol{B}}E \right\|_{\mathrm{L}^{\frac{2d}{d+2}}(Q_{i})} \right)^{\frac{1}{2}}. \end{split}$$

Combining this with (4.20) and (4.21), and taking the supremum over test functions  $h \in H^1(B)$ , we conclude for all  $s \in (1, \infty)$ ,

$$\begin{split} \|\tilde{q}_E(\frac{\cdot}{\varepsilon}) - \bar{\boldsymbol{B}}E\|_{H^{-1}(B)} \\ \lesssim \left( \sup_i \left\| \frac{\mathbb{1}_{Q_i}}{|Q_i|} \right\|_{W^{\frac{1}{s},s}(B)} \right) \|\tilde{q}_E(\frac{\cdot}{\varepsilon}) - \bar{\boldsymbol{B}}E\|_{W^{-\frac{1}{s},s'}(B)} + \left( \sum_i \|\tilde{q}_E(\frac{\cdot}{\varepsilon}) - \bar{\boldsymbol{B}}E\|_{\mathrm{L}^{\frac{2d}{d+2}}(Q_i)}^2 \right)^{\frac{1}{2}}. \end{split}$$

We now pass to the limit  $\varepsilon \downarrow 0$  in this estimate. Choosing  $2\frac{d-1}{d-2} < s < \infty$ , the compact Rellich embedding ensures that  $L^{\frac{2d}{d+2}}(B)$  is compactly embedded in  $W^{-\frac{1}{s},s'}(B)$ . Therefore, in view of (4.15) with  $\alpha = \frac{2d}{d+2}$ , we deduce  $\tilde{q}_E(\frac{1}{\varepsilon}) \to \bar{B}E$  strongly in  $W^{-\frac{1}{s},s'}(B)$  almost surely as  $\varepsilon \downarrow 0$ . Further using the stationarity and the boundedness of  $\tilde{q}_E(\frac{\cdot}{\varepsilon}) - 2\bar{B}E$  in  $L^{\frac{2d}{d+2}}(\Omega)$ , cf. Corollary 4.1(i), we get almost surely

$$\limsup_{\varepsilon \downarrow 0} \|\tilde{q}_E(\frac{\cdot}{\varepsilon}) - \bar{\boldsymbol{B}}E\|_{H^{-1}(B)} \lesssim \left(\sum_i |Q_i|^{\frac{d+2}{d}}\right)^{\frac{1}{2}}$$

Using that  $\sum_i |Q_i| \lesssim 1$  and  $|Q_i| \lesssim \eta^d$ , this turns into

$$\limsup_{\varepsilon \downarrow 0} \|\tilde{q}_E(\frac{\cdot}{\varepsilon}) - \bar{\boldsymbol{B}}E\|_{H^{-1}(B)} \lesssim \eta.$$

Finally letting the mesh  $\eta$  of the partition  $\{Q_i\}_i$  tend to 0, the conclusion follows.

4.3. **Proof of Theorem 3.** The moment condition (2.11) amounts to the following: for some  $2 \le r \ne \frac{2d}{d-2}$  and  $\frac{2d}{d+2} \le \alpha \le 2 \land \frac{2dr}{r(d-2)+2d}$ , with  $\alpha < \frac{d}{d-1}$  if r = 2, the interparticle distances satisfy almost surely

$$\limsup_{\varepsilon \downarrow 0} \varepsilon^d \sum_{n \in \mathcal{N}_{\varepsilon}(U)} \mu_r(\rho_{n;U,\varepsilon})^{\frac{2\alpha}{2-\alpha}} < \infty.$$
(4.22)

We split the proof into two steps. First, we establish the convergence of the velocity field by a direct div-curl argument inspired by the work of Jikov [20, 21] on homogenization problems with stiff inclusions (see also [22, Section 3.2]), and then we turn to the convergence of the pressure.

Step 1. Div-curl argument: we prove that almost surely, as  $\varepsilon \downarrow 0$ ,

$$\begin{array}{cccc} u_{\varepsilon} & \rightharpoonup & \bar{u}, & \text{weakly in } H^{1}_{0}(U), \\ \tilde{p}_{\varepsilon} & \rightharpoonup & \bar{\boldsymbol{B}} \operatorname{D}(\bar{u}), & \text{weakly in } \operatorname{L}^{\alpha}(U), \\ \tilde{S}_{\varepsilon} - \oint_{U} \tilde{S}_{\varepsilon} & \rightharpoonup & \bar{S}, & \text{weakly in } \operatorname{L}^{\alpha}(U), \end{array}$$
(4.23)

where  $(\bar{u}, \bar{S})$  is the solution of the homogenized equation (2.14). By a standard energy argument as e.g. in [10, Step 8.1 of the proof of Proposition 2.1], provided that  $f \in L^p(U)$ for some p > d, this weak convergence result easily implies the following corresponding corrector result, almost surely,

$$p_{\varepsilon} - \sum_{E \in \mathcal{E}} q_E(\frac{\cdot}{\varepsilon}) \nabla_E \bar{u} \to 0, \quad \text{strongly in } L^2(U),$$
$$u_{\varepsilon} - \bar{u} - \sum_{E \in \mathcal{E}} \varepsilon \psi_E(\frac{\cdot}{\varepsilon}) \nabla_E \bar{u} \to 0, \quad \text{strongly in } H^1_0(U), \quad (4.24)$$

where we recall the short-hand notation  $\nabla_E \bar{u} = E : D(\bar{u})$  and where  $\mathcal{E}$  stands for an orthonormal basis of  $\mathbb{M}_0^{\text{sym}}$ . We omit the proof of this standard consequence (4.24) and rather focus on the proof of (4.23).

For  $\kappa > 0$  we set for abbreviation  $U^{\kappa} := \{x \in U : \operatorname{dist}(x, \partial U) > \kappa\}$ . Since  $q_E|_{\mathcal{I}} = 0$  and  $p_{\varepsilon}|_{\mathcal{I}_{\varepsilon}(U)} = 0$ , since  $\tilde{q}_E$  and  $q_E$  coincide on  $\mathbb{R}^d \setminus \mathcal{I}$ , since  $\tilde{p}_{\varepsilon}$  and  $p_{\varepsilon}$  coincide on  $U \setminus \mathcal{I}_{\varepsilon}(U)$ , and since the definition (2.10) of  $\mathcal{I}_{\varepsilon}(U)$  entails  $\mathcal{I}_{\varepsilon}(U) \cap U^{\kappa} = (\varepsilon \mathcal{I}) \cap U^{\kappa}$  whenever  $\varepsilon < \frac{\kappa}{2}$ , we deduce the following identity on  $U^{\kappa}$  for  $\varepsilon < \frac{\kappa}{2}$ ,

$$\tilde{q}_E(\frac{\cdot}{\varepsilon}): p_{\varepsilon} = q_E(\frac{\cdot}{\varepsilon}): \tilde{p}_{\varepsilon}, \qquad (4.25)$$

and we aim at passing to the limit in both sides. Since the energy bound entails that  $(u_{\varepsilon})_{\varepsilon}$  is almost surely bounded in  $H^1_0(U)$ , since Corollary 4.1(ii) ensures that  $(\tilde{p}_{\varepsilon}, \tilde{S}_{\varepsilon})_{\varepsilon}$  is almost

surely bounded in  $L^{\alpha}(U)$ , further recalling (2.9) and Lemma 4.3, we find almost surely, up to extraction of a subsequence as  $\varepsilon \downarrow 0$ ,

$$\begin{array}{lll} q_E(\frac{\cdot}{\varepsilon}) & \rightharpoonup & E, & \text{weakly in } \mathrm{L}^2(U), \\ \tilde{q}_E(\frac{\cdot}{\varepsilon}) & \rightharpoonup & \bar{B}E, & \text{weakly in } \mathrm{L}^\alpha(U), \\ \tilde{\Sigma}_E(\frac{\cdot}{\varepsilon}) & \rightharpoonup & -\bar{b}:E, & \text{weakly in } \mathrm{L}^\alpha(U), \\ p_{\varepsilon} & \rightharpoonup & \mathrm{D}(u_0), & \text{weakly in } \mathrm{L}^2(U), \\ \tilde{p}_{\varepsilon} & \rightharpoonup & \tilde{p}_0, & \text{weakly in } \mathrm{L}^\alpha(U), \\ \tilde{S}_{\varepsilon} & \rightharpoonup & \tilde{S}_0, & \text{weakly in } \mathrm{L}^\alpha(U). \end{array}$$

$$(4.26)$$

for some  $u_0 \in H_0^1(U)^d$ ,  $\tilde{p}_0 \in L^{\alpha}(U)_{\text{sym}}^{d \times d}$ , and  $\tilde{S}_0 \in L^{\alpha}(U)$ . In case  $\alpha > \frac{2d}{d+2}$  (hence  $\alpha' < \frac{2d}{d-2}$ ), further appealing to the compact Rellich embedding and to the sublinearity of  $\psi_E^{\kappa}$ , cf. (2.9), we further deduce almost surely, up to extraction of a subsequence,

$$\varepsilon \psi_E(\frac{\cdot}{\varepsilon}) \to 0, \quad \text{strongly in } \mathbf{L}^{\alpha'}(U), \\ u_{\varepsilon} \to u_0, \quad \text{strongly in } \mathbf{L}^{\alpha'}(U).$$

$$(4.27)$$

If the inclusions  $\{I_n\}_n$  were uniformly separated as assumed in [10], then we could choose  $\alpha = 2$ , cf. (4.22), so that a standard div-curl argument in form of e.g. [22, Lemma 12.12] would allow to use (4.26) and pass to the limit in both sides of identity (4.25) (along the subsequence), to the effect of

$$\bar{\boldsymbol{B}}E: \mathcal{D}(u_0) = E: \tilde{p}_0, \quad \text{in } U.$$
(4.28)

In the present situation, with  $\alpha < 2$ , we need to repeat the proof of the div-curl lemma and show that this identity (4.28) still holds. Once this is proven, the conclusion (4.23) easily follows: passing to the weak limit in (4.12) (along the subsequence) yields

$$-\operatorname{div}(2\tilde{p}_0 - \tilde{S}_0 \operatorname{Id}) = (1 - \lambda)f, \quad \text{in } U,$$

and thus, inserting (4.28) in form of  $\tilde{p}_0 = \bar{B} D(u_0)$ , we deduce that  $(u_0, S_0 - f_U S_0)$  coincides with the unique solution  $(\bar{u}, \bar{S})$  of the homogenized equation (2.14). With this characterization of the limit, the conclusion (4.23) now follows from (4.26).

It remains to prove (4.28), and we split the proof in two further substeps. We start with the case  $\frac{2d}{d+2} < \alpha < 2$ , and next we discuss the critical case  $\alpha = \frac{2d}{d+2}$ .

Substep 1.1. Proof of (4.28) in case  $\frac{2d}{d+2} < \alpha < 2$ .

We shall pass to the limit in both sides of (4.25) and we start with the analysis of the left-hand side. Given a test function  $h \in C_c^1(U)$  supported in  $U^{\kappa}$  for some fixed  $\kappa > 2\varepsilon$ , integrating by parts, using the property (4.11) of the extension  $(\tilde{q}_E, \tilde{\Sigma}_E)$ , and using the constraint div $(u_{\varepsilon}) = 0$ , we find

$$\int_{U} h \, \tilde{q}_{E}(\frac{\cdot}{\varepsilon}) : p_{\varepsilon} = \int_{U} h \, \tilde{q}_{E}(\frac{\cdot}{\varepsilon}) : D(u_{\varepsilon})$$

$$= \int_{U} D(hu_{\varepsilon}) : \tilde{q}_{E}(\frac{\cdot}{\varepsilon}) - \int_{U} (\nabla h \otimes u_{\varepsilon}) : \tilde{q}_{E}(\frac{\cdot}{\varepsilon})$$

$$= \frac{1}{2} \int_{U} \tilde{\Sigma}_{E}(\frac{\cdot}{\varepsilon}) \operatorname{div}(hu_{\varepsilon}) - \int_{U} (\nabla h \otimes u_{\varepsilon}) : \tilde{q}_{E}(\frac{\cdot}{\varepsilon})$$

$$= -\frac{1}{2} \int_{U} (\nabla h \otimes u_{\varepsilon}) : (2\tilde{q}_{E} - \tilde{\Sigma}_{E} \operatorname{Id})(\frac{\cdot}{\varepsilon}).$$
(4.29)

Note that the relation  $\operatorname{div}(u_{\varepsilon}) = 0$  entails  $\int_{U} \nabla h \cdot u_{\varepsilon} = 0$ , which allows to add any constant to the pressure  $\tilde{\Sigma}_{E}$ , for instance replacing it by  $\tilde{\Sigma}_{E} - \mathbb{E}[\tilde{\Sigma}_{E}]$ . In view of (4.26) and (4.27), we may now pass to the limit in the above, to the effect of

$$\lim_{\varepsilon \downarrow 0} \int_{U} h \, \tilde{q}_{E}(\frac{\cdot}{\varepsilon}) : p_{\varepsilon} = -\int_{U} (\nabla h \otimes u_{0}) : \bar{\boldsymbol{B}}E = \int_{U} h \, \bar{\boldsymbol{B}}E : D(u_{0}).$$
(4.30)

We turn to the analysis of the right-hand side of (4.25). Integrating by parts, using the property (4.12) of the extension  $(\tilde{p}_{\varepsilon}, \tilde{S}_{\varepsilon})$ , and using the constraint  $\operatorname{div}(\psi_E) = 0$ , we find

$$\int_{U} h q_{E}(\frac{\cdot}{\varepsilon}) : \tilde{p}_{\varepsilon} = E : \int_{U} h \tilde{p}_{\varepsilon} + \int_{U} h \operatorname{D}(\psi_{E})(\frac{\cdot}{\varepsilon}) : \tilde{p}_{\varepsilon}$$

$$= E : \int_{U} h \tilde{p}_{\varepsilon} + \int_{U} \operatorname{D}\left(h \varepsilon \psi_{E}(\frac{\cdot}{\varepsilon})\right) : \tilde{p}_{\varepsilon} - \int_{U} \left(\nabla h \otimes \varepsilon \psi_{E}(\frac{\cdot}{\varepsilon})\right) : \tilde{p}_{\varepsilon}$$

$$= E : \int_{U} h \tilde{p}_{\varepsilon} + \frac{1}{2} \int_{U \setminus \mathcal{I}_{\varepsilon}(U)} h \varepsilon \psi_{E}(\frac{\cdot}{\varepsilon}) \cdot f$$

$$- \frac{1}{2} \int_{U} \left(\nabla h \otimes \varepsilon \psi_{E}(\frac{\cdot}{\varepsilon})\right) : \left(2\tilde{p}_{\varepsilon} - \tilde{S}_{\varepsilon} \operatorname{Id}\right).$$
(4.31)

In view of (4.26) and (4.27), we may now pass to the limit in the above, to the effect of

$$\lim_{\varepsilon \downarrow 0} \int_{U} h \, q_E(\frac{\cdot}{\varepsilon}) : \tilde{p}_{\varepsilon} = E : \int_{U} h \, \tilde{p}_0.$$
(4.32)

Combining this with (4.25) and (4.30), and choosing an arbitrary test function  $h \in C_c^{\infty}(U)$ , this proves the claim (4.28).

Substep 1.2. Proof of (4.28) in the critical case  $\alpha = \frac{2d}{d+2}$ . It suffices to prove that (4.30) and (4.32) still hold in this case. Due to the failure of the compact Rellich embedding (4.27), we can no longer pass to the limit directly in (4.29) and (4.31), so a finer analysis is needed. We appeal again to a two-scale argument as inspired by [23, Lemma 1.15].

We start with the proof of (4.30). Given  $\eta > 0$ , we choose a partition  $\{Q_i\}_i$  of U into measurable subsets with  $|Q_i| \simeq \eta^d$ . In these terms, we can decompose (4.29) as

$$\int_{U} h \, \tilde{q}_{E}(\frac{\cdot}{\varepsilon}) : p_{\varepsilon} = -\frac{1}{2} \sum_{i} \left( \int_{Q_{i}} u_{\varepsilon} \right) \cdot \int_{Q_{i}} \left( 2\tilde{q}_{E} - \tilde{\Sigma}_{E} \operatorname{Id} \right)(\frac{\cdot}{\varepsilon}) \, \nabla h \\ - \frac{1}{2} \sum_{i} \int_{Q_{i}} \nabla h \otimes \left( u_{\varepsilon} - \int_{Q_{i}} u_{\varepsilon} \right) : \left( 2\tilde{q}_{E} - \tilde{\Sigma}_{E} \operatorname{Id} \right)(\frac{\cdot}{\varepsilon}). \quad (4.33)$$

On the one hand, using the compact Rellich embedding in form of the almost sure strong convergence  $u_{\varepsilon} \to u_0$  in  $L^1(U)$ , and using Lemma 4.3, we find

$$\begin{split} \lim_{\varepsilon \downarrow 0} \frac{1}{2} \sum_{i} \left( \int_{Q_{i}} u_{\varepsilon} \right) \cdot \int_{Q_{i}} \nabla h \cdot \left( 2\tilde{q}_{E} - \tilde{\Sigma}_{E} \operatorname{Id} \right) (\frac{\cdot}{\varepsilon}) \\ &= \frac{1}{2} \sum_{i} \left( \int_{Q_{i}} \nabla h \right) \otimes \left( \int_{Q_{i}} u_{0} \right) : \left( 2\bar{B}E + (\bar{b}:E) \operatorname{Id} \right), \end{split}$$

hence, letting the mesh  $\eta$  of the partition  $\{Q_i\}_i$  tend to 0, using that the constraint  $\operatorname{div}(u_{\varepsilon}) = 0$  entails  $\int_U \nabla h \cdot u_0 = 0$ , and integrating by parts,

$$\lim_{\eta \downarrow 0} \lim_{\varepsilon \downarrow 0} \frac{1}{2} \sum_{i} \left( \int_{Q_{i}} u_{\varepsilon} \right) \cdot \int_{Q_{i}} \nabla h \cdot \left( 2\tilde{q}_{E} - \tilde{\Sigma}_{E} \operatorname{Id} \right) \left( \frac{\cdot}{\varepsilon} \right) \\
= \frac{1}{2} \left( \int_{U} \nabla h \otimes u_{0} \right) : \left( 2\bar{B}E + (\bar{b}:E) \operatorname{Id} \right) = - \int_{U} h \,\bar{B}E : D(u_{0}). \quad (4.34)$$

On the other hand, using Hölder's inequality and the Poincaré–Sobolev embedding, the second right-hand side term in (4.33) can be estimated as

$$\begin{split} \left| \sum_{i} \int_{Q_{i}} \nabla h \otimes \left( u_{\varepsilon} - \int_{Q_{i}} u_{\varepsilon} \right) : \left( 2\tilde{q}_{E} - \tilde{\Sigma}_{E} \operatorname{Id} \right) \left( \frac{\cdot}{\varepsilon} \right) \right| \\ &\leq \| \nabla h \|_{\mathrm{L}^{\infty}(U)} \sum_{i} \left\| u_{\varepsilon} - \int_{Q_{i}} u_{\varepsilon} \right\|_{\mathrm{L}^{\frac{2d}{d-2}}(Q_{i})} \| \left( \tilde{q}_{E}, \tilde{\Sigma}_{E} \right) \left( \frac{\cdot}{\varepsilon} \right) \|_{\mathrm{L}^{\frac{2d}{d+2}}(Q_{i})} \\ &\lesssim \| \nabla h \|_{\mathrm{L}^{\infty}(U)} \sum_{i} \| \nabla u_{\varepsilon} \|_{\mathrm{L}^{2}(Q_{i})} \| \left( \tilde{q}_{E}, \tilde{\Sigma}_{E} \right) \left( \frac{\cdot}{\varepsilon} \right) \|_{\mathrm{L}^{\frac{2d}{d+2}}(Q_{i})} \\ &\leq \| \nabla h \|_{\mathrm{L}^{\infty}(U)} \| \nabla u_{\varepsilon} \|_{\mathrm{L}^{2}(U)} \left( \sum_{i} \| \left( \tilde{q}_{E}, \tilde{\Sigma}_{E} \right) \left( \frac{\cdot}{\varepsilon} \right) \|_{\mathrm{L}^{\frac{2d}{d+2}}(Q_{i})} \right)^{\frac{1}{2}}, \end{split}$$

hence, passing to the limit  $\varepsilon \downarrow 0$ , using the boundedness of  $\nabla u_{\varepsilon}$  in  $L^2(U)$ , and using the stationarity and the boundedness of  $(\tilde{q}_E, \tilde{\Sigma}_E)$  in  $L^{\frac{2d}{d+2}}(\Omega)$ , cf. Corollary 4.1(i),

$$\begin{split} \limsup_{\varepsilon \downarrow 0} \Big| \sum_{i} \int_{Q_{i}} \nabla h \otimes \Big( u_{\varepsilon} - \oint_{Q_{i}} u_{\varepsilon} \Big) : \Big( 2\tilde{q}_{E} - \tilde{\Sigma}_{E} \operatorname{Id} \Big) \big( \frac{\cdot}{\varepsilon} \big) \Big| \\ \lesssim_{f} \| \nabla h \|_{\operatorname{L}^{\infty}(U)} \Big( \sum_{i} |Q_{i}|^{\frac{d+2}{d}} \Big)^{\frac{1}{2}} \lesssim \eta \| \nabla h \|_{\operatorname{L}^{\infty}(U)}. \end{split}$$

Now letting the mesh  $\eta$  of the partition  $\{Q_i\}_i$  tend to 0, and combining this with (4.33) and (4.34), we deduce (4.30).

We turn to the proof of (4.32). Given  $\eta > 0$ , we consider as above a partition  $\{Q_i\}_i$  of U into measurable subsets with  $|Q_i| \simeq \eta^d$ . Starting point is the Poincaré–Sobolev embedding in the form

$$\|\varepsilon\psi_E(\frac{\cdot}{\varepsilon})\|_{\mathrm{L}^{\frac{2d}{d-2}}(Q_i)} \lesssim \|\nabla\psi_E(\frac{\cdot}{\varepsilon})\|_{\mathrm{L}^2(Q_i)} + |Q_i|^{\frac{d-2}{2d}} \oint_{Q_i} |\varepsilon\psi_E(\frac{\cdot}{\varepsilon})|.$$

By the stationarity and the boundedness of  $\nabla \psi_E$  in  $L^2(\Omega)$ , and by the sublinearity of  $\psi_E$  in  $L^1$ , cf. (2.9), we deduce almost surely

$$\limsup_{\varepsilon \downarrow 0} \| \varepsilon \psi_E(\frac{\cdot}{\varepsilon}) \|_{\mathrm{L}^{\frac{2d}{d-2}}(Q_i)} \lesssim \| Q_i \|^{\frac{1}{2}} \| \nabla \psi_E \|_{\mathrm{L}^2(\Omega)} \lesssim \| Q_i \|^{\frac{1}{2}}.$$

Summing over i, this yields

$$\limsup_{\varepsilon \downarrow 0} \left\| \varepsilon \psi_E(\frac{\cdot}{\varepsilon}) \right\|_{\mathrm{L}^{\frac{2d}{d-2}}(U)} \lesssim \left( \sum_i |Q_i|^{\frac{d}{d-2}} \right)^{\frac{d-2}{2d}} \lesssim \eta,$$

and thus, letting the mesh  $\eta$  of the partition  $\{Q_i\}_i$  tend to 0,

$$\lim_{\varepsilon \downarrow 0} \left\| \varepsilon \psi_E(\frac{\cdot}{\varepsilon}) \right\|_{\mathcal{L}^{\frac{2d}{d-2}}(U)} = 0, \qquad (4.35)$$

which proves that  $\psi_E$  is in fact still sublinear in  $L^{\alpha'} = L^{\frac{2d}{d-2}}$ . This allows to pass to the limit in (4.31), and the claim (4.32) follows.

Step 2. Convergence of the pressure.

While it is already shown in Step 1, cf. (4.23), that almost surely  $\tilde{S}_{\varepsilon} - \int_{U} \tilde{S}_{\varepsilon} \rightarrow \bar{S}$ weakly in  $L^{\alpha}(U)$ , we turn to the weak convergence of the restricted pressure  $S_{\varepsilon} \mathbb{1}_{U \setminus \mathcal{I}_{\varepsilon}(U)} = \tilde{S}_{\varepsilon} \mathbb{1}_{U \setminus \mathcal{I}_{\varepsilon}(U)}$ , and we establish at the same time the corrector result for the pressure, cf. (2.15). For that purpose, we start by examining the two-scale expansion errors

$$w_{\varepsilon} := u_{\varepsilon} - \bar{u} - \sum_{E \in \mathcal{E}} \varepsilon \psi_{E}(\frac{\cdot}{\varepsilon}) \nabla_{E} \bar{u},$$
  
$$Q_{\varepsilon} := S_{\varepsilon} \mathbb{1}_{U \setminus \mathcal{I}_{\varepsilon}(U)} - \bar{S} - \bar{b} : D(\bar{u}) - \sum_{E \in \mathcal{E}} (\Sigma_{E} \mathbb{1}_{\mathbb{R}^{d} \setminus \mathcal{I}})(\frac{\cdot}{\varepsilon}) \nabla_{E} \bar{u}.$$

Without loss of generality, we may assume that  $f \in W^{1,\infty}(U)^d$  and  $\bar{u} \in W^{3,\infty}_0(U)^d$ , while the general case easily follows by an approximation argument as in [10, Step 8.4 of the proof of Proposition 2.1].

Consider a test function  $g \in C_c^{\infty}(U)^d$  with  $D(g)|_{\varepsilon \mathcal{I}} = 0$ . Inserting the above definition of  $(w_{\varepsilon}, Q_{\varepsilon})$  and reorganizing the terms, we compute

$$\begin{split} \int_{U} \mathcal{D}(g) &: \left(2 \operatorname{D}(w_{\varepsilon}) - Q_{\varepsilon} \operatorname{Id}\right) = \int_{U} \mathcal{D}(g) : \left(2p_{\varepsilon} - S_{\varepsilon} \operatorname{Id}\right) - \int_{U} \mathcal{D}(g) : \left(2\bar{B} \operatorname{D}(\bar{u}) - \bar{S} \operatorname{Id}\right) \\ &- \sum_{E \in \mathcal{E}} \int_{U} \mathcal{D}(g) : \left(2q_{E} - \Sigma_{E} \mathbb{1}_{\mathbb{R}^{d} \setminus \mathcal{I}} \operatorname{Id}\right) (\frac{\cdot}{\varepsilon}) \nabla_{E} \bar{u} + \sum_{E \in \mathcal{E}} \int_{U} \mathcal{D}(g) : \left(2\bar{B}E + (\bar{b}:E) \operatorname{Id}\right) \nabla_{E} \bar{u} \\ &- 2\sum_{E \in \mathcal{E}} \int_{U} \mathcal{D}(g) : \left(\nabla \nabla_{E} \bar{u} \otimes \varepsilon \psi_{E} (\frac{\cdot}{\varepsilon})\right). \end{split}$$

Since D(g) vanishes in  $\varepsilon \mathcal{I}$ , recalling that  $(q_E, \Sigma_E)(\frac{\cdot}{\varepsilon})$  and  $(p_{\varepsilon}, S_{\varepsilon})$  coincide with  $(\tilde{q}_E, \tilde{\Sigma}_E)(\frac{\cdot}{\varepsilon})$ and  $(\tilde{p}_{\varepsilon}, \tilde{S}_{\varepsilon})$  in  $U \setminus \varepsilon \mathcal{I} \subset U \setminus \mathcal{I}_{\varepsilon}(U)$ , and appealing to (4.11) and (4.12), and to the homogenized equation (2.14), we easily find

$$\int_{U} \mathcal{D}(g) : \left(2 \mathcal{D}(w_{\varepsilon}) - Q_{\varepsilon} \operatorname{Id}\right) = \mathcal{F}_{\varepsilon}(g), \qquad (4.36)$$

in terms of

$$\mathcal{F}_{\varepsilon}(g) := -\int_{U} g \cdot \left(\mathbb{1}_{\mathcal{I}}(\frac{\cdot}{\varepsilon}) - \lambda\right) f - 2 \sum_{E \in \mathcal{E}} \int_{U} \mathcal{D}(g) : \left(\nabla \nabla_{E} \bar{u} \otimes \varepsilon \psi_{E}(\frac{\cdot}{\varepsilon})\right) \\ + \sum_{E \in \mathcal{E}} \int_{U} \left(\nabla \nabla_{E} \bar{u} \otimes g\right) : \left(\left(2\tilde{q}_{E} - \tilde{\Sigma}_{E} \operatorname{Id}\right)(\frac{\cdot}{\varepsilon}) - \left(2\bar{B}E + (\bar{b}:E) \operatorname{Id}\right)\right).$$
(4.37)

We now appeal to Lemma 3.2 in the following form: there exists  $z_{\varepsilon} \in H_0^1(U)^d$  with  $D(z_{\varepsilon})|_{\varepsilon \mathcal{I}} = 0$ , such that

$$\operatorname{div}(z_{\varepsilon}) = \left(T_{\varepsilon}|T_{\varepsilon}|^{\alpha-2} - f_{U\setminus\varepsilon\mathcal{I}}T_{\varepsilon}|^{\alpha-2}\right)\mathbb{1}_{U\setminus\varepsilon\mathcal{I}}, \qquad T_{\varepsilon} := Q_{\varepsilon} - f_{U\setminus\varepsilon\mathcal{I}}Q_{\varepsilon},$$

and

$$\begin{aligned} \|\nabla z_{\varepsilon}\|_{\mathrm{L}^{2}(U)} &\lesssim_{U,\alpha,r} \quad \Lambda_{\varepsilon}(U;r,\frac{2\alpha}{2-\alpha}) \|T_{\varepsilon}|T_{\varepsilon}|^{\alpha-2}\|_{\mathrm{L}^{\alpha'}(U\setminus\varepsilon\mathcal{I})} \\ &\lesssim \quad \Lambda_{\varepsilon}(U;r,\frac{2\alpha}{2-\alpha}) \|Q_{\varepsilon} - f_{U\setminus\varepsilon\mathcal{I}} Q_{\varepsilon}\|_{\mathrm{L}^{\alpha}(U\setminus\varepsilon\mathcal{I})}^{\alpha-1}, \end{aligned}$$
(4.38)

where we have set

$$\Lambda_{\varepsilon}(U;r,p) := \left( |U| + \varepsilon^d \sum_{n:\varepsilon I_n \cap U \neq \varnothing} \mu_r(\rho_{n;U,\varepsilon})^p \right)^{\frac{1}{p}}.$$

Testing (4.36) with  $g = z_{\varepsilon}$ , and using the properties of  $z_{\varepsilon}$ , we find

$$\|Q_{\varepsilon} - f_{U \setminus \varepsilon \mathcal{I}} Q_{\varepsilon}\|_{\mathcal{L}^{\alpha}(U \setminus \varepsilon \mathcal{I})}^{\alpha} = -\mathcal{F}_{\varepsilon}(z_{\varepsilon}) + 2 \int_{U} \mathcal{D}(z_{\varepsilon}) : \mathcal{D}(w_{\varepsilon}).$$
(4.39)

Noting that the definition (4.37) of  $\mathcal{F}_{\varepsilon}$  yields

$$\begin{aligned} |\mathcal{F}_{\varepsilon}(g)| \lesssim \|g\|_{H^{1}(U)} \Big(\|f\|_{W^{1,\infty}(U)} + \|\nabla \bar{u}\|_{W^{2,\infty}(U)}\Big) \\ \times \sup_{E \in \mathcal{E}} \Big(\|\varepsilon \psi_{E}(\frac{\cdot}{\varepsilon})\|_{L^{2}(U)} + \|\mathbb{1}_{\mathcal{I}}(\frac{\cdot}{\varepsilon}) - \lambda\|_{H^{-1}(U)} \\ &+ \|\tilde{q}_{E}(\frac{\cdot}{\varepsilon}) - \bar{B}E\|_{H^{-1}(U)} + \|\tilde{\Sigma}_{E}(\frac{\cdot}{\varepsilon}) + \bar{b}:E\|_{H^{-1}(U)}\Big), \end{aligned}$$

inserting this into (4.39), and using (4.38), we deduce

$$\begin{split} \|Q_{\varepsilon} - \oint_{U \setminus \varepsilon \mathcal{I}} Q_{\varepsilon}\|_{\mathcal{L}^{\alpha}(U \setminus \varepsilon \mathcal{I})} &\lesssim_{U,\alpha,r} \Lambda_{\varepsilon}(U;r, \frac{2\alpha}{2-\alpha}) \|w_{\varepsilon}\|_{H^{1}(U)} \\ &+ \Lambda_{\varepsilon}(U;r, \frac{2\alpha}{2-\alpha}) \left( \|f\|_{W^{1,\infty}(U)} + \|\nabla \bar{u}\|_{W^{2,\infty}(U)} \right) \\ &\times \sup_{E \in \mathcal{E}} \left( \|\varepsilon \psi_{E}(\frac{\cdot}{\varepsilon})\|_{\mathcal{L}^{2}(U)} + \|\mathbb{1}_{\mathcal{I}}(\frac{\cdot}{\varepsilon}) - \lambda\|_{H^{-1}(U)} \\ &+ \|\tilde{q}_{E}(\frac{\cdot}{\varepsilon}) - \bar{B}E\|_{H^{-1}(U)} + \|\tilde{\Sigma}_{E}(\frac{\cdot}{\varepsilon}) + \bar{b}:E\|_{H^{-1}(U)} \right). \end{split}$$

Noting that the moment condition (4.22) entails  $\limsup_{\varepsilon \downarrow 0} \Lambda_{\varepsilon}(U; r, \frac{2\alpha}{2-\alpha}) < \infty$ , and using (2.9), (4.24), and Lemma 4.3, together with the ergodic theorem in form of the almost sure weak convergence  $\mathbb{1}_{\mathcal{I}}(\frac{\cdot}{\varepsilon}) \rightharpoonup \lambda$  in  $L^2_{\text{loc}}(\mathbb{R}^d)$ , the above right-hand side tends to 0 almost surely as  $\varepsilon \downarrow 0$ . This concludes the proof of (2.15).

#### 5. Further technical tools

This last section is devoted to the proof of Corollaries 5 and 6, which are further technical tools for the analysis of particle suspensions without uniform separation.

Proof of Corollary 5. Note that the Stokes equation (2.22) entails  $\operatorname{div}(\sigma(u, S)) = 0$  in  $\mathbb{R}^d \setminus \mathcal{I}$ . For all *n*, in terms of the cut-off function  $w_n \in H^1_0(I_n^+)$  with  $w_n|_{I_n} = 1$  that we have constructed in Lemma 3.3, an integration by parts then yields

$$\int_{\partial I_n} g \cdot \sigma(u, S) \nu = -\int_{I_n^+ \setminus I_n} \operatorname{div}(w_n \sigma(u, S)g) = -\int_{I_n^+ \setminus I_n} \mathcal{D}(w_n g) : \sigma(u, S).$$
(5.1)

In order to reformulate the right-hand side, we appeal to the extension result of Theorem 4. More precisely, given  $\beta \in (1, \infty)$  and  $\alpha, r$  as in (2.17), since the Stokes equation (2.22) ensures that the flux  $p = D(u) \in L^2_{loc}(\mathbb{R}^d)^{d \times d}_{sym}$  satisfies tr(p) = 0 and

$$\int_{\mathbb{R}^d} \mathcal{D}(g) : p = 0, \qquad \forall g \in C_c^1(\mathbb{R}^d)^d : \operatorname{div}(g) = 0, \, \mathcal{D}(g)|_{\mathcal{I}} = 0,$$

Theorem 4 provides an extension  $\tilde{p} \in L^{\alpha}(I_n^+)^{d \times d}_{sym}$  with  $tr(\tilde{p}) = 0$ , and an associated pressure field  $\tilde{S} \in L^{\alpha}_{loc}(\mathbb{R}^d)$ , such that

$$(\tilde{p}, \tilde{S})|_{\mathbb{R}^d \setminus \mathcal{I}} = (p, S)|_{\mathbb{R}^d \setminus \mathcal{I}}, \quad \text{and} \quad \operatorname{div}(2\tilde{p} - \tilde{S}\operatorname{Id}) = 0, \quad \operatorname{in} \mathbb{R}^d,$$

and such that the following estimate holds, for all n,

$$\|(\tilde{p},\tilde{S})\|_{\mathrm{L}^{\alpha}(I_{n}^{+})} \lesssim_{\alpha,\beta,r} \mu_{r}(\rho_{n}) \|\mathrm{D}(u)\|_{\mathrm{L}^{\beta}(I_{n}^{+}\setminus I_{n})}.$$

Writing  $\sigma(u, S) = 2p - S \operatorname{Id}$  in (5.1), and using these extensions, we find

$$\int_{\partial I_n} g \cdot \sigma(u, S) \nu = -\int_{I_n^+ \setminus I_n} \mathcal{D}(w_n g) : (2p - S \operatorname{Id}) = \int_{I_n} \mathcal{D}(w_n g) : (2\tilde{p} - \tilde{S} \operatorname{Id}),$$

and we may then estimate

$$\begin{aligned} \left| \int_{\partial I_n} g \cdot \sigma(u, S) \nu \right| &\lesssim \|w_n\|_{W^{1,\alpha'}(I_n^+)} \|g\|_{W^{1,\infty}(I_n^+)} \|(\tilde{p}, \tilde{S})\|_{\mathcal{L}^{\alpha}(I_n)} \\ &\lesssim_{\alpha,\beta,r} \ \mu_r(\rho_n) \|w_n\|_{W^{1,\alpha'}(I_n^+)} \|g\|_{W^{1,\infty}(I_n^+)} \|\mathcal{D}(u)\|_{\mathcal{L}^{\beta}(I_n^+ \setminus I_n)}. \end{aligned}$$

Combining this with the bound on norms of  $w_n$  in Lemma 3.3, choosing  $\beta = 2$ , and optimizing the choice of  $\alpha, r$ , the conclusion follows.

Proof of Corollary 6. For  $R \geq 5$ , choose  $\zeta_R \in C_c^{\infty}(B_{2R-4}; \mathbb{R}^+)$  with  $\zeta_R|_{B_R} = 1$  and with  $|\nabla \zeta_R| \leq R^{-1}$ . For any  $V \in \mathbb{R}^d$  and  $c \in \mathbb{R}$ , testing the Stokes equation (2.22) with  $\zeta_R(u-V)$ , and replacing the pressure S by S - c, we find

$$\int_{\mathbb{R}^d} \zeta_R |\nabla u|^2 = -\int_{\mathbb{R}^d} \left( (u - V) \otimes \nabla \zeta_R \right) : \left( \nabla u - (S - c) \operatorname{Id} \mathbb{1}_{\mathbb{R}^d \setminus \mathcal{I}} \right) - \sum_{n: I_n^+ \subset B_{2R}} \int_{\partial I_n} \zeta_R \left( u - V \right) \cdot \sigma(u, S - c) \nu.$$

Since D(u) = 0 in  $I_n$ , we may write  $u = V_n + \Theta_n(x - x_n)$  in  $I_n$  for some  $V_n \in \mathbb{R}^d$  and  $\Theta_n \in \mathbb{M}^{skew}$ . The boundary conditions for u then allow to add any constant to the test function  $\zeta_R$  in the last right-hand side term, and we obtain

$$\int_{\mathbb{R}^d} \zeta_R |\nabla u|^2 = -\int_{\mathbb{R}^d} \left( (u - V) \otimes \nabla \zeta_R \right) : \left( \nabla u - (S - c) \operatorname{Id} \mathbb{1}_{\mathbb{R}^d \setminus \mathcal{I}} \right) - \sum_{n: I_n^+ \subset B_{2R}} \int_{\partial I_n} \left( \zeta_R - \oint_{I_n} \zeta_R \right) \left( V_n - V + \Theta_n (x - x_n) \right) \cdot \sigma(u, S - c) \nu.$$

Hence, using the properties of  $\zeta_R$ , Hölder's inequality, and appealing to the trace estimate of Corollary 5 to bound the last right-hand side term, we deduce for all  $s \ge 1$ ,

$$\begin{aligned} \|\nabla u\|_{\mathrm{L}^{2}(B_{R})}^{2} \lesssim R^{-1} \|u - V\|_{\mathrm{L}^{s}(B_{2R})} \Big( \|\nabla u\|_{\mathrm{L}^{s'}(B_{2R})} + \|S - c\|_{\mathrm{L}^{s'}(B_{2R}\setminus\mathcal{I})} \Big) \\ &+ R^{-1} \Big( \sum_{n:I_{n}^{+}\subset B_{2R}} \mu'(\rho_{n})^{2} (|V_{n} - V|^{2} + |\Theta_{n}|^{2}) \Big)^{\frac{1}{2}} \|\nabla u\|_{\mathrm{L}^{2}(B_{2R})}, \end{aligned}$$

where we have set for abbreviation,

$$\mu'(\rho_n) := \begin{cases} \rho_n^{\frac{1}{4d}(d+1)(d+2) - \frac{5}{2}} & : & d \le 6, \\ 1 & : & d > 6. \end{cases}$$

Choosing  $c = \int_{B_{2R} \setminus \mathcal{I}} S$  and appealing to a pressure estimate as in (4.7) (with  $\alpha = s'$ ), this becomes for all  $2 \leq r \neq \frac{2d}{d-2}$  and  $2 \vee \frac{2dr}{d(r-2)+2r} \leq s < \infty$ , with s > d if r = 2,

$$\begin{aligned} \|\nabla u\|_{\mathrm{L}^{2}(B_{R})}^{2} &\lesssim R^{-1} \Big( |B_{R}| + \sum_{n:I_{n}^{+} \subset B_{2R}} \mu_{r}(\rho_{n})^{\frac{2s}{s-2}} \Big)^{\frac{s-2}{2s}} \|u - V\|_{\mathrm{L}^{s}(B_{2R})} \|\nabla u\|_{\mathrm{L}^{2}(B_{2R})} \\ &+ R^{-1} \Big( \sum_{n:I_{n}^{+} \subset B_{2R}} \mu'(\rho_{n})^{2} (|V_{n} - V|^{2} + |\Theta_{n}|^{2}) \Big)^{\frac{1}{2}} \|\nabla u\|_{\mathrm{L}^{2}(B_{2R})}. \end{aligned}$$

Noting that

$$|V_n - V|^2 \lesssim \int_{I_n} |u - V|^2, \qquad |\Theta_n|^2 \lesssim \int_{I_n} |\nabla u|^2$$

Hölder's inequality yields

$$\sum_{n:I_n^+\subset B_{2R}} \mu'(\rho_n)^2 (|V_n-V|^2 + |\Theta_n|^2)$$

$$\lesssim \left(\sum_{n:I_n^+\subset B_{2R}} \mu'(\rho_n)^{\frac{2s}{s-2}}\right)^{\frac{s-2}{s}} ||u-V||^2_{\mathrm{L}^s(B_{2R})} + \left(\sup_{n:I_n^+\subset B_{2R}} \mu'(\rho_n)^2\right) ||\nabla u||^2_{\mathrm{L}^2(B_{2R})}$$

$$\lesssim \left(\sum_{n:I_n^+\subset B_{2R}} \mu'(\rho_n)^{\frac{2s}{s-2}}\right)^{\frac{s-2}{s}} \left(||u-V||^2_{\mathrm{L}^s(B_{2R})} + ||\nabla u||^2_{\mathrm{L}^2(B_{2R})}\right).$$

Inserting this into the above, choosing  $V := \int_{B_{2R}} u$ , and optimizing in r, the conclusion follows.

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